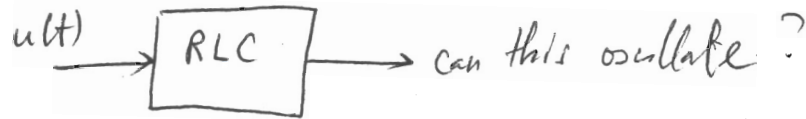
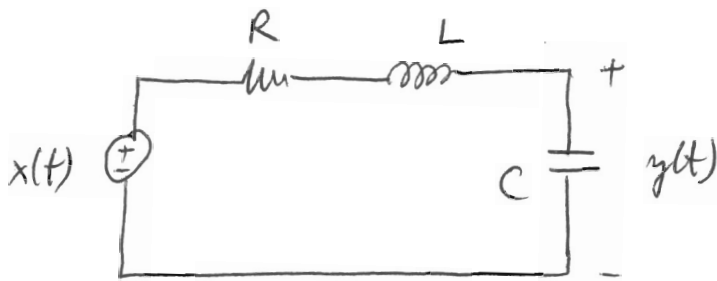


6.19

(117)

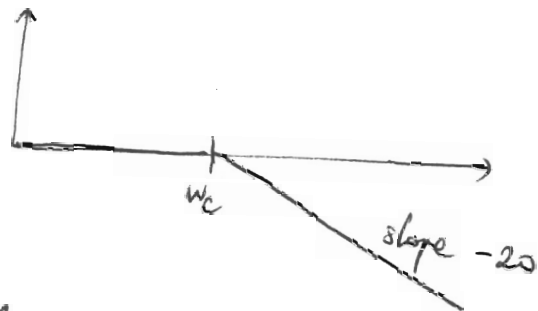


$$\hat{H} = \frac{\hat{Y}}{\hat{X}} = \frac{\text{impedance at } C}{\text{total impedance}} = \frac{\frac{1}{j\omega C}}{R + j\omega L + \frac{1}{j\omega C}} = \frac{1}{j\omega RC + (j\omega)^2 LC + 1}$$

Voltage division using Phasors

2nd order pole.

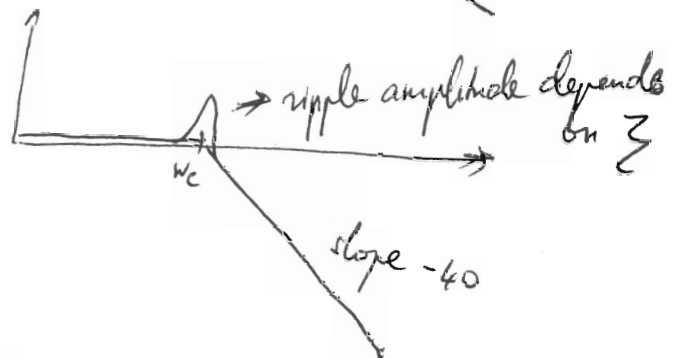
Bode Plot: 1st order pole:



2nd order pole:

$$\frac{1}{1 + 2(j\omega\tau\xi) + (j\omega\tau)^2}$$

$\tau \downarrow \xi \downarrow$
tan xi



$$\tau = \sqrt{LC} \rightarrow 2\xi\tau = RC$$

$$\xi = \frac{RC}{2\tau} = \frac{RC}{2\sqrt{LC}} = \frac{R}{2}\sqrt{\frac{C}{L}}$$

$$y(t) = F^{-1} \left[\left(\frac{1}{j\omega} + \pi \delta(\omega) \right) \frac{1}{j\omega RC + (j\omega\tau)^2 + 1} \right]$$

has a ripple depending on ξ

→ oscillation

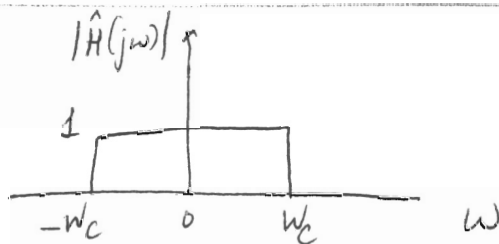
Can we adjust R, L, C such that the oscillation is eliminated? (118)

Yes, since there is no ripple when $\xi \geq 1$ or $\frac{R}{2} \sqrt{\frac{C}{L}} \geq 1$
 $\hookrightarrow$ no oscillation

or $\boxed{R \geq 2\sqrt{\frac{L}{C}}}$

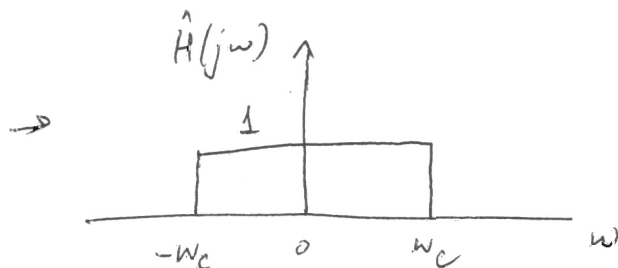
6.23

Low-pass filter:



Sketch impulse response for:

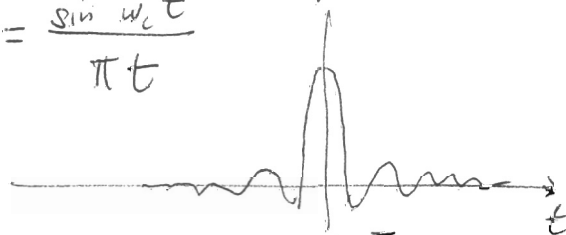
a) $\text{Phase}(\hat{H}(jw)) = 0$ or $\hat{H}(jw) = |\hat{H}(jw)| \cdot \frac{e^{j0}}{1}$



$\rightarrow h(t) = F^{-1}[\hat{H}]$

what is the inverse Fourier Transform of a rectangular pulse?

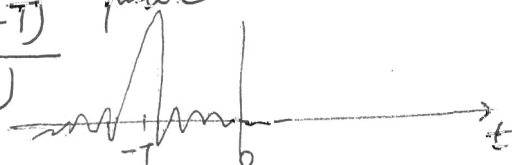
Table 4.2: Row #9: $h(t) = \frac{\sin w_c t}{\pi t}$



b) $\text{Phase}(\hat{H}(jw)) = \omega T \rightarrow \hat{H}(jw) = |\hat{H}(jw)| e^{j\omega T}$

rectangular pulse $\hookrightarrow$ time-shift

$h(t) = F^{-1}[\hat{H}] = \frac{\sin w_c (t+T)}{\pi (t+T)}$

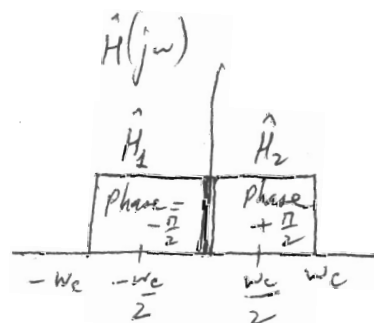


c) $\text{Phase}(H(j\omega)) = \begin{cases} 2 & \omega > 0 \\ -\frac{\pi}{2} & \omega < 0 \end{cases}$

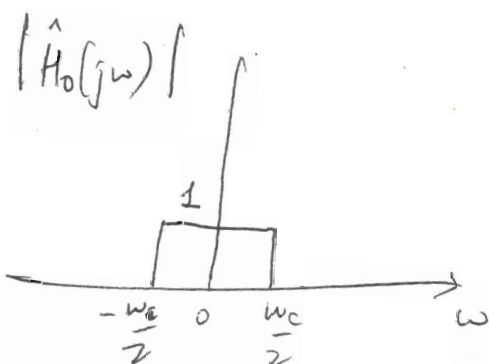
119



=



$$\hat{H}(j\omega) = \hat{H}_1(j\omega) + \hat{H}_2(j\omega) = \underbrace{j \left| \hat{H}_0(j(\omega + \frac{\omega_c}{2})) \right|}_{\text{phase} = -\frac{\pi}{2}} + \underbrace{j \left| \hat{H}_0(j(\omega - \frac{\omega_c}{2})) \right|}_{\text{phase} = +\frac{\pi}{2}}$$



Shift in frequency = convolution with a delta function

$$\hat{H}(j\omega) = \underbrace{|\hat{H}_0(j\omega)|}_{\downarrow \text{Table 4.2 row \# 9}} * \underbrace{\left[-j \delta(\omega + \frac{\omega_c}{2}) + j \delta(\omega - \frac{\omega_c}{2}) \right]}_{\downarrow \text{Table 4.2 row \# 4}}$$

$$h(t) = \frac{\sin \frac{\omega_c}{2} t}{\pi t} \left(-\frac{1}{\pi} \sin \frac{\omega_c}{2} t \right)$$

$$h(t) = \left(-\frac{1}{\pi} \right) \frac{\sin^2 \frac{\omega_c}{2} t}{\pi t}$$

(6.31)

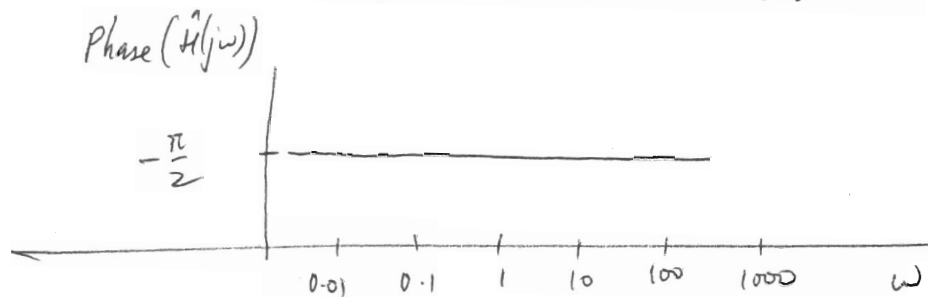
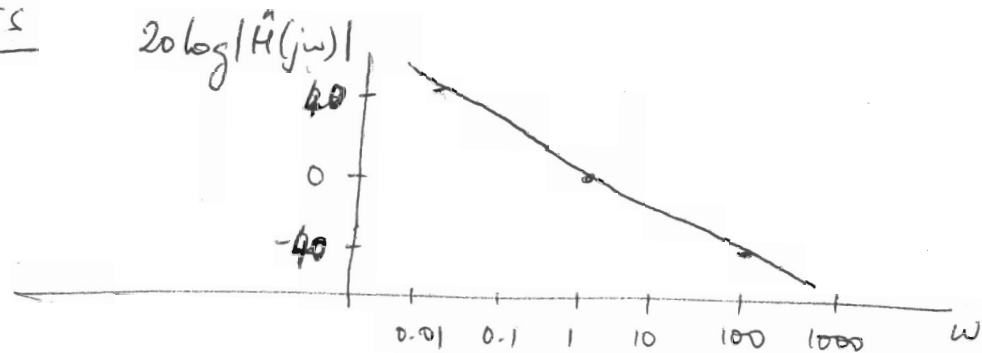
Integrator: $\hat{H}(j\omega) = \frac{1}{j\omega} + \pi \delta(\omega)$

(120)

b/c integration of a
constant from $t = -\infty$
at $\omega = 0$

If only examine $\omega > 0 \rightarrow \begin{cases} 20 \log |\hat{H}(j\omega)| = 20 \log \left| \frac{1}{j\omega} \right| = -20 \log \omega \\ \text{Phase}(\hat{H}(j\omega)) = \text{Phase}(-j) = -\frac{\pi}{2} \end{cases}$

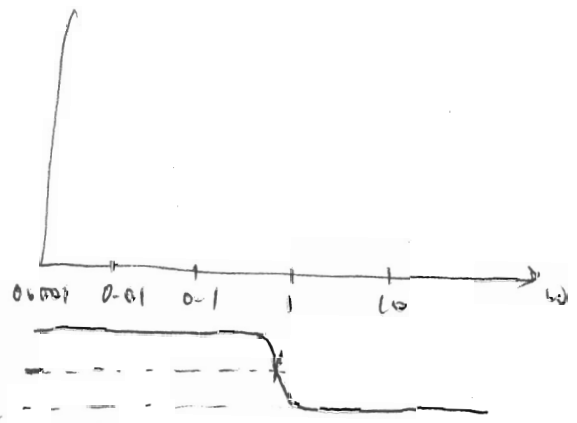
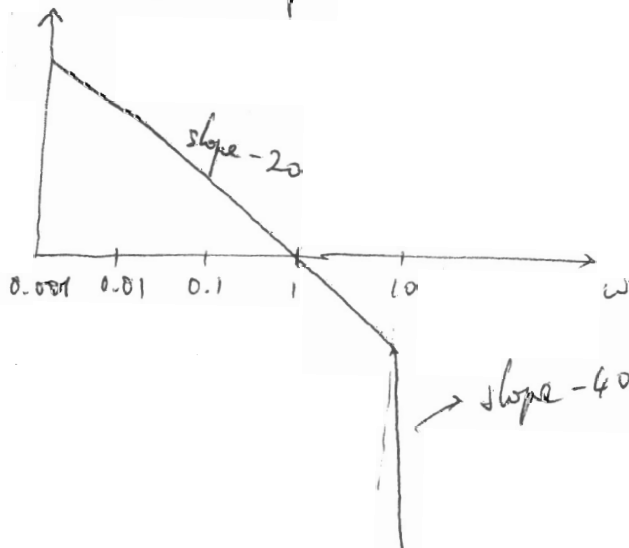
Bode Plots

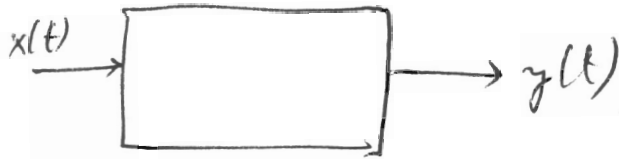


(a)

$\hat{H}(j\omega) = \frac{1}{j\omega(1 + j\frac{\omega}{10})} + \pi \delta(\omega)$ (Electric motor)

Bode Plots for $\omega > 0.001$





$$F \left\{ \frac{dy}{dt} + 2y = x(t) \right\} \rightarrow j\omega \hat{Y} + 2\hat{Y} = \hat{X}$$

$$a) \quad \hat{H}(j\omega) = \frac{\hat{Y}(j\omega)}{\hat{X}(j\omega)} = \frac{1}{2+j\omega}$$

Bode plot:

$$\hat{H} = \frac{1/2}{1+j\frac{\omega}{2}}$$

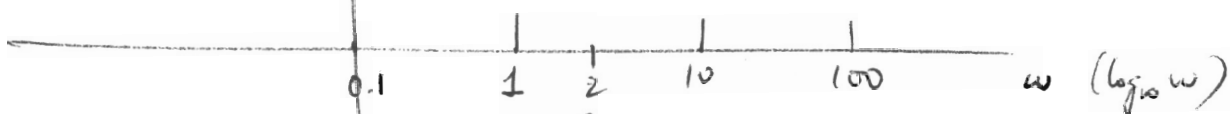
$$20 \log_{10} |\hat{H}| = \underbrace{20 \log_{10} 0.5} - \underbrace{20 \log_{10} |1+j\frac{\omega}{2}|}$$

small $\omega \rightarrow 0$

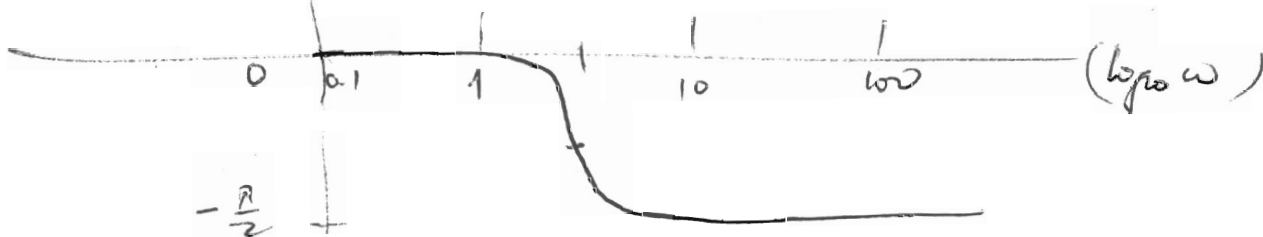
high $\omega \rightarrow 20 \log_{10} \omega + 20 \log_{10} 0.5$

critical $\omega \rightarrow 20 \log_{10} \sqrt{2} \approx -0.3 \text{ dB}$

Magnitude



Phase



c) if $x(t) = e^{-t} u(t) \rightarrow \hat{Y}(j\omega)?$

$$\downarrow$$

$$\hat{X}(j\omega) = \frac{1}{1+j\omega} \rightarrow \hat{Y}(j\omega) = \hat{X}(j\omega) \hat{H}(j\omega)$$

$$= \frac{1}{1+j\omega} \cdot \frac{1/2}{1+j\frac{\omega}{2}}$$

d) $y(t) = F^{-1} \left[\frac{a}{1+j\omega} + \frac{b}{1+j\frac{\omega}{2}} \right]$

$$a + j\frac{\omega}{2}a + b + j\omega b = \frac{1}{2} \left\{ \begin{array}{l} a+b = \frac{1}{2} \\ \frac{a}{2} + b = 0 \end{array} \right.$$

$$\frac{a}{2} = \frac{1}{2} \Rightarrow \boxed{a=1}$$

$$\boxed{b = -\frac{1}{2}}$$

$$y(t) = F^{-1} \left[\frac{1}{1+j\omega} \right] + \underbrace{F^{-1} \left[\frac{-\frac{1}{2}}{1+j\frac{\omega}{2}} \right]}_{F^{-1} \left[\frac{-1}{2+j\omega} \right]}$$

$$= e^{-t} u(t) - e^{-2t} u(t)$$

Ch 7 Sampling

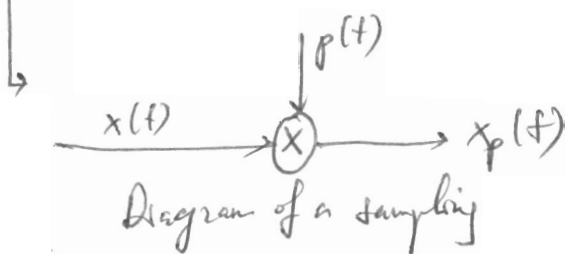
HW7: 7.7; 7.9; 7.15; 7.24; 7.30; 7.31; 7.40; 7.45;
7.49; 7.50

Why sampling? → for signal processing using a computer
→ @ at adequate rate (or frequency) to retain important information in signal but not to overload the computer

Sampled signal:

$$x_p(t) = \underbrace{x(t)}_{\text{original signal}} \cdot \underbrace{p(t)}_{\text{pulse (sampling)}}$$

→ obtained by multiplying the original signal by sampling pulse



$$p(t) = \sum_{n=-\infty}^{\infty} \delta(t - nT)$$

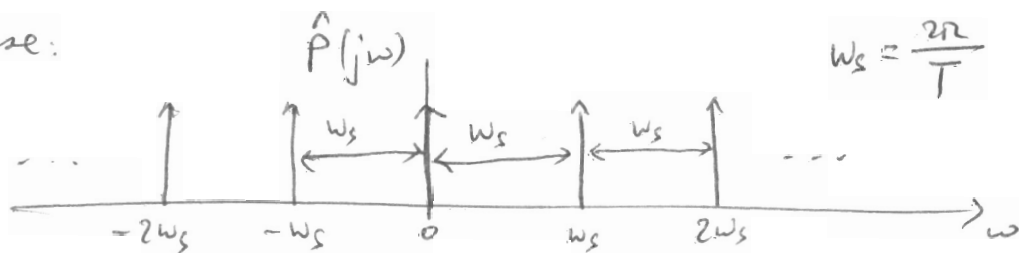
Example: what is the spectrum of a sampled signal $x_p(t)$?

$$F \{ x_p(t) = x(t) \cdot p(t) \}$$

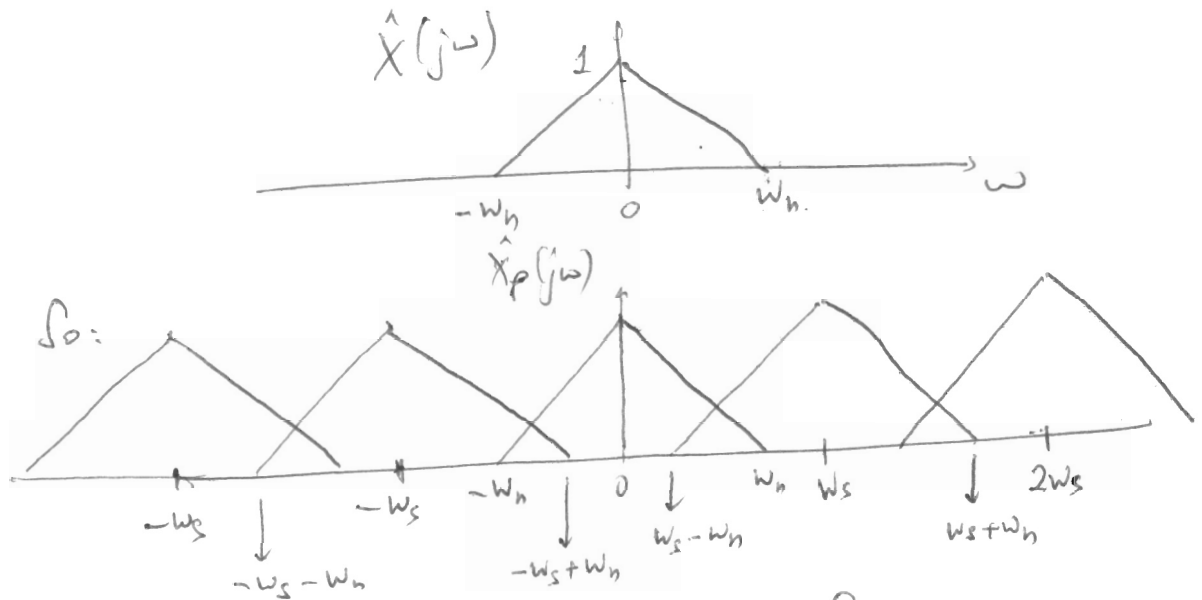
$$\hat{X}_p = \frac{1}{T} \hat{X} * \hat{P}$$

↑
convolution.

In our case:



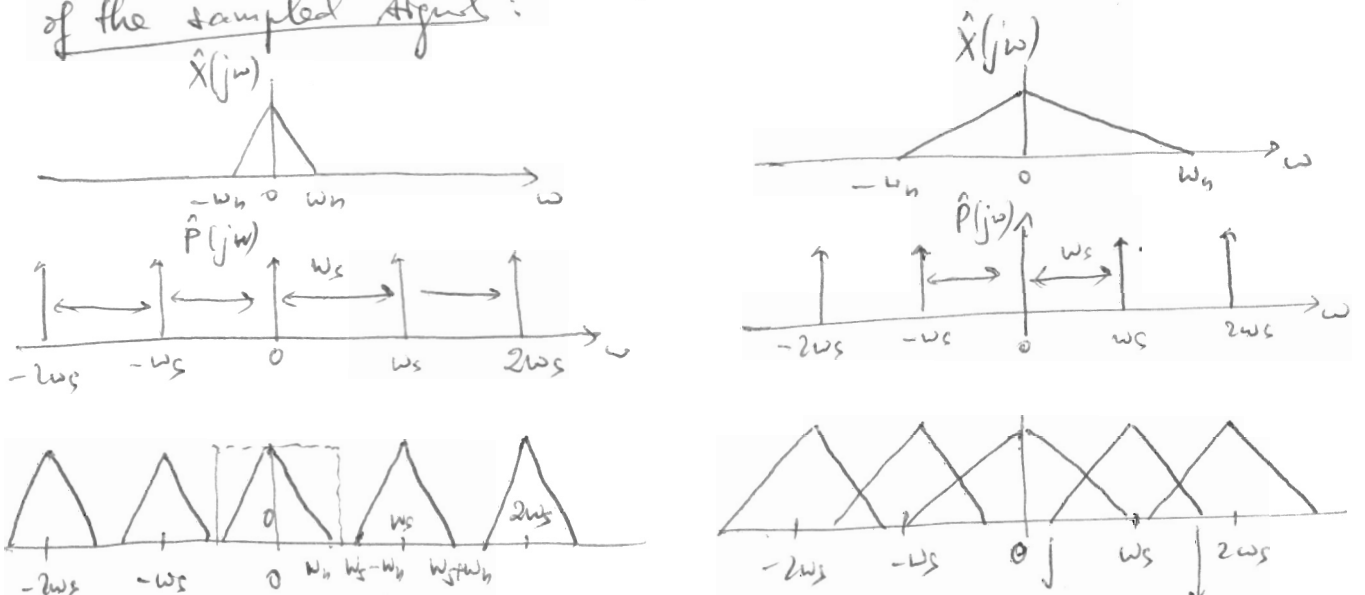
Assume $x(t)$ is such that $\hat{x}$ is a triangular pulse:



The spectrum of the our sampled signal consists of a series of triangular pulses centered @ multiples of ω_s with a half base of ω_h

Essential part of signal processing: signal reconstruction;
reconstruct the original signal from the sampled signal.

For a complete reconstruction: we need to be able to isolate the spectrum of the original signal from among the spectrum of the sampled signal:



can reconstruct original signal cannot reconstruct original signal

Nyquist Theorem: for complete reconstruction of original signal from a sampled signal (no loss of information): the sampling frequency w_s has to be equal or greater than 2 times the max. frequency w_m in the signal.

$$w_s \geq 2w_m$$

Interpolation methods:

a) "Zero-order hold" : hold value until next sample

