

$$a_k = \frac{1}{N} e^{jk \frac{2\pi N}{N}} \frac{e^{-j \frac{k 2\pi}{N} (N_1 + \frac{1}{2})} \left[ e^{j \frac{k 2\pi}{N} (N_1 + \frac{1}{2})} - e^{-j \frac{k 2\pi}{N} (N_1 + \frac{1}{2})} \right]}{e^{-j k \frac{\pi}{N}} \left[ e^{j k \frac{\pi}{N}} - e^{-j k \frac{\pi}{N}} \right]}$$

$$a_k = \frac{1}{N} \sum_j \sin \frac{k 2\pi}{N} (N_1 + \frac{1}{2})$$

(FS coefficients for discrete-time train of rectangular pulses of width  $2N_1$  and period  $N$ )

When  $k=0$  this gives  $\rightarrow$  needs a different equation:

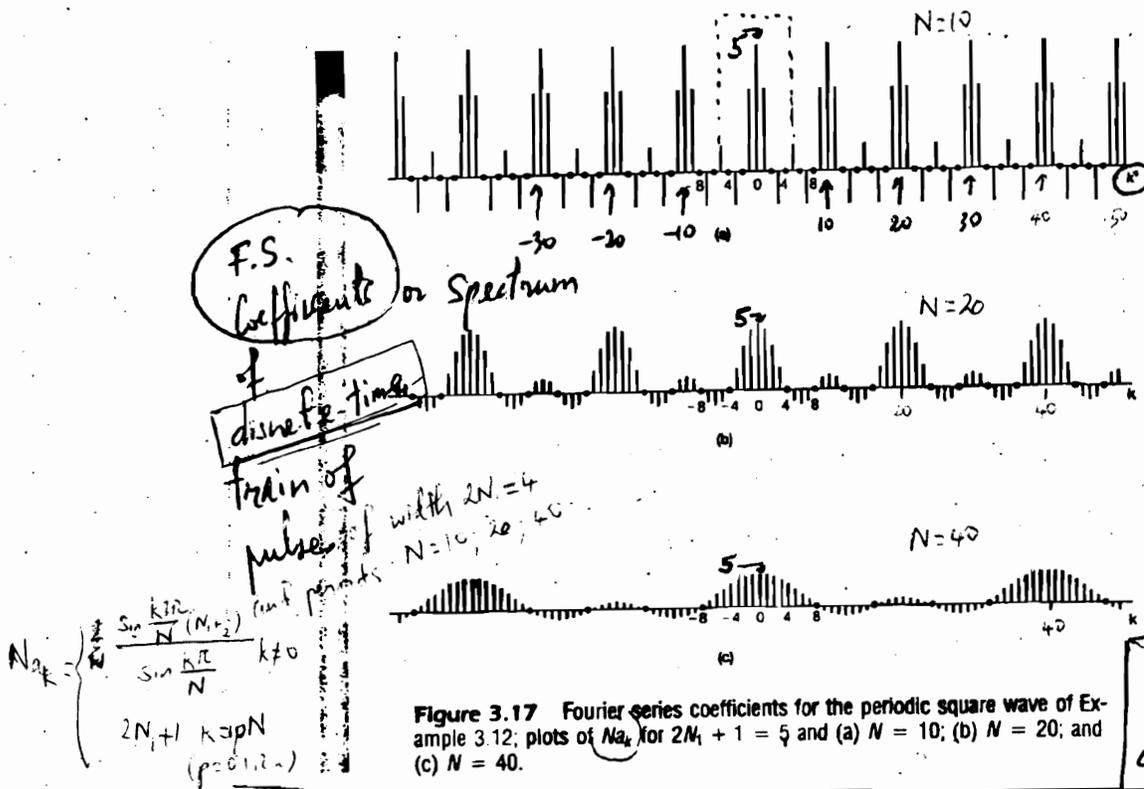
$$a_k = \frac{1}{N} \sum_{n=-N_1}^{N_1} x[n] e^{-j k \frac{2\pi}{N} n}$$

when  $k=0$  or a multiple of  $N$  ( $k=pN; p=0,1,2,\dots$ )  
 $\rightarrow e^{-j p \frac{2\pi}{N} n} = 1$

$$= \frac{1}{N} \sum_{n=-N_1}^{N_1} 1 = \frac{1}{N} (2N_1 + 1)$$

$$\rightarrow a_k = \begin{cases} \frac{1}{N} \frac{\sin \frac{k 2\pi}{N} (N_1 + \frac{1}{2})}{\sin \frac{k \pi}{N}} & k \neq 0 \\ \frac{1}{N} (2N_1 + 1) & k = 0 \text{ or multiple of } N \end{cases}$$

( $k=pN; p=0,1,2,3,\dots$ )



$N_{a_k} = 2N_1+1 = 5$   
when  $k=pN$ ;  $p=0,1,2,\dots$

Figure 3.17 Fourier series coefficients for the periodic square wave of Example 3.12; plots of  $N_{a_k}$  for  $2N_1+1=5$  and (a)  $N=10$ ; (b)  $N=20$ ; and (c)  $N=40$ .

The effect of discretizing a signal is the repetition of the original spectrum in frequency

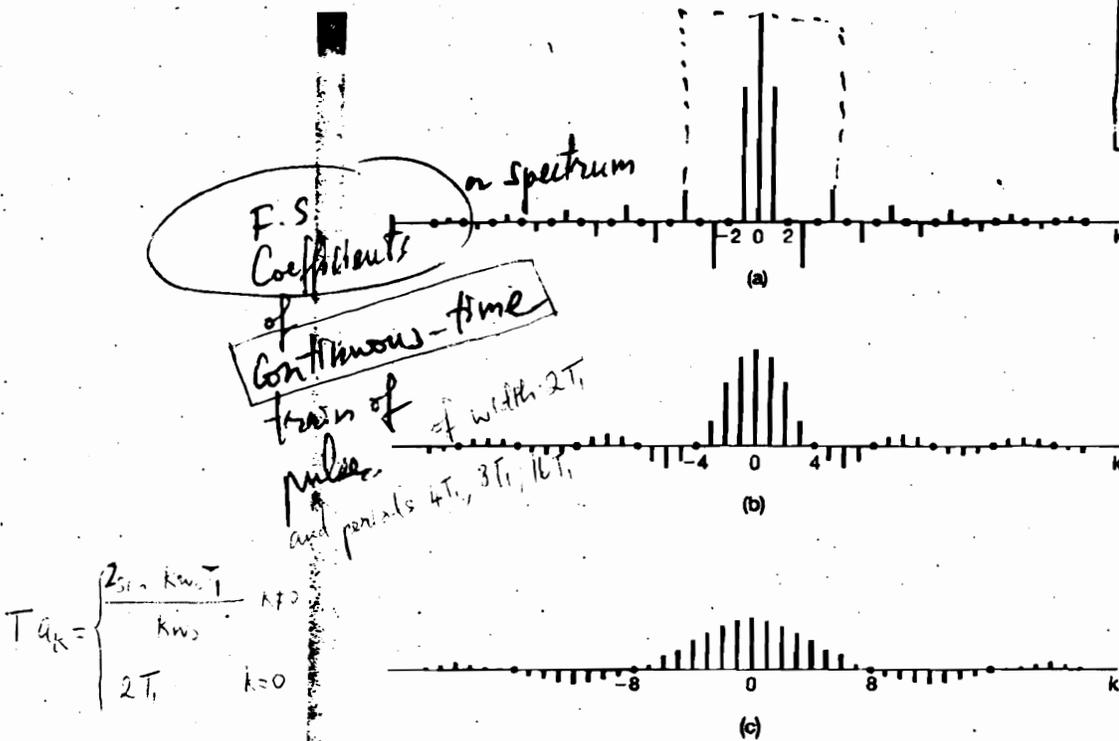


Figure 3.7 Plots of the scaled Fourier series coefficients  $T a_k$  for the periodic square wave with  $T_1$  fixed and for several values of  $T$ : (a)  $T=4T_1$ ; (b)  $T=8T_1$ ; (c)  $T=16T_1$ . The coefficients are regularly spaced samples of the envelope  $(2 \sin \omega T_1)/\omega$ , where the spacing between samples,  $2\pi/T$ , decreases as  $T$  increases.

Reconstruction of a discrete-time signal requires prior application of a low-pass filter

3.12

$$\begin{cases} x_1[n], \text{ period } N=4; \text{ F.S. coefficients } a_k: & a_0 = a_3 = 1 \text{ \& } a_1 = a_2 = 2 \\ x_2[n], \text{ period } N=4; \text{ F.S. coefficients } b_k: & b_0 = b_1 = b_2 = b_3 = 1 \end{cases}$$

Multiplication property in Table 3.1 (continuous-time).

$$x(t)y(t) \rightarrow \text{F.S. coeff. } c_k = \sum_{l=-\infty}^{\infty} a_l b_{k-l} \quad \begin{cases} x(t) \rightarrow \text{F.S. coeff } a_k's \\ y(t) \rightarrow \text{F.S. coeff } b_k's \end{cases}$$

Multiplication property in Table 3.2 (discrete-time)

$$x[n]y[n] \rightarrow \text{F.S. coeff. } c_k = \sum_{l=\langle N \rangle} a_l b_{k-l}$$

in this problem  $N=4 \rightarrow \sum_{l=\langle N \rangle} = \sum_{l=0,1,2,3}$

$$c_k = a_0 b_k + a_1 b_{k-1} + a_2 b_{k-2} + a_3 b_{k-3}$$

F.S. coeff for  $x_1[n]x_2[n]$

$$c_0 = a_0 b_0 + a_1 b_{-1} + a_2 b_{-2} + a_3 b_{-3}$$

$$\begin{cases} b_{-1} = b_{-1+4} = b_3 = 1 \\ b_{-2} = b_{-2+4} = b_2 = 1 \\ b_{-3} = b_{-3+4} = b_1 = 1 \end{cases}$$

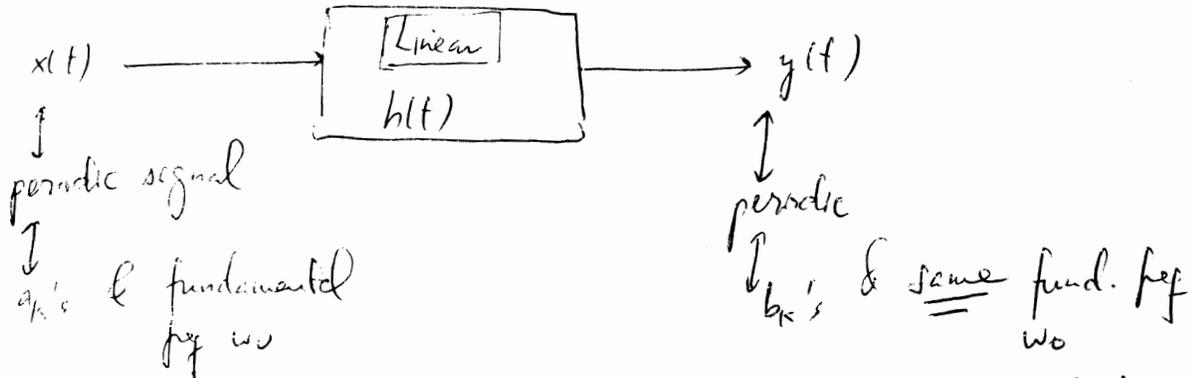
$$= 1 \cdot 1 + 2 \cdot 1 + 2 \cdot 1 + 1 \cdot 1 = 6$$

$$c_1 = a_0 b_1 + a_1 b_0 + a_2 b_{-1} + a_3 b_{-2} = 1 \cdot 1 + 2 \cdot 1 + 2 \cdot 1 + 1 \cdot 1 = 6$$

$$c_2 = a_0 b_2 + a_1 b_1 + a_2 b_0 + a_3 b_{-1} = 1 \cdot 1 + 2 \cdot 1 + 2 \cdot 1 + 1 \cdot 1 = 6$$

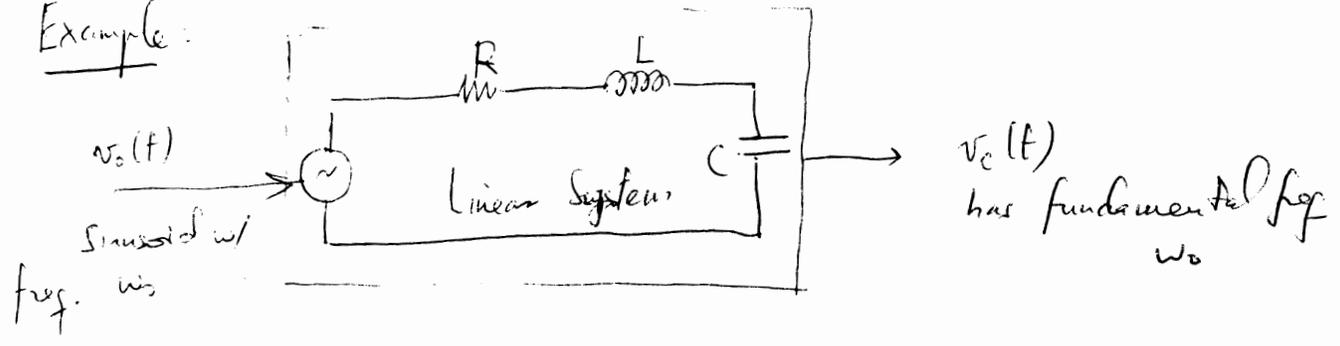
$$\Rightarrow [c_k = 6 \quad \forall k]$$

# Fourier Series & Linear Systems



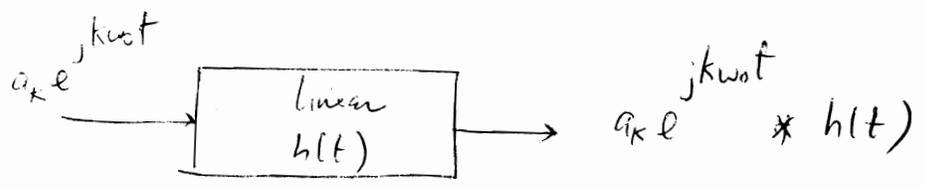
\* Linear systems won't change frequency of input signal!  
 Using the convolution we will see that  $b_k = a_k \hat{H}(jk\omega_0)$  ①

Example:

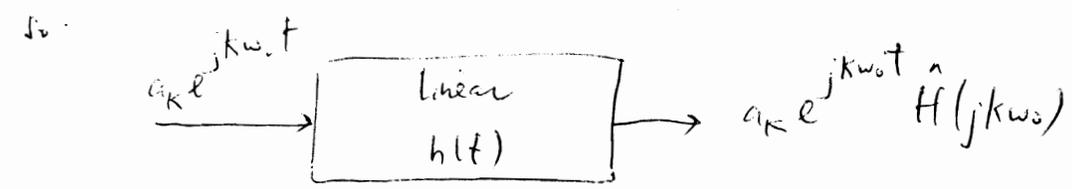


Derive eq ①:

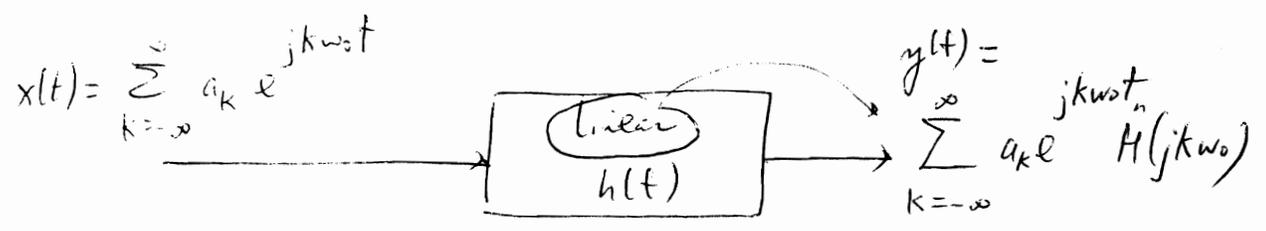
a) instead of  $x(t)$ , we use  $a_k e^{jk\omega_0 t}$



$$\begin{aligned}
 a_k e^{jk\omega_0 t} * h(t) &= a_k \int_{-\infty}^{\infty} d\tau h(\tau) e^{jk\omega_0(t-\tau)} \\
 &= a_k e^{jk\omega_0 t} \underbrace{\int_{-\infty}^{\infty} d\tau h(\tau) e^{-jk\omega_0 \tau}}_{\text{Fourier Transform of } h(t) = \hat{H}(jk\omega_0)}
 \end{aligned}$$



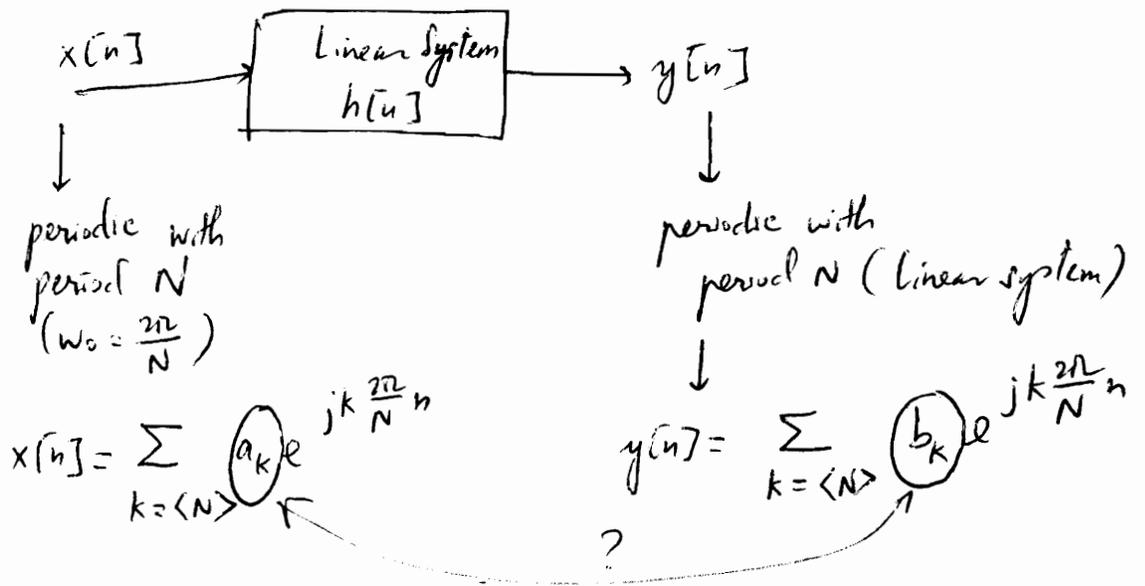
b) Now use  $x(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk\omega_0 t}$



Also  $y(t) = \sum_{k=-\infty}^{\infty} b_k e^{jk\omega_0 t} \rightarrow \boxed{b_k = a_k \hat{H}(jk\omega_0)}$

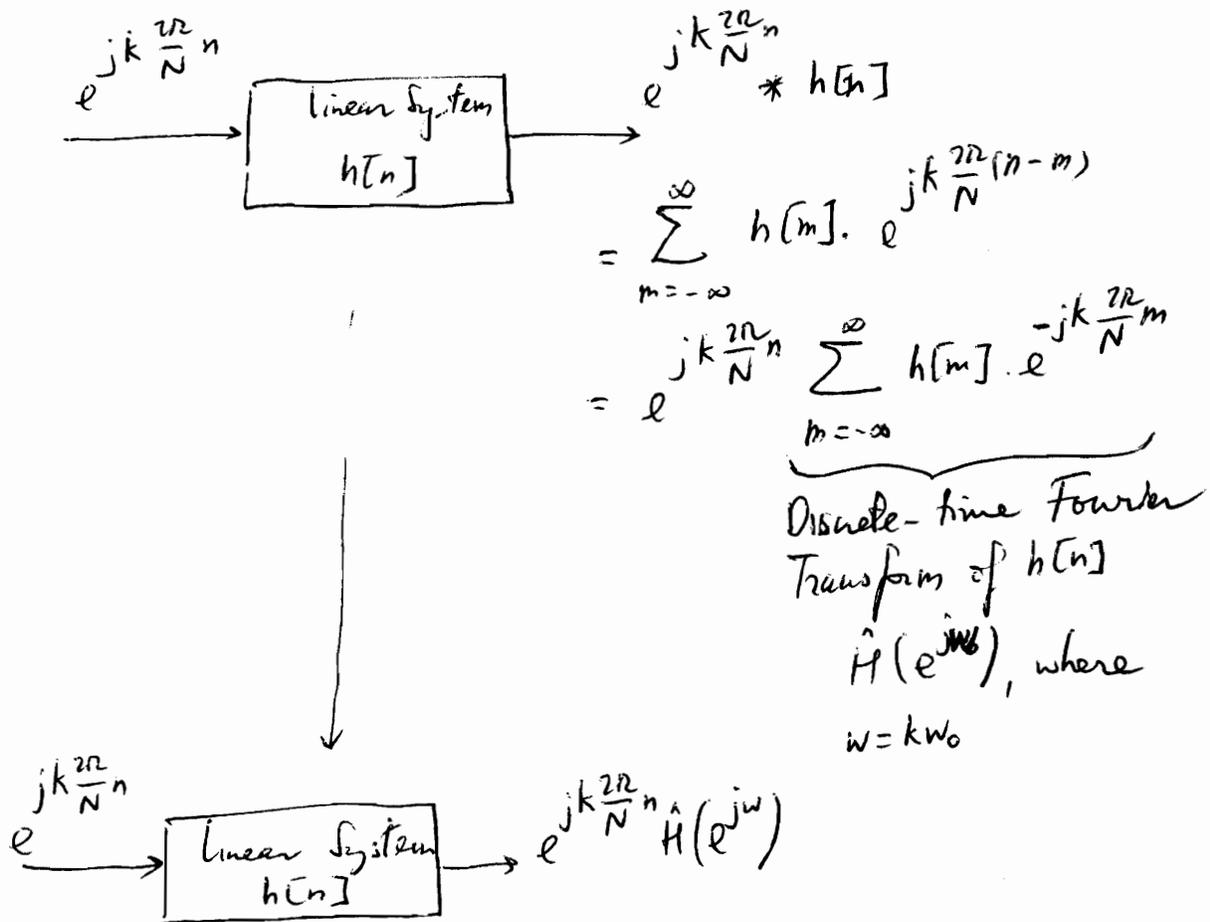
Conclusion. F.S coeff of the output of a linear system are simply the F.S coeff's of the input multiplied by the Fourier transform of the impulse response.

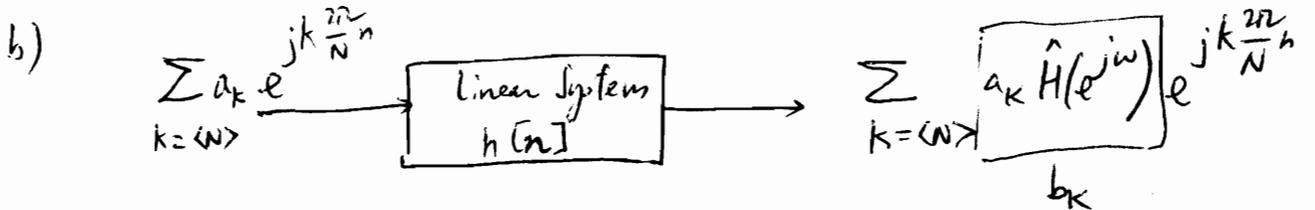
# Fourier Series & Linear Systems (discrete signals)



In 2 steps:

a)

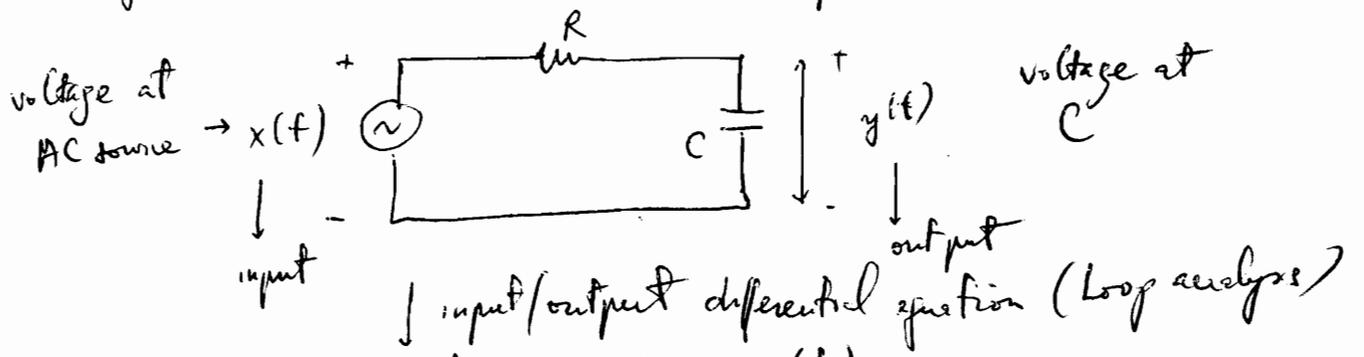




⇒ 
$$b_k = a_k \underbrace{\hat{H}(e^{jw})}_{\substack{\text{discrete-time Fourier Transform} \\ \text{of } h[n]}}$$

Filters as linear systems :

Example: RC circuit acts as a "low-pass" filter, because the Fourier Transform of the impulse response for an RC circuit shows a "low-pass" behavior



$$RC \frac{dy}{dt} + y(t) = x(t)$$
 ↳ solution: 
$$y(t) = \frac{1}{RC} \int_0^t d\lambda x(\lambda) e^{-\frac{1}{RC}(t-\lambda)}$$

$$= \frac{1}{RC} \int_0^\infty d\lambda x(\lambda) e^{-\frac{1}{RC}(t-\lambda)} u(t-\lambda)$$

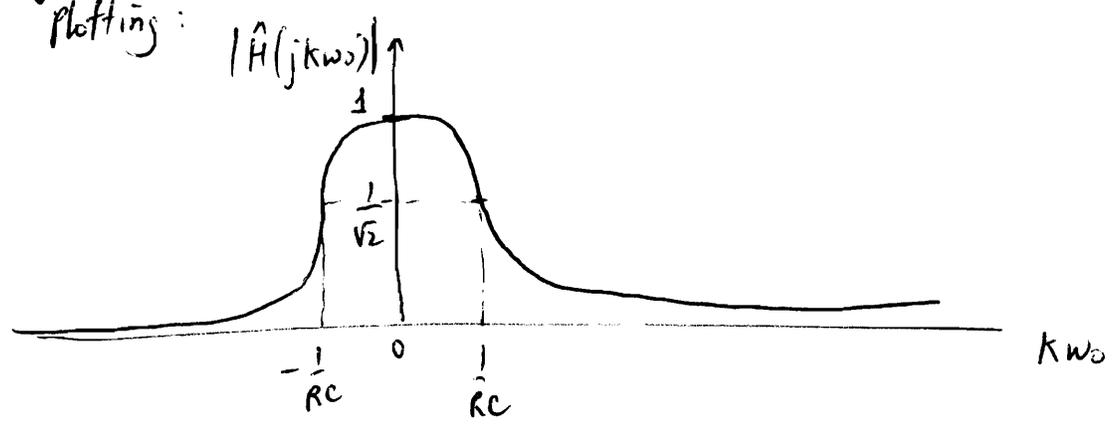
$$\rightarrow \boxed{h(t) = \frac{1}{RC} e^{-\frac{t}{RC}} u(t)}$$
 =  $x(t) * h(t) = \int_0^\infty d\lambda x(\lambda) h(t-\lambda)$   
 impulse response for RC circuit.

→ Fourier transform of  $h(t)$  is:

$$\begin{aligned} \hat{H}(j\omega) &= \hat{H}(jk\omega_0) = \int_{-\infty}^{\infty} dt h(t) e^{-jk\omega_0 t} = \frac{1}{RC} \int_{-\infty}^{\infty} dt e^{-\frac{t}{RC}} e^{-jk\omega_0 t} \\ &= \frac{1}{RC} \int_0^{\infty} dt e^{-(jk\omega_0 + \frac{1}{RC})t} \\ &= \frac{1}{RC} \left[ \frac{e^{-(jk\omega_0 + \frac{1}{RC})t}}{-(jk\omega_0 + \frac{1}{RC})} \right]_{t=0}^{t=\infty} = \frac{1}{RC} \frac{0 - 1}{-(jk\omega_0 + \frac{1}{RC})} \end{aligned}$$

$$\hat{H}(j\omega) = \frac{1}{1 + jk\omega_0 RC}$$

↓ plotting:



low-pass behavior = passing low frequencies

→ Conclusion: in general:  
 differential equation of type  
 is a low-pass filter!

systems governed by input/output

$$\frac{dy}{dt} + ay(t) = bx(t)$$

→ What discrete-time system would behave as a low-pass filter?

If we use finite-difference approximation for time derivative:

$$\frac{dy}{dt} = \lim_{\Delta \rightarrow 0} \frac{y(t) - y(t-\Delta)}{\Delta} \rightarrow \text{Finite difference approx.}$$

↓  
exact

$$\frac{dy}{dt} = \frac{y(t) - y(t-\Delta)}{\Delta}$$

$$= \frac{y[n] - y[n-1]}{\Delta}$$

$$\frac{dy}{dt} + ay = bx$$

↓

$t = n\Delta$  in discrete time  
 $t - \Delta = n\Delta - \Delta = (n-1)\Delta$   
 we ignore  $\Delta$  in time index notation.

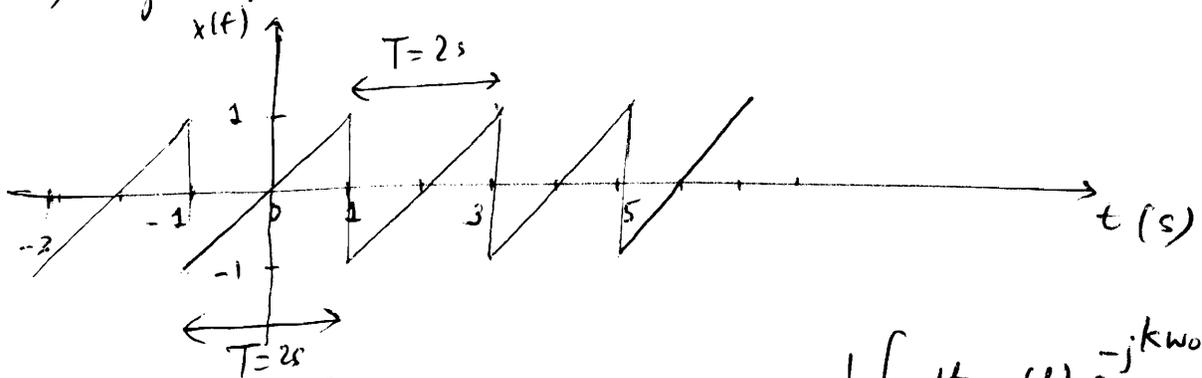
$$\frac{y[n] - y[n-1]}{\Delta} + ay[n] = bx[n]$$

$$\left(\frac{1}{\Delta} + a\right)y[n] - \frac{1}{\Delta}y[n-1] = bx[n]$$

$$\underbrace{\frac{1}{b}\left(\frac{1}{\Delta} + a\right)}_{\beta} y[n] - \underbrace{\frac{1}{b\Delta}}_{\alpha} y[n-1] = x[n]$$

→  $\beta y[n] + \alpha y[n-1] = x[n]$  input/output equation of a discrete-time system that behaves like a low-pass filter.

3.22 a) Figure P3.22a



Find  $a_k$ 's for  $x(t)$   $\rightarrow$   $a_k = \frac{1}{T} \int_{\text{centered period}} dt x(t) e^{-jk\omega_0 t}$

period of  $x(t) = T = 2s$ ;  $\omega_0 = \frac{2\pi}{T} = \pi$   
 (from the figure above)

$$a_k = \frac{1}{2} \int_{-1}^1 dt t e^{-jk\omega_0 t} \rightarrow \begin{cases} \text{integration by parts} \\ \text{derivative trick} \leftarrow \\ \text{table} \end{cases}$$

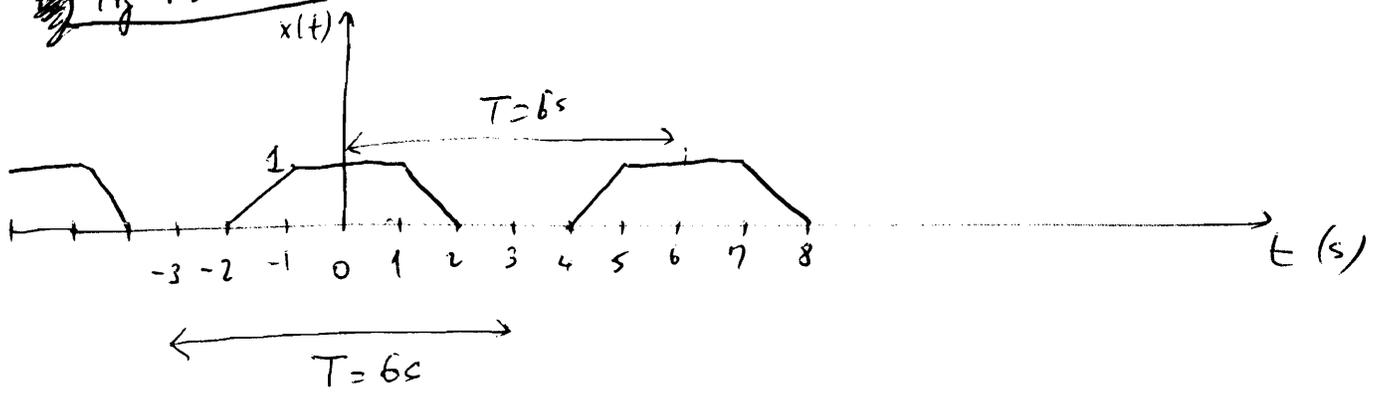
$$a_k = \frac{1}{2} \frac{1}{-jk} \frac{d}{d\omega_0} \left[ \int_{-1}^1 dt e^{-jk\omega_0 t} \right] = \frac{e^{-jk\omega_0} - e^{jk\omega_0}}{-jk\omega_0} = \frac{-2j \sin k\omega_0}{jk\omega_0}$$

$$a_k = \frac{1}{2} \frac{1}{-jk} \frac{d}{d\omega_0} \left( \frac{2 \sin k\omega_0}{k\omega_0} \right) = \frac{1}{-jk} \left[ \frac{k \cos k\omega_0}{k\omega_0} - \frac{\sin k\omega_0}{k\omega_0^2} \right]$$

$$= \frac{1}{-jk\omega_0} \left[ \cos k\omega_0 - \frac{\sin k\omega_0}{k\omega_0} \right] \xrightarrow{\omega_0 = \pi} \frac{1}{-jk\pi} \left[ \cos k\pi - \frac{\sin k\pi}{k\pi} \right] = \frac{1}{-jk\pi} \left[ (-1)^k - 0 \right]$$

$$\Rightarrow a_k = \begin{cases} \frac{j}{k\pi} (-1)^k & k \neq 0 \\ \frac{1}{2} \int_{-1}^1 dt t = \left[ \frac{t^2}{4} \right]_{-1}^1 = 0 & k = 0 \end{cases}$$

Fig P3.22b:



$$a_k = \frac{1}{T} \int_T dt x(t) e^{-jk\omega_0 t}$$

→ centered period of  $x(t)$  →

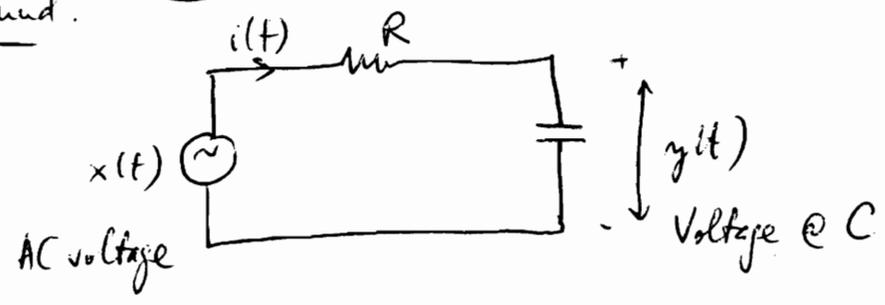
$$x(t) = \begin{cases} t+2 & -2 < t < -1 \\ 1 & -1 < t < 1 \\ -t+2 & 1 < t < 2 \end{cases}$$

$$\rightarrow a_k = \frac{1}{6} \left\{ \int_{-2}^{-1} dt (t+2) e^{-jk\omega_0 t} + \int_{-1}^1 dt e^{-jk\omega_0 t} + \int_1^2 dt (-t+2) e^{-jk\omega_0 t} \right\}$$

use from previous Fig P.3.22a:

$$\int_a^b dt t e^{-jk\omega_0 t} = \frac{1}{-jk\omega_0} \left[ \frac{e^{-jk\omega_0 t}}{-jk\omega_0} - t \right]_a^b$$

Background for pgs



Loop equation:  $x(t) = i(t)R + y(t)$

input/output equation (involving  $x$  &  $y$ )  $\rightarrow$  eliminate  $i(t)$

$$y(t) = \frac{1}{C} \int dt i(t) \rightarrow \frac{dy}{dt} = \frac{1}{C} i(t) \rightarrow i(t) = C \frac{dy}{dt}$$

$x(t) = RC \frac{dy}{dt} + y(t)$

1<sup>st</sup> order differential equation. (non-homogeneous)

$\rightarrow \frac{dy}{dt} + ay = bx$  (general form)  $\rightarrow RC$  circuit  $\begin{cases} a = \frac{1}{RC} \\ b = \frac{1}{RC} \end{cases}$

$\hookrightarrow$  solution:  $y(t) = y(t_0) e^{-a(t-t_0)} + b \int_{t_0}^t d\lambda x(\lambda) e^{-a(t-\lambda)}$

Why?: using the integrating factor  $b e^{at}$ : multiplying it to both sides of the D.E.

$$\frac{dy}{dt} b e^{at} + a y b e^{at} = b x e^{at}$$

$$b \frac{d}{dt} (y e^{at}) = b x e^{at} \rightarrow y e^{at} \Big|_{t_0}^t = b \int_{t_0}^t dt x e^{at}$$

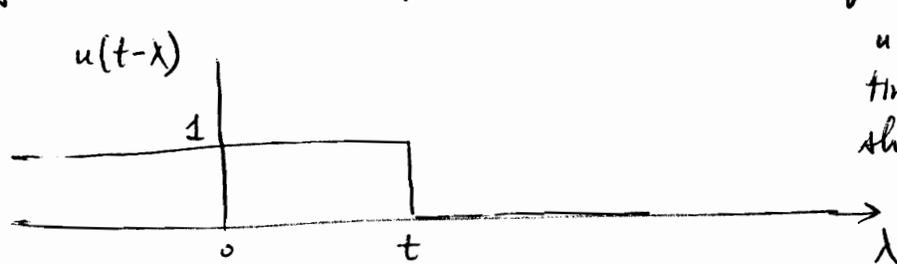
$$y(t) e^{at} - y(t_0) e^{at_0} = b \int_{t_0}^t d\lambda x(\lambda) e^{a\lambda}$$

Then dividing both sides by  $e^{at}$ :

$$y(t) = y(t_0) e^{-a(t-t_0)} + b \int_{t_0}^t d\lambda x(\lambda) e^{-a(t-\lambda)}$$

For our RC circuit:  $\left\{ \begin{array}{l} t_0=0 \\ y(0)=0 \\ a = \frac{1}{RC} = b \end{array} \right\} \rightarrow y(t) = \frac{1}{RC} \int_0^t d\lambda x(\lambda) e^{-\frac{1}{RC}(t-\lambda)}$  (71)

Now I can rewrite the upper integration limit  $t$  to  $\infty$  if a factor of  $u(t-\lambda)$  is incorporated into the integrand since:

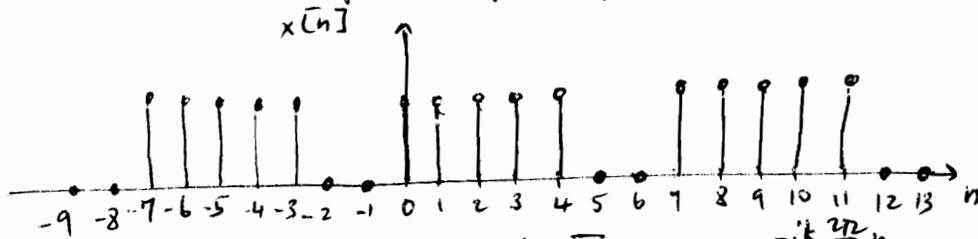


$u(t-\lambda)$  is  $u(\lambda)$  time reversed & shifted by  $t > 0$

$\Rightarrow y(t) = \frac{1}{RC} \int_0^{\infty} d\lambda x(\lambda) e^{-\frac{1}{RC}(t-\lambda)} u(t-\lambda)$  (2)

(1) & (2) are equal since the integrand in (2) is non-trivial only b/w 0 & t

3.22 a) Find F.S. coefficients  $a_k$  for different discrete-time periodic signals.

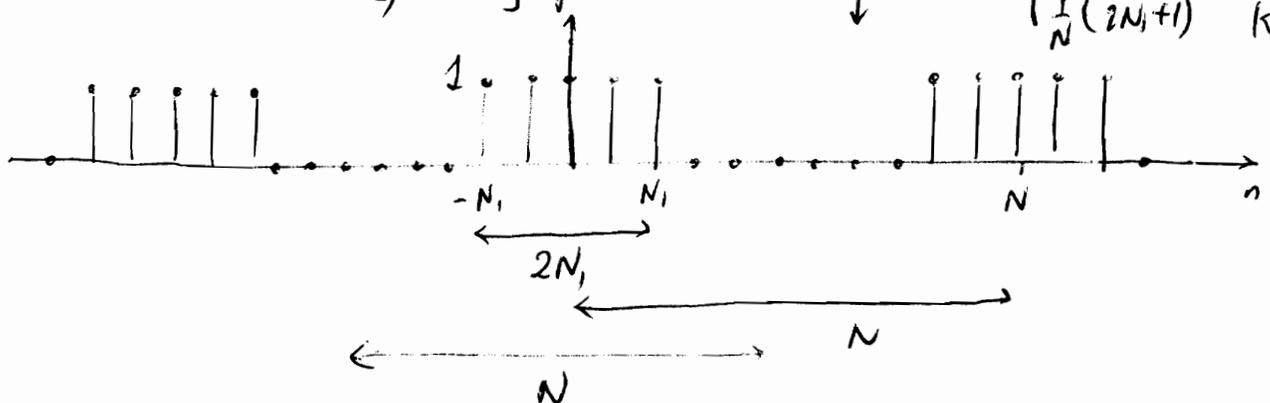


$x[n] = \sum_{k=\langle N \rangle} a_k e^{jk \frac{2\pi}{N} n}$

$N$  = period of signal.

Alternative 1:  $a_k = \frac{1}{N} \sum_{n=\langle N \rangle} x[n] e^{-jk \frac{2\pi}{N} n}$

Alternative 2: using previous results:  $a_k = \begin{cases} \frac{1}{N} \frac{\sin \frac{\pi k}{N} (2N+1)}{\sin \frac{\pi k}{N}} & k \neq 0 \\ \frac{1}{N} (2N+1) & k=0 \end{cases}$  (pg 59)



Alternative 2) (shorter) we do not need to do a new geometric sum but will need to incorporate a time shift into the  $a_k$ 's

Comparing with the original signal  $\left\{ \begin{array}{l} N_2 = 2 \\ N = 7 \\ \text{time shift } n_0 = 2 \end{array} \right. \leftarrow \text{Table 3.2}$

$$x[n-n_0] \longleftrightarrow a_k e^{-jk \frac{2\pi}{N} n_0}$$

$$\begin{array}{l} k \neq 0 = \frac{1}{7} \frac{\sin(\frac{5\pi k}{7})}{\sin(\frac{\pi k}{7})} e^{jk \frac{4\pi}{7}} \\ k = 0 = \frac{5}{7} e^{-jk \frac{4\pi}{7}} \end{array}$$

$$\rightarrow a_k = \begin{cases} \frac{1}{7} \frac{\sin[\frac{\pi k}{7}(5)]}{\sin[\frac{k\pi}{7}]} e^{-jk \frac{2\pi}{7} 2} \\ \frac{1}{7}(5) e^{-jk \frac{2\pi}{7} 2} \end{cases}$$

3.32

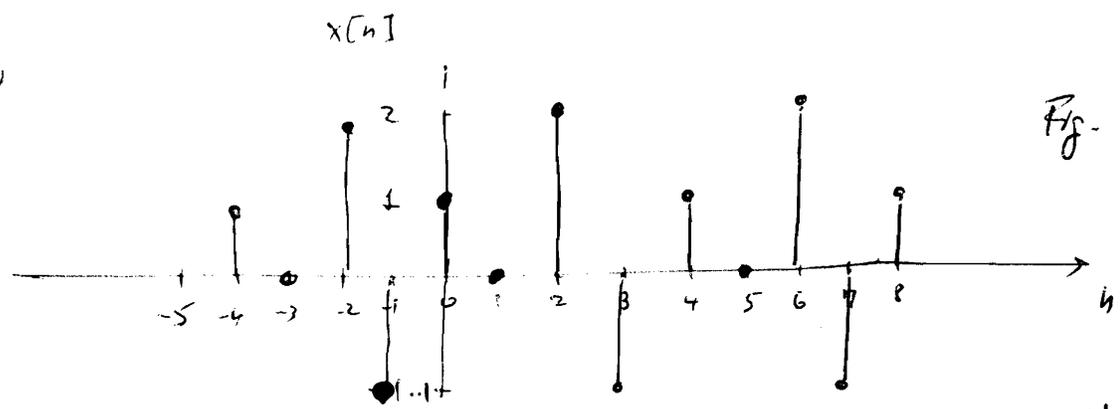


Fig. P3.32

$x[n]$  : periodic with  $N=4 \rightarrow x[n] = \sum_{k=\langle 4 \rangle} a_k e^{jk \frac{2\pi}{4} n}$

$$\Rightarrow x[n] = \sum_{k=0}^3 a_k e^{jk \frac{2\pi}{4} n}$$

To find  $a_k$ 's (4)  $\rightarrow$  set the system of 4 equations:

$$\begin{aligned} n=0 \rightarrow x[0] = 1 &= a_0 + a_1 + a_2 + a_3 \\ n=1 \rightarrow x[1] = 0 &= a_0 + a_1 e^{j\frac{\pi}{2}} + a_2 e^{j\pi} + a_3 e^{j\frac{3\pi}{2}} = a_0 + ja_1 - a_2 - ja_3 \\ n=2 \rightarrow x[2] = 2 &= a_0 + a_1 e^{j\pi} + a_2 e^{j2\pi} + a_3 e^{j3\pi} = a_0 - a_1 + a_2 - a_3 \\ n=3 \rightarrow x[3] = -1 &= a_0 + a_1 e^{j\frac{3\pi}{2}} + a_2 e^{j3\pi} + a_3 e^{j\frac{9\pi}{2}} = a_0 - ja_1 - a_2 + ja_3 \end{aligned}$$

$$\rightarrow \begin{cases} 1 = a_0 + a_1 + a_2 + a_3 & (1) \\ 0 = a_0 + ja_1 - a_2 - ja_3 & (2) \\ 2 = a_0 - a_1 + a_2 - a_3 & (3) \\ -1 = a_0 - ja_1 - a_2 + ja_3 & (4) \end{cases}$$

$$(2)+(4) \rightarrow -1 = 2a_0 - 2a_2$$

$$(1)+(3) \rightarrow 3 = 2a_0 + 2a_2$$

$$\rightarrow a_2 = \frac{3-2a_0}{2} \rightarrow \boxed{a_2=1}$$

$$2 = 4a_0 \rightarrow \boxed{a_0 = \frac{1}{2}}$$

$$\left. \begin{array}{l} (2) \\ (4) \end{array} \right\} \begin{cases} 0 = \frac{1}{2} + ja_1 - 1 - ja_3 \rightarrow \frac{1}{2} = ja_1 - ja_3 \\ -1 = \frac{1}{2} - ja_1 - 1 + ja_3 \rightarrow -\frac{1}{2} = -ja_1 + ja_3 \end{cases}$$
  

$$\left. \begin{array}{l} (1) \\ (3) \end{array} \right\} \begin{cases} 1 = \frac{1}{2} + a_1 + 1 + a_3 \rightarrow -\frac{1}{2} = a_1 + a_3 \\ 2 = \frac{1}{2} - a_1 + 1 - a_3 \rightarrow \frac{1}{2} = -a_1 - a_3 \end{cases}$$
  

$$\rightarrow \begin{cases} \frac{1}{2}j = -a_1 + a_3 \\ \frac{1}{2} = -a_1 - a_3 \end{cases} \rightarrow \begin{cases} \boxed{a_1 = -\frac{1}{4}(1+j)} \\ \boxed{a_3 = -\frac{1}{4}(1-j)} \end{cases}$$

Try to obtain some results using formula for FS coefficients instead of solving a system of 4 equations.

$$a_k = \frac{1}{4} \sum_{n=0}^3 x[n] e^{-jk(\frac{2\pi}{4})n}$$

$$k=0 \quad a_0 = \frac{1}{4} \left\{ \begin{array}{cccc} 1 & + & 0 & + & 2 & - & 1 \\ \downarrow & & \downarrow & & \downarrow & & \downarrow \\ x[0] & & x[1] & & x[2] & & x[3] \end{array} \right\} = \frac{1}{2} \quad \checkmark$$

$$k=1 \quad a_1 = \frac{1}{4} \left\{ 1 + 0 + \underbrace{2 e^{-j\frac{4\pi}{4}}}_{-1} - \underbrace{1}_{j} e^{-j\frac{6\pi}{4}} \right\} = \frac{1}{4} \{-1 - j\} \quad \checkmark$$

$$k=2 \quad a_2 = \frac{1}{4} \left\{ 1 + 0 + \underbrace{2 e^{-j\frac{8\pi}{4}}}_1 - \underbrace{1}_{-1} e^{-j\frac{10\pi}{4}} \right\} = \frac{1}{4} \{4\} = 1 \quad \checkmark$$

$$k=3 \quad a_3 = \frac{1}{4} \left\{ 1 + 0 + \underbrace{2 e^{-j\frac{12\pi}{4}}}_{-1} - \underbrace{1}_{j} e^{-j\frac{14\pi}{4}} \right\} = \frac{1}{4} \{-1 + j\} \quad \checkmark$$

3.46

a) Given  $x(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk\omega_0 t}$  &  $y(t) = \sum_{k=-\infty}^{\infty} b_k e^{jk\omega_0 t}$

(both  $x$  &  $y$  are periodic with same period  $\frac{2\pi}{\omega_0}$ )

Prove that if  $z(t) \equiv x(t) \cdot y(t) = \sum_{k=-\infty}^{\infty} c_k e^{jk\omega_0 t}$

product

$$\Rightarrow \boxed{c_k = \sum_{n=-\infty}^{\infty} a_n b_{k-n}}$$

$c_k$ 's are the convolution of  $a_k$  &  $b_k$

Proof:

$$x(t)y(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk\omega_0 t} \cdot \sum_{l=-\infty}^{\infty} b_l e^{jl\omega_0 t}$$

use  $l$  as dummy index for this summation for not missing cross terms in the big product.

regroup

$$\uparrow = \sum_{k=-\infty}^{\infty} \sum_{l=-\infty}^{\infty} a_k b_l e^{j(k+l)\omega_0 t}$$

$k$  &  $l$  are dummy indices  $\rightarrow$  rename  $k \rightarrow k-l$

$$x(t)y(t) = \sum_{k=-\infty}^{\infty} \left( \sum_{l=-\infty}^{\infty} a_{k-l} b_l \right) \underbrace{e^{j(k-l+l)\omega t}}_{e^{jk\omega t}}$$

$$= \sum_{k=-\infty}^{\infty} \left( \sum_{l=-\infty}^{\infty} a_{k-l} b_l \right) e^{jk\omega t}$$

Recall:  $z(t) = \sum_{k=-\infty}^{\infty} c_k e^{jk\omega t}$

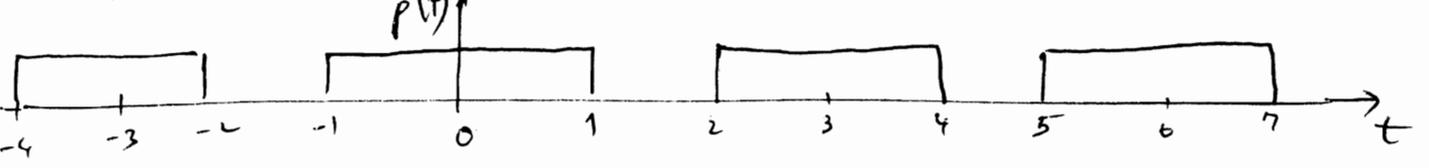
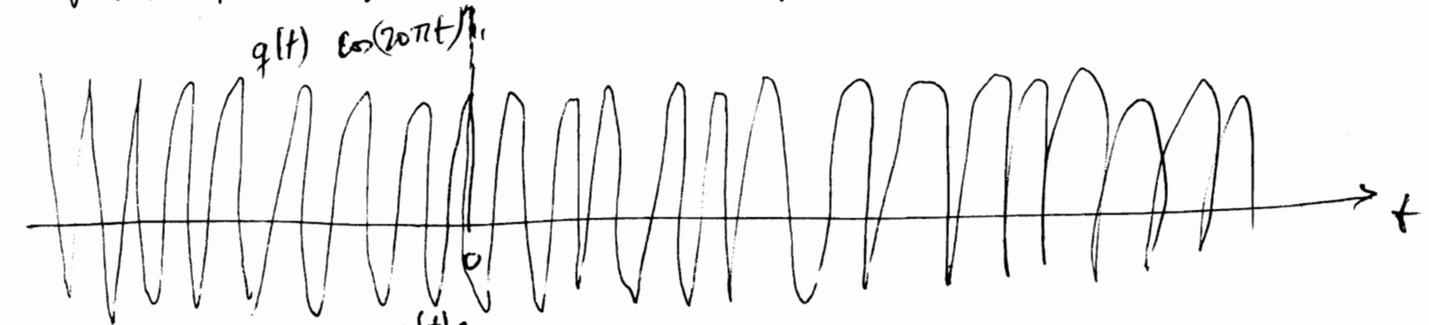
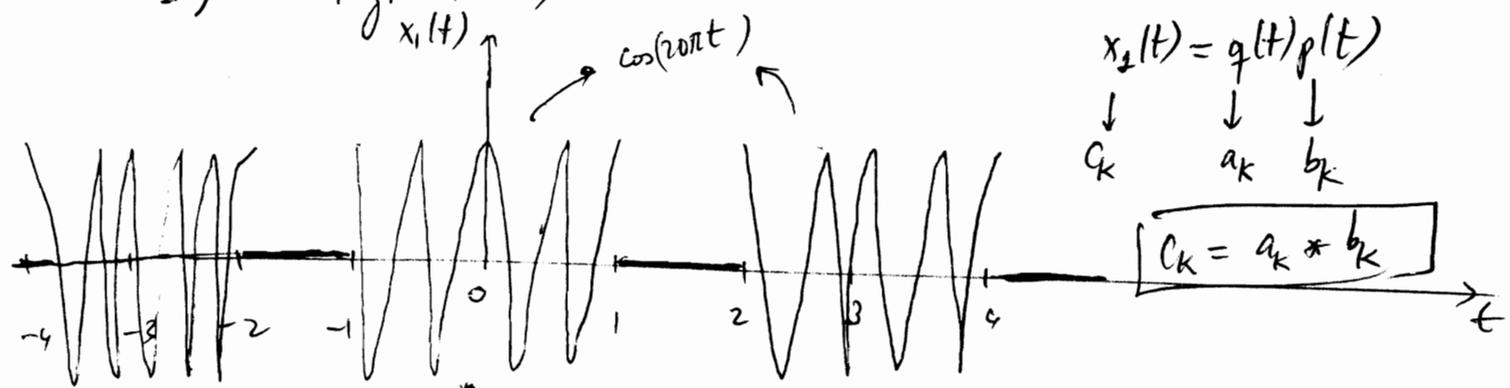
$$\rightarrow c_k = \sum_{l=-\infty}^{\infty} a_{k-l} b_l \quad \text{or} \quad l \rightarrow n \quad c_k = \sum_{n=-\infty}^{\infty} a_{k-n} b_n$$

$$c_k = b * a = a * b = \sum_{n=-\infty}^{\infty} a_n b_{k-n}$$

↓  
convolution is commutative

what we wanted!

b) Fig P3.46 a)



Strategy: find  $a_k$  (F.S. coefficients for  $\cos(20\pi t)$ )  
 &  $b_k$  (F.S. coefficients for  $p(t)$ ): train of rectangular pulses of width 2 ( $T_1=1$ ) & period 3 ( $T=3$ )

$a_k$ 's:  $\rightarrow g(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk\omega_0 t}$  where  $\omega_0 = \frac{2\pi}{T} = \frac{2\pi}{3}$

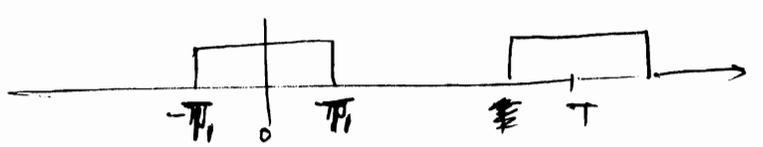
$= \sum_{k=-\infty}^{\infty} a_k e^{jk \frac{2\pi}{3} t}$

also  $\downarrow$   
 $\cos(20\pi t) = \frac{e^{j20\pi t} + e^{-j20\pi t}}{2}$

$\rightarrow a_k = \begin{cases} k=30 \rightarrow a_{30} = \frac{1}{2} \\ k=-30 \rightarrow a_{-30} = \frac{1}{2} \\ \text{otherwise } a_k = 0 \end{cases}$

Then:  
 $\cos(20\pi t) = \frac{1}{2} \delta(k-30) e^{jk \frac{2\pi}{3} t} + \frac{1}{2} \delta(k+30) e^{jk \frac{2\pi}{3} t}$

$= \underbrace{\left[ \frac{1}{2} \delta(k-30) + \frac{1}{2} \delta(k+30) \right]}_{a_k} e^{jk \frac{2\pi}{3} t}$

$b_k$ 's:   $\rightarrow b_k = \begin{cases} \frac{2 \sin k\omega_0 T_1}{k\omega_0 T} & k \neq 0 \\ \frac{2T_1}{T} & k=0 \end{cases}$

In this problem  $\begin{cases} T_1=1 \\ T=3 \\ \omega_0 = \frac{2\pi}{3} \end{cases} \rightarrow b_k = \begin{cases} \frac{2 \sin k \frac{2\pi}{3} 1}{k \frac{2\pi}{3} 3} = \frac{2 \sin k \frac{2\pi}{3}}{k 2\pi} & k \neq 0 \\ \frac{2}{3} & k=0 \end{cases}$

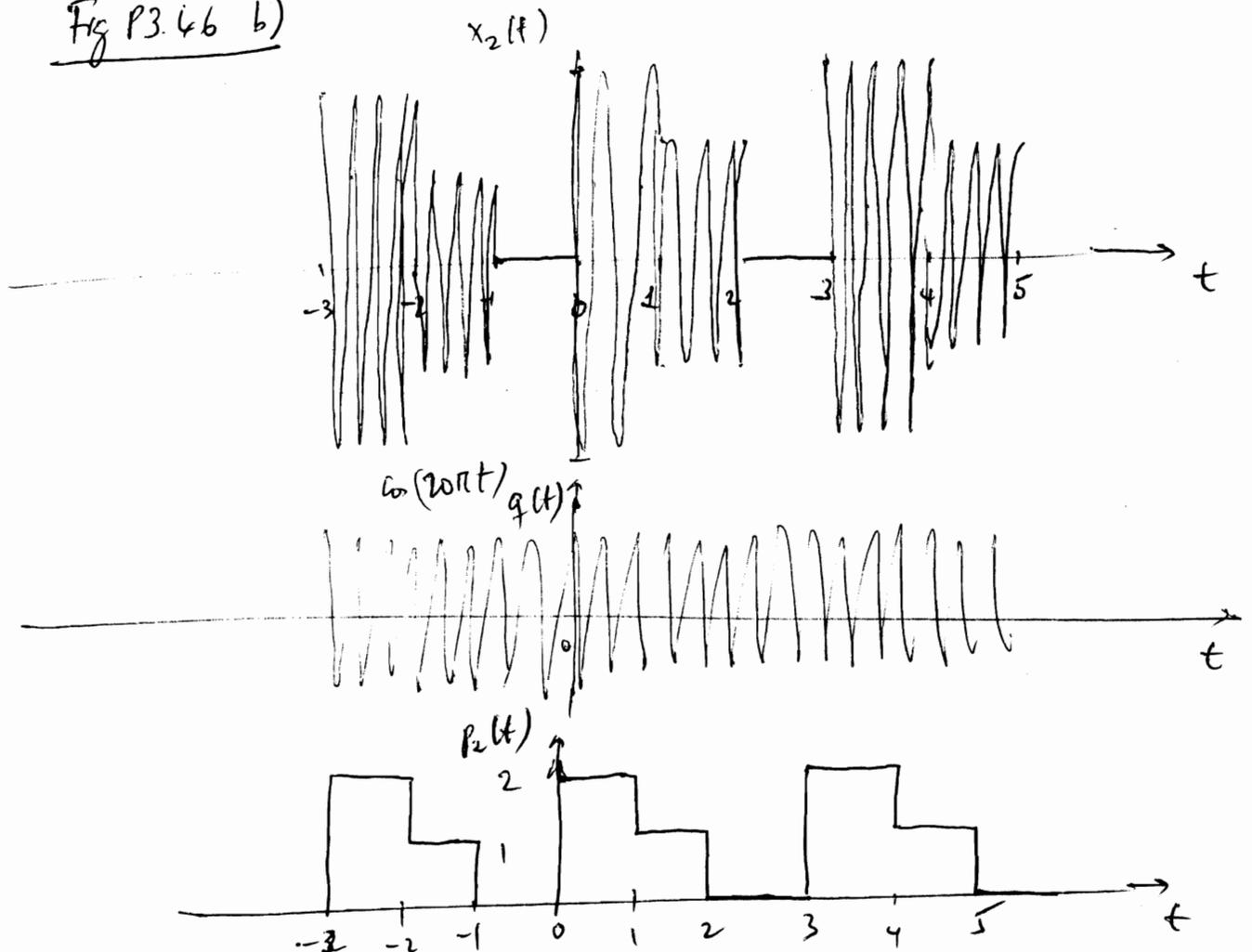
$$\rightarrow c_k = a_k * b_k = \underbrace{\frac{1}{2} [\delta(k-30) + \delta(k+30)]}_{a_k} * \underbrace{\frac{2 \sin k \frac{2\pi}{3}}{k 2\pi}}_{b_k}$$

Recall convolution property:  $f[n] * \delta[n-j] = f[n-j]$

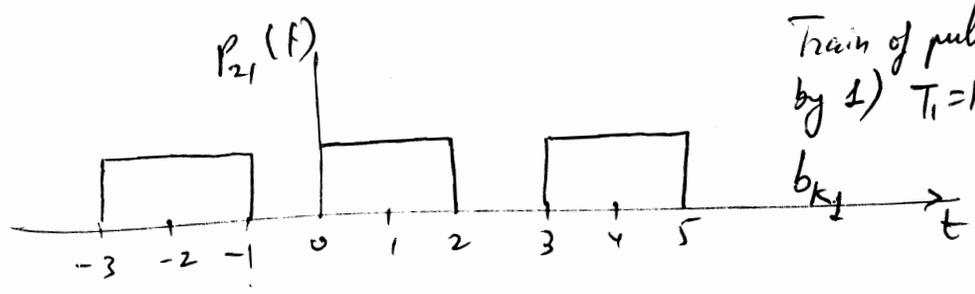
$$\hookrightarrow c_k = \frac{1}{2} \left[ \frac{2 \sin(k 30) \frac{2\pi}{3}}{(k-30) 2\pi} + \frac{2 \sin(k+30) \frac{2\pi}{3}}{(k+30) 2\pi} \right]$$

↓  
F.S. coefficients for  $x_1(t)$ .

Fig P3.46 b)



Note:  $p_2(t)$  is the sum of 2 signals below:



Train of pulses (shifted by 1)  $T_1 = 1$  &  $T = 3$



Train of pulses (shifted by  $\frac{1}{2}$ )  $T_1 = \frac{1}{2}$ ,  $T = 3$

$$\begin{aligned}
 p_2(t) &= p_{21}(t) + p_{22}(t) \\
 &= \sum_{k=-\infty}^{\infty} b_{k1} e^{jk\omega t} + \sum_{k=-\infty}^{\infty} b_{k2} e^{jk\omega t} \\
 &= \sum_{k=-\infty}^{\infty} (b_{k1} + b_{k2}) e^{jk\omega t}
 \end{aligned}$$

$b_k = b_{k1} + b_{k2}$

$\sum_{k=-\infty}^{\infty} b_k e^{jk\omega t}$

$\rightarrow b_k$ 's  $\rightarrow$

$$b_{k1} = \frac{2 \sin k \frac{2\pi}{3} 1}{k \frac{2\pi}{3}} e^{-jk \frac{2\pi}{3}} = \frac{2 \sin k \frac{2\pi}{3}}{k 2\pi} e^{-jk \frac{2\pi}{3}}$$

shift of 1

$$b_{k2} = \frac{2 \sin k \frac{2\pi}{3} \frac{1}{2}}{k \frac{2\pi}{3}} e^{-jk \frac{2\pi}{3} \frac{1}{2}} = \frac{2 \sin k \frac{\pi}{3}}{k 2\pi} e^{-jk \frac{\pi}{3}}$$

$$b_k = b_{k1} + b_{k2}$$

$$\Rightarrow c_k = a_k * b_k = a_k * (b_{k_1} + b_{k_2})$$

$$= \left[ \frac{1}{2} \delta(k-30) + \frac{1}{2} \delta(k+30) \right] * \left\{ \frac{2 \sin k \frac{2\pi}{3}}{k 2\pi} e^{-jk \frac{2\pi}{3}} + \frac{2 \sin k \frac{\pi}{3}}{k 2\pi} e^{-jk \frac{\pi}{3}} \right\}$$

F.S. coefficients for  $q(t) = \cos(20\pi t)$ 
F.S. coefficients for  $p_2(t) = p_{21}(t) + p_{22}(t)$

Convolution with a delta is equivalent to shifting to the center of the delta

$$= \frac{\sin(k-30) \frac{2\pi}{3}}{(k-30) 2\pi} e^{-j(k-30) \frac{2\pi}{3}} + \frac{\sin(k-30) \frac{\pi}{3}}{(k-30) 2\pi} e^{-j(k-30) \frac{\pi}{3}}$$

$$+ \frac{\sin(k+30) \frac{2\pi}{3}}{(k+30) 2\pi} e^{-j(k+30) \frac{2\pi}{3}} + \frac{\sin(k+30) \frac{\pi}{3}}{(k+30) 2\pi} e^{-j(k+30) \frac{\pi}{3}}$$

3.48

$$x[n] = \sum_{k \in \langle N \rangle} a_k e^{jk \left(\frac{2\pi}{N}\right) n}$$

periodic with period  $N$ 
F.S. coefficients of  $x[n]$

a) Find  $b_k$  for  $x[n-n_0]$

$$x[n-n_0] = \sum_{k \in \langle N \rangle} a_k e^{jk \frac{2\pi}{N} (n-n_0)} = \sum_{k \in \langle N \rangle} \underbrace{a_k e^{-jk \frac{2\pi}{N} n_0}}_{b_k} e^{jk \frac{2\pi}{N} n}$$

b) Find  $b_k$  for  $x[n] - x[n-1]$

$$b_k = a_k - a_k e^{jk \frac{2\pi}{N}} = a_k (1 - e^{-jk \frac{2\pi}{N}})$$

( $n_0 = 1$ , use a)

c)  $\rightarrow$  d)

3.52

$x[n]$  real periodic with period  $N$  & complex F.S. coefficients

$$x[n] = \sum_{k \in \langle N \rangle} a_k e^{jk \frac{2\pi}{N} n}$$

F.S. expansion for  $x[n]$

Notation  $\rightarrow$

$$a_k = b_k + jc_k \text{ where } b_k = \text{Re}\{a_k\}; c_k = \text{Im}\{a_k\}$$

a) Show that  $a_{-k} = a_k^* = b_k - jc_k$  when we replace  $k \rightarrow -k$  we get the complex conjugate of  $a_k$ .

Reversed equation:  $a_k = \frac{1}{N} \sum_n x[n] e^{-jk \frac{2\pi}{N} n}$

$$a_{-k} = \frac{1}{N} \sum_n x[n] e^{+jk \frac{2\pi}{N} n}$$

$$a_k^* = \frac{1}{N} \left( \sum_n x[n] e^{-jk \frac{2\pi}{N} n} \right)^* = \frac{1}{N} \sum_n x[n] e^{+jk \frac{2\pi}{N} n}$$

$$\Rightarrow a_k^* = a_{-k}$$

$$b_k - jc_k = b_{-k} + jc_{-k} \begin{cases} b_k = b_{-k} \\ c_k = -c_{-k} \end{cases}$$

b) Suppose  $N$  is even show that  $a_{\frac{N}{2}}$  is real

$$a_{\frac{N}{2}} = \frac{1}{N} \sum_n x[n] e^{-j \frac{N}{2} \frac{2\pi}{N} n} = \frac{1}{N} \sum_n x[n] (-1)^n = \text{real number!}$$

$e^{-j\pi n} = (-1)^n$

(Complex exponential is a real number when  $k = \frac{N}{2}$ )

Note  $a_{\frac{N}{2}}$  is also real!

Find that...