

## Ch6 (Cont.)

2)  $X$  is also ergodic: statistical average is given by the time average  
requires information  
on prob. distribution  
Via the density function  
Simple integral

$$R_X(\tau) = E[X(t_1)X(t_2)] = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T dt x(t)x(t+\tau)$$

(statistical or ensemble average)

↴ "straight  $R$ " to go with ensemble average  
 $\equiv \langle x(t)x(t+\tau) \rangle$  (time average)

$\equiv R_{\bar{x}}(\tau)$   
 ↴ "curly  $R$ " to go with time average

Properties of the Auto-correlation function:

$$1) R_X(0) = R_{\bar{x}}(t_1, t_1) = E[X_1 X_1] = \overline{X^2}$$

Auto correlation function at  $\tau=0$  is the moment of second order

$$2) \underbrace{R_X(\tau)}_{t_2-t_1=\tau} = R_{\bar{x}}(t_1, t_2) = R_{\bar{x}}(t_1+T, t_2+T)$$

↳ stationary

$$\boxed{T = -t_2} \quad \boxed{R_X(t_2-t_1, 0) = R_{\bar{x}}(-\tau)}$$

Auto correlation function is symmetric or even in  $\tau$

$$3) |R_X(\tau)| \leq R_{\bar{x}}(0)$$

↑  
max

Proof:  $E[\underbrace{(X(t_1)+X(t_2))^2}_{\text{non-negative}}] \geq 0$  (ensemble average of a non-negative variable is non-negative)

$$\underbrace{E[X^2(t_1)]}_{\bar{X}^2} + \underbrace{E[X^2(t_2)]}_{\bar{X}^2} + \underbrace{2E[X(t_1)X(t_2)]}_{2R_X(\tau)} \geq 0$$

$$\bar{X}^2 + \bar{X}^2 + 2R_X(\tau) \geq 0$$

↳ Prop #1

$$R_X(0)$$

$$\hookrightarrow 2R_X(0) + 2R_X(\tau) \geq 0 \rightarrow R_X(\tau) \geq -R_X(0)$$

$$\text{Sim. similarly: } E[\underbrace{(X(t_1) - X(t_2))^2}_{\text{non-negative}}] \geq 0$$

$$\hookrightarrow 2R_X(0) - 2R_X(\tau) \geq 0 \rightarrow R_X(\tau) \leq R_X(0)$$

$$\rightarrow -R_X(0) \leq R_X(\tau) \leq R_X(0) \rightarrow |R_X(\tau)| \leq R_X(0) \quad \checkmark$$

$$4) \quad \text{If } X(t) = \bar{X} + N(t) \rightarrow R_X(\tau) = \bar{X}^2 + R_N(\tau)$$

$\downarrow$  Noise  $\left\{ \bar{N}=0 \text{ and } E[N(t)]=0 \right.$

Proof:  $R_X(\tau) = E[(\bar{X} + N(t_1))(\bar{X} + N(t_2))]$

$$= E[\bar{X}^2 + \bar{X}N(t_1) + \bar{X}N(t_2) + N(t_1)N(t_2)]$$

$$= E[\bar{X}^2] + \underbrace{\bar{X}E[N(t_1)]}_{\text{number 0}} + \underbrace{\bar{X}E[N(t_2)]}_{0} + \underbrace{E[N(t_1)N(t_2)]}_{R_N(\tau)}$$

$$= \bar{X}^2 + R_N(\tau) \quad \checkmark$$

Consequence:  $\left\{ R_X(\tau \rightarrow \infty) = \bar{X}^2 + \underbrace{R_N(\tau \rightarrow \infty)}_0 = \bar{X}^2 \right.$

$\text{also } \rightarrow R_X(\tau=0) \stackrel{!}{=} \bar{X}^2$

Summary:  $X(t) = \bar{X} + N(t) \rightarrow \left\{ \begin{array}{|c|c|} \hline \text{Statistical} & \text{Auto-correlation} \\ \hline \bar{X}^2 & R_X(0) \\ \bar{X}^2 & R_X(\infty) \\ \hline \end{array} \right.$

There is the importance or usefulness of the auto-correlation functions

We can obtain statistical information such as : moment of 2nd order and the mean (ensemble average) w/o knowing the probability distribution (or density function) if we know auto-correlation function at  $\tau=0$  &  $\tau=\infty$ . Furthermore, for ergodic & stationary processes these auto-correlations are equal to time auto-correlations (using time average)

### Cross-correlation functions:

$$X_1 = X(t_1); \quad Y_2 = Y(t_2); \quad t_2 = t_1 + \tau$$

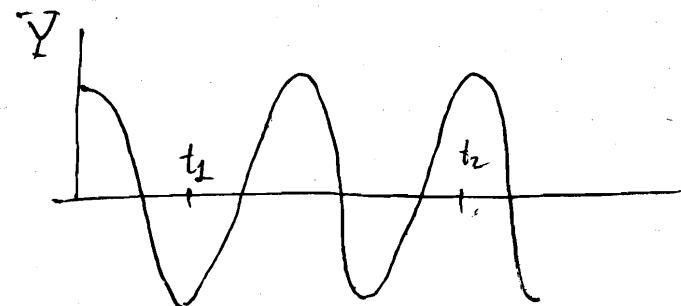
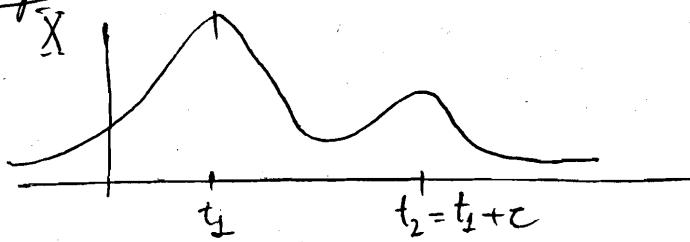
$X_1, Y_2$  are stationary & ergodic random variables

$$R_{XY}(\tau) = E[X_1 Y_2] = \int_{-\infty}^{\infty} dx_1 \int_{-\infty}^{\infty} dy_2 \ x_1 y_2 f(x_1) f(y_2)$$

$$R_{YX}(\tau) = E[Y_2 X_1] = \int_{-\infty}^{\infty} dy_1 \int_{-\infty}^{\infty} dx_2 \ x_2 y_1 f(x_2) f(y_1)$$

$$Y_1 = Y(t_1); \quad X_2 = X(t_2)$$

Example:



$\hookrightarrow R_{XY}(\tau) \neq R_{YX}(\tau)$

Cross correlation functions using time average:

$$R_{XY}(\tau) = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T dt \ x(t) y(t+\tau)$$

$$R_{YX}(\tau) = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T dt \ y(t) x(t+\tau)$$

Properties of Cross-correlation Functions:

$$\left. \begin{array}{l} 1) R_{XY}(0) \\ E[X(t_1) Y(t_2)] \end{array} \right\} R_{YX}(0) \quad \left. \begin{array}{l} R_{YX}(0) \\ E[Y(t_1) X(t_2)] \end{array} \right\} R_{XY}(0) = R_{YX}(0)$$

Cross-correlations b/w  $X \& Y$  and b/w  $Y \& X$  are the same only at  $\tau = 0$

2) No even symmetry as with autocorrelation function:

$$R_{XY}(-\tau) \neq R_{XY}(\tau)$$

However:  $\underbrace{R_{XY}(-\tau)}_{\sim} = \underbrace{R_{YX}(\tau)}_{\sim}$

3)  $|R_{XY}(\tau)| \leq R_{XY}(0)$

However:  $|R_{XY}(\tau)| \leq \sqrt{R_X(0) R_Y(0)}$

4) If  $X \& Y$  are stat. independent:

$$R_{XY}(\tau) = E[X_1 Y_2] = \underset{X \& Y \text{ are stat. independent}}{\overset{\uparrow}{E[X_1] E[Y_2]}} = \bar{X} \bar{Y} \quad \left. \begin{array}{l} R_{XY}(\tau) \\ = \end{array} \right\}$$

$$R_{YX}(\tau) = E[Y_1 X_2] = \underset{\uparrow}{E[Y_1] E[X_2]} = \bar{Y} \bar{X} = \bar{X} \bar{Y} \quad \left. \begin{array}{l} R_{YX}(\tau) \\ = \end{array} \right\}$$

$$5) R_{XX'}(\tau) = E[X(t) \dot{X}(t+\tau)] = \lim_{\epsilon \rightarrow 0} E[X(t)(X(t+\tau+\epsilon) - X(t+\tau))]$$

$$\dot{X} \equiv \frac{dX}{dt} = \lim_{\epsilon \rightarrow 0} \frac{X(t+\tau+\epsilon) - X(t+\tau)}{\epsilon}$$

$$= \lim_{\epsilon \rightarrow 0} \frac{1}{\epsilon} \left\{ \underbrace{E[X(t)X(t+\tau+\epsilon)]}_{R_X(\tau+\epsilon)} - \underbrace{E[X(t)X(t+\tau)]}_{R_X(\tau)} \right\}$$

$$= \frac{dR_X}{d\tau} \Rightarrow R_{XX'}(\tau) = \frac{dR_X}{d\tau}$$

Similarly:

$$R_{X'X'}(\tau) = R_{\dot{X}}(\tau) = -\frac{d^2R_X}{d\tau^2}$$

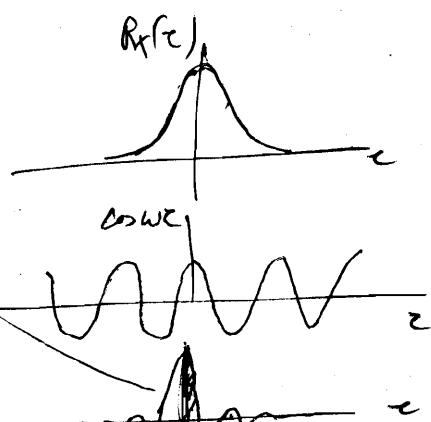
One more property for the Auto-correlation Function:

Fourier transform of an auto-correlation function:

$$F[R_X(\tau)] = \int_{-\infty}^{\infty} d\tau R_X(\tau) e^{-j\omega\tau}$$

$$= \int_{-\infty}^{\infty} d\tau \underbrace{R_X(\tau)}_{\substack{\text{even} \\ \text{in } \tau}} \underbrace{\cos \omega\tau}_{\substack{\text{even} \\ \text{in } \tau}} - j \int_{-\infty}^{\infty} d\tau \underbrace{\frac{R_X(\tau)}{\tau}}_{\substack{\text{even} \\ \text{in } \tau}} \underbrace{\sin \omega\tau}_{\substack{\text{odd} \\ \text{in } \tau}} \quad \underbrace{\text{odd in } \tau}_0$$

$$F[R_X(\tau)] = 2 \int_0^{\infty} d\tau R_X(\tau) \cos \omega\tau$$



$\boxed{F[R_X(\tau)] \geq 0}$  if  $\underline{\text{main peak}}$   
or  $R_X(\tau)$  not too wide  $\rightarrow$  no flat tops  
and sharp vertical sides or discontinuities.

$$\left\{ \begin{array}{l} \text{HW7 (Ch6): } (3.2; 5.3; 5.4) \text{ due 5/6} \\ \text{HW8 (Ch6): } 7.1; \underline{8.2} \text{ due 5/6} \end{array} \right.$$

$$\rightarrow \text{HW9 (Ch7): } 2.2; 3.1; 4.1; 5.4; 6.2; 7.1 \text{ due 5/13}$$

$$\rightarrow \text{HW10 (Ch8): } 3.3; 4.1; 4.4; 7.1 \text{ due 5/13}$$

**HW7: 5.3**

Find mean & variance for random process with given autocorrelation functions:

$$a) R_x(\tau) = 10 e^{-\tau^2} \quad \left\{ \begin{array}{l} \bar{X^2} = R_x(0) = 10 \\ \bar{X} = \sqrt{R_x(\infty)} = 0 \end{array} \right\} \rightarrow \sigma_x^2 = \bar{X^2} - \bar{X}^2 = 10$$

$$b) R_x(\tau) = 10 e^{-\tau^2} \cos(2\pi\tau^2) \quad \left\{ \begin{array}{l} \bar{X^2} = R_x(0) = 10 \\ \bar{X} = \sqrt{R_x(\infty)} = 0 \end{array} \right\} \sigma_x^2 = 10$$

$$c) R_x(\tau) = 10 \frac{\tau^2 + 8}{\tau^2 + 4} \quad \left\{ \begin{array}{l} \bar{X^2} = R_x(0) = 20 \\ \bar{X} = \sqrt{R_x(\infty)} = \sqrt{10} \end{array} \right\} \sigma_x^2 = \bar{X^2} - \bar{X}^2 = 20 - 10 = 10$$

**HW7: 5.4**

$$R_x(\tau) = 10 e^{-2|\tau|} - 5 e^{-4|\tau|}$$

a) Mean & variance of  $X$ :

$$\bar{X} = \sqrt{R_x(\infty)} = 0 \quad \left\{ \begin{array}{l} \bar{X^2} = R_x(0) = 5 \\ \sigma_x^2 = \bar{X^2} - \bar{X}^2 = 5 \end{array} \right.$$

b) Is this process differentiable? Why?

Property:  $R_{XX}(\tau) = \frac{dR_X}{d\tau} \rightarrow$  if we can find  $R_{XX}$   
 $\rightarrow X$  does exist  $\rightarrow$  process described by  $X$  is differentiable:

$$\frac{dR_X}{dz} = \begin{cases} z \geq 0 \rightarrow |z| = z \rightarrow \frac{d(10e^{-2z} - 5e^{-4z})}{dz} = -20e^{-2z} + 20e^{-4z} \\ z < 0 \rightarrow |z| = -z \rightarrow \frac{d(10e^{2z} - 5e^{4z})}{dz} = 20e^{2z} - 20e^{4z} \end{cases}$$

$\rightarrow R_X(z)$  is differentiable for  $z \geq 0$  &  $z < 0 \rightarrow \frac{dR_X}{dz}$  exist if it is continuous at  $z=0$ :

$$\frac{dR_X}{dz}(z=0) \left\{ \begin{array}{l} z \geq 0 : -20 + 20 = 0 \\ z < 0 : 20 - 20 = 0 \end{array} \right\} \checkmark$$

$\Rightarrow R_{Xx}(z)$  does exist  $\Rightarrow X$  or  $\frac{dx}{dt}$  exist  $\rightarrow X$  is differentiable (also the process it describes)

HW8: 7.1 Two independent stationary random processes  $X(t)$  &  $Y(t)$

with  $\begin{cases} R_X(z) = 25e^{-10|z|} \cos(100\pi z) \\ R_Y(z) = 16 \frac{\sin(50\pi z)}{50\pi z} \end{cases}$

a) Find autocorrelation function of  $X(t) + Y(t)$ :

$$\begin{aligned} R_{X+Y}(z) &= E[(X_1 + Y_1)(X_2 + Y_2)] = E[X_1 X_2] + E[Y_1 Y_2] \\ &\quad + E[X_1 Y_2] + E[X_2 Y_1] \\ &= R_X(z) + R_Y(z) + \underbrace{E[X_1]}_{\bar{X}} \underbrace{E[Y_2]}_{\bar{Y}} + \underbrace{E[X_2]}_{\bar{X}} \underbrace{E[Y_1]}_{\bar{Y}} \\ &= R_X(z) + R_Y(z) + 2\bar{X}\bar{Y} = R_X(z) + R_Y(z) + 2\sqrt{R_X(0)}\sqrt{R_Y(0)} \\ &= 25e^{-10|z|} \cos(100\pi z) + 16 \frac{\sin(50\pi z)}{50\pi z} \end{aligned}$$

b) Find autocorrelation function of  $X(t) - Y(t)$

$$R_{X-Y}(\tau) = R_X(\tau) + R_Y(\tau) - \underbrace{2\bar{X}\bar{Y}}_0 = R_X(\tau) + R_Y(\tau)$$

$$= 25e^{-10|\tau|} \cos 100\pi\tau + 16 \frac{\sin 50\pi\tau}{50\pi\tau}$$

d) Find  $R_{XY}(\tau)$  &  $R_{YX}(\tau)$  (Autocorrelation functions of  $XY$  &  $YX$ , not the cross correlation functions of  $X$  &  $Y$ )

$$R_{XY}(\tau) = E[X_1 Y_1 X_2 Y_2]$$

$$= \underbrace{E[X_1 X_2]}_{X \& Y \text{ stat. indep.}} E[Y_1 Y_2]$$

$$= R_X(\tau) \cdot R_Y(\tau)$$

$$R_{YX}(\tau) = E[Y_1 X_1 Y_2 X_2] = \underbrace{E[Y_1 Y_2]}_{\text{stat indep.}} E[X_1 X_2]$$

$$= R_Y(\tau) \cdot R_X(\tau)$$

$$= R_{XY}(\tau)$$

c) Find cross correlation function defined by a) & b):

b/w  $X+Y$  &  $X-Y$

$$R_{(X+Y)(X-Y)} = E[(X_1 + Y_1)(X_2 - Y_2)] = E[X_1 X_2] - E[X_1 Y_2]$$

$$+ E[Y_1 X_2] - E[X_1 Y_2]$$

$$= R_X(\tau) - R_Y(\tau) + \underbrace{\bar{Y} \cdot \bar{X}}_0 - \bar{X} \cdot \bar{Y}$$

$$= 25e^{-10|\tau|} \cos 100\pi\tau - 16 \frac{\sin 50\pi\tau}{50\pi\tau}$$

## Ch 7: Spectral Density

Fourier transform of a random signal  $X$ : issues:

$$F_X(\omega) = \int_{-\infty}^{\infty} dt \ x(t) e^{-j\omega t}$$

- Two problems
- 1) integral does not exist for a random signal since it may not go to 0 at  $\infty$
  - 2) as it is  $F_X(\omega)$  is another random variable  $\rightarrow$  not useful for signal processing applications: noise filtering etc.

To address these 2 problems: modify the def. of a Fourier transform for a random variable:

- 1) Limit the integral to a window (of size  $T$ ) of  $x(t)$  then will take the limit  $T \rightarrow \infty$

This can be achieved if we replace  $x(t)$  by a

$$x_T(t) = \begin{cases} x(t) & |t| \leq T \\ 0 & |t| > T \end{cases}$$

$$\rightarrow \hat{F}_X(\omega) = \int_{-\infty}^{\infty} dt \ x_T(t) e^{-j\omega t}$$

This integral always exists b/c of the finite size of the imposed window of size  $T$

- 2) To eliminate the randomness, take the ensemble average:

$\rightarrow$  new quantity: Spectral density:  $S_{\hat{X}}(\omega)$

$$S_X(\omega) = \lim_{T \rightarrow \infty} \frac{E\{|F_X(\omega)|^2\}}{2T}$$

This will replace a Fourier transform for a random signal.

## Properties of the Spectral density:

$$\boxed{\overline{x^2} = \frac{1}{2\pi} \int_{-\infty}^{\infty} d\omega S_x(\omega)}$$

We can obtain a statistical information such as the moment of second order by integrating the spectral density  $S_x(\omega)$  and divide by  $2\pi$ .

Proof:- using Parseval theorem:  $\int_{-T}^T dt x_T^2(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} d\omega |\hat{F}_x(\omega)|^2$

$\left\{ \begin{array}{l} x_T(t) : \text{signal} \\ \hat{F}_x(\omega) : \text{its Fourier transform.} \end{array} \right.$

Let's apply  $\lim_{T \rightarrow \infty} E \left\{ \frac{1}{2T} \times \text{Parseval Theorem} \right\}$ :

$$\begin{aligned}
 E \left\{ \underbrace{\lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T dt x_T^2(t)}_{\langle x_T^2 \rangle} \right\} &= \frac{1}{2\pi} \int_{-\infty}^{\infty} d\omega \underbrace{\lim_{T \rightarrow \infty} E \left\{ \frac{|\hat{F}_x(\omega)|^2}{2T} \right\}}_{S_x(\omega)} \\
 \underbrace{\langle x^2 \rangle}_{\overline{x^2}} &= \frac{1}{2\pi} \int_{-\infty}^{\infty} d\omega S_x(\omega) \quad \checkmark
 \end{aligned}$$