

Trick: factor something out so the fraction carries exponentials with same exponent but opposite signs:

$$1 - e^{j\beta} = e^{j\frac{\beta}{2}} \left(e^{j\frac{\beta}{2}} - e^{-j\frac{\beta}{2}} \right)$$

$$= 2j \sin\left(\frac{\beta}{2}\right)$$

$$\Rightarrow a_k = \frac{1}{N} \cdot \frac{j \frac{k 2\pi N_1}{N}}{e^{-j \frac{k 2\pi}{N} (N_1 + \frac{1}{2})}} \cdot \frac{\left(e^{j \frac{k 2\pi}{N} (N_1 + \frac{1}{2})} - e^{-j \frac{k 2\pi}{N} (N_1 + \frac{1}{2})} \right)}{e^{-j \frac{k 2\pi}{2N}}} \cdot \left(e^{j \frac{k 2\pi}{2N}} - e^{-j \frac{k 2\pi}{2N}} \right)$$

$$= 1$$

$$= \frac{1}{N} \cdot \frac{2j \sin \frac{k 2\pi}{N} (N_1 + \frac{1}{2})}{2j \sin \frac{k 2\pi}{2N}}$$

$$\sin(m\pi) = 0 \longrightarrow$$

good for?

$k \neq 0, 2N, 4N, \dots$

(any k different than 0 and multiple of $2N$)

For $k=0$, and multiple of $2N$:

$$a_k = \frac{1}{N} \sum_{n=-N_1}^{N_1} \underbrace{x[n]}_{1} \cdot \underbrace{e^{-j \frac{k 2\pi}{N} n}}_1 = \frac{1}{N} \sum_{n=-N_1}^{N_1} 1 = \frac{1}{N} (2N_1 + 1)$$

$$k=0 : e^0 = 1$$

$$k=2N : e^{-j 4\pi n} =$$

$$1+2+3+\dots+n = \text{arithmetic sum}$$

$$1+n+n^2+\dots+n^x = \text{geometric sum}$$

$$1+1+1+\dots=1 = \text{constant series sum}$$

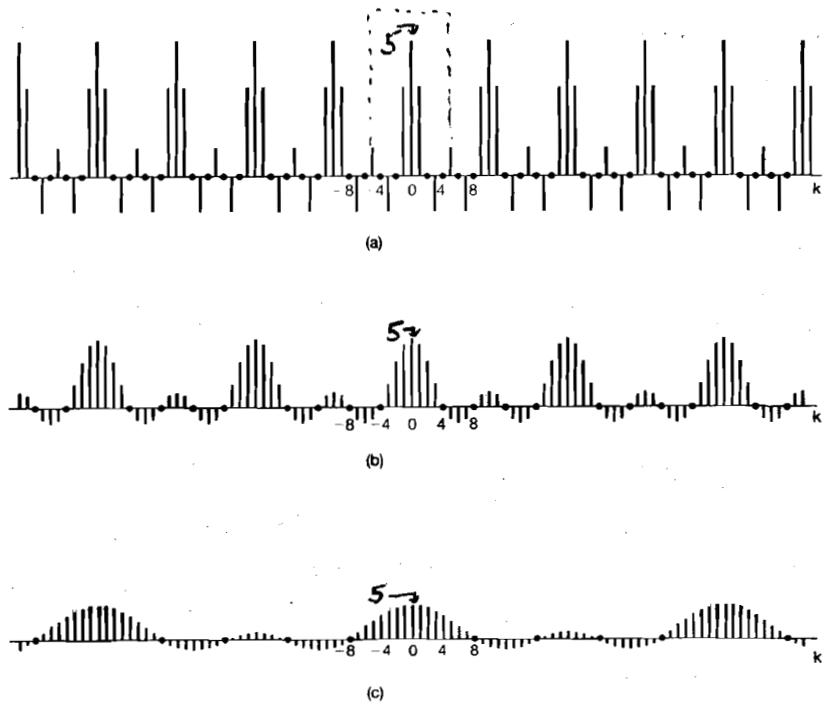


Figure 3.17 Fourier series coefficients for the periodic square wave of Example 3.12; plots of $|N a_k|$ for $2N_1 + 1 = 5$ and (a) $N = 10$; (b) $N = 20$; and (c) $N = 40$.

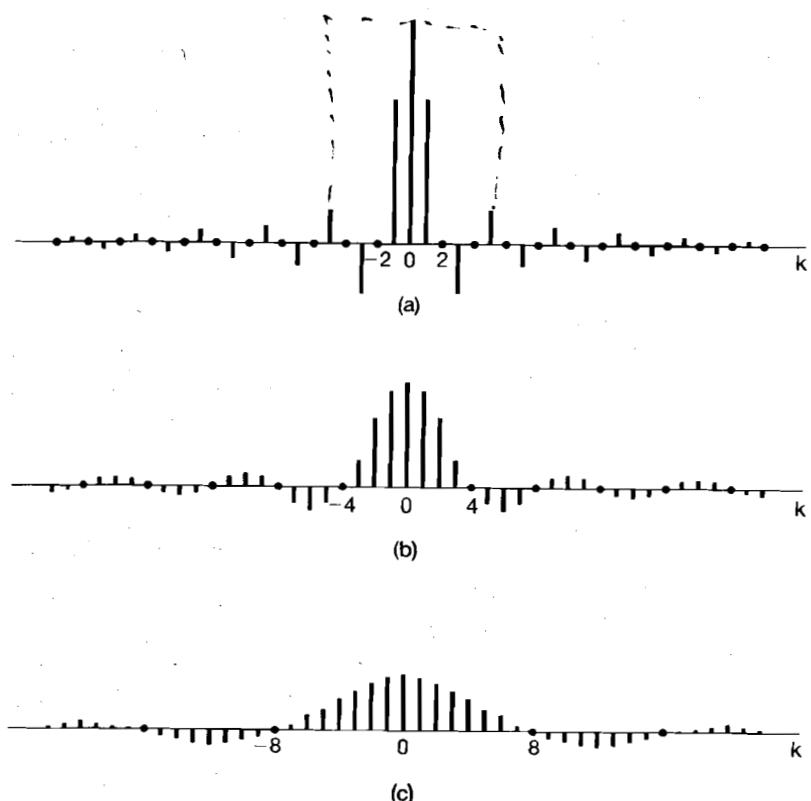


Figure 3.7 Plots of the scaled Fourier series coefficients $T a_k$ for the periodic square wave with T_1 fixed and for several values of T : (a) $T = 4T_1$; (b) $T = 8T_1$; (c) $T = 16T_1$. The coefficients are regularly spaced samples of the envelope $(2 \sin \omega T_1)/\omega$, where the spacing between samples, $2\pi/T$, decreases as T increases.

3.12

 $x_1[n]$ & $x_2[n]$ both with period $N=4$ \downarrow a_k \downarrow b_k

are Fourier series coefficients.

$$a_0 = a_3 = 1 ; a_1 = a_2 = 2$$

$$b_k = 1 , k = 0, 1, 2, 3$$

Multiplication property in Table 3.1

find $[c_k]$ for $x_1[n]x_2[n]$

continuous time: $x(t)y(t) \rightarrow \sum_{l=-\infty}^{\infty} a_l b_{k-l}$

discrete time: $x_1[n]x_2[n] \rightarrow \sum_{l=\langle N \rangle}^{\infty} a_l b_{k-l} = a_0 b_k + a_1 b_{k-1} + a_2 b_{k-2} + a_3 b_{k-3}$

(Period of $x_1[n]x_2[n]$ is N)

True or false

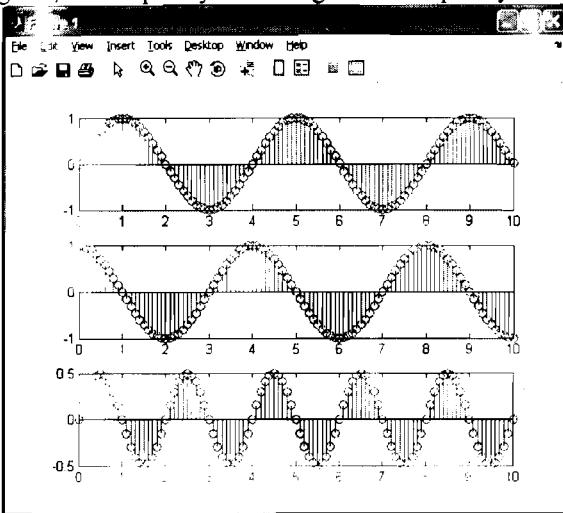
↳ see attached Matlab's plot

$$= b_k + 2(b_{k-1} + b_{k-2}) + b_{k-3}$$

$$C_k \left\{ \begin{array}{l} C_0 = b_0 + 2(b_{-1} + b_{-2}) + b_{-3} = 1 + 2(1 + 1) + 1 = 6 \\ C_1 = b_1 + 2(b_0 + b_{-1}) + b_{-2} = 6 \\ C_2 = \\ C_3 = \end{array} \right. \quad \left. \begin{array}{l} b_{-1} = b_3 \\ b_{-2} = b_2 \\ b_{-3} = b_0 \end{array} \right.$$

↳ $C_k = 6 \quad \forall k.$

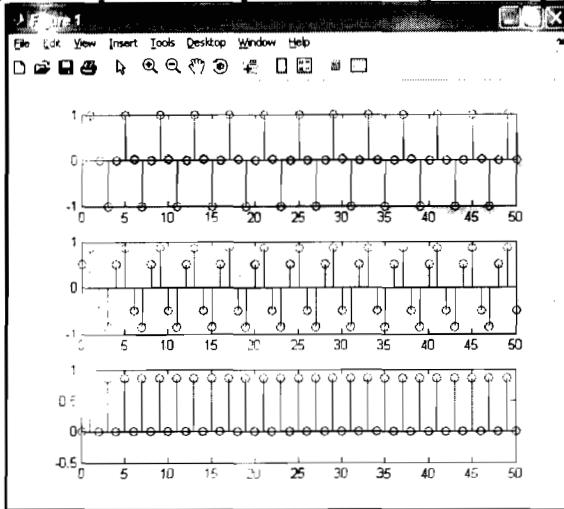
For continuous times signals, the frequency of two signals of frequency f is 2f or the period is halved



%is product of two discrete-time signals with periods of 4 also periodic
%with the same period?

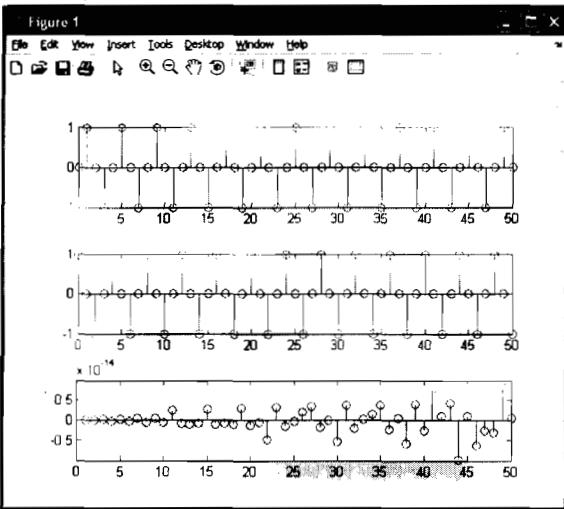
```
period=4;  
freq=1/period;  
t=0:.1:10; %Increment of less than 1 to represent continuous-time signals  
x1=sin(2*pi*freq*t);  
x2=cos(2*pi*freq*t);  
%x2=sin(2*pi*freq*t+30/180*pi);  
figure(1), subplot(3,1,1), stem(t,x1)  
figure(1), subplot(3,1,2), stem(t,x2)  
figure(1), subplot(3,1,3), stem(t,x1.*x2)  
figure(2), stem(t,x1.*x2)
```

For discrete-time signals, the period of the product of two signals with period 4 is not always 2



%is product of two discrete-time signals with periods of 4 also periodic
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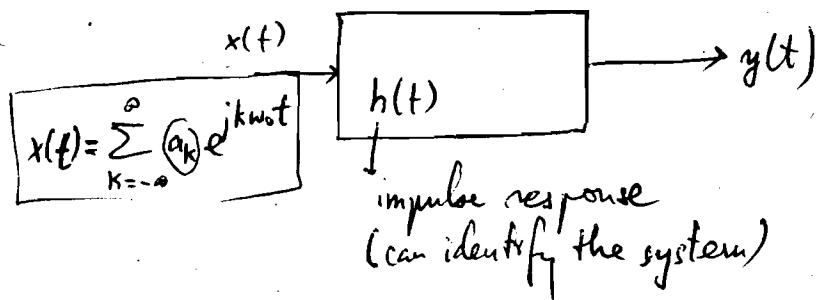
```
period=4;  
freq=1/period;  
t=0:1:50; %increment of 1 to represent discrete-time signals  
x1=sin(2*pi*freq*t);  
%x2=cos(2*pi*freq*t);  
x2=sin(2*pi*freq*t+30/180*pi);  
figure(1), subplot(3,1,1), stem(t,x1)  
figure(1), subplot(3,1,2), stem(t,x2)  
figure(1), subplot(3,1,3), stem(t,x1.*x2)  
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figure(2), stem(t,x1.*x2)
```

Fourier Series & Linear Systems:



if we know the Fourier series coefficients for $x(t) \rightarrow a_k$, what are the corresponding coefficients for $y(t)$?

If $y(t) = \sum_{k=-\infty}^{\infty} b_k e^{jkw_0 t}$, then what are b_k 's in terms of a_k 's

- 1) Instead of inputting $x(t)$, if it's the sum of I inputs $e^{jkw_0 t_k}$ then ~~the~~ sum over k (there is a 1-to-1 representation of a signal by its Fourier series): a_k is a constant; what is the output for $e^{jkw_0 t}$?

$$e^{jkw_0 t} * h(t) = \int_{-\infty}^{\infty} dx h(x) e^{+jkw_0(t-x)}$$

definition
of convolution

$$= e^{jkw_0 t} \underbrace{\int_{-\infty}^{\infty} dx h(x) e^{-jkw_0 x}}_{\text{Fourier Transform of } h(t)}$$

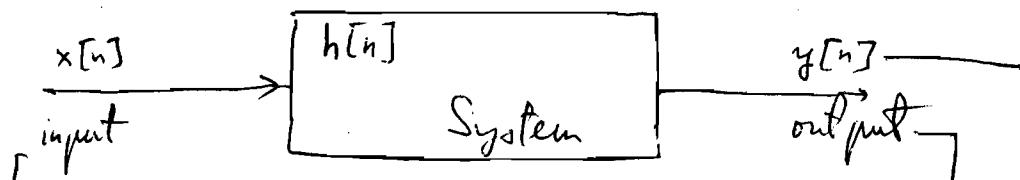
or $\hat{h}(jkw_0)$

Output for $e^{jkw_0 t}$ is $e^{jkw_0 t} \hat{h}(jkw_0) \rightarrow y(t) = \sum_{k=-\infty}^{\infty} a_k \hat{h}(jkw_0) e^{jkw_0 t}$

$\Rightarrow b_k = a_k \hat{h}(jkw_0)$

→ We proved that the F.S. coefficients for the output $y(t)$ were $b_k = a_k \hat{H}(jk\omega_0)$, where a_k were the F.S. coefficients for the input $x(t)$ and \hat{H} is the Fourier Transform of the impulse response of the system. This was for continuous-time signals.

→ For discrete-time signals :



$$x[n] = \sum_{k=-N}^N a_k e^{jk\frac{2\pi}{N}n} \quad (N: \text{period of } x[n])$$

$$y[n] = \sum_{k=-N}^N b_k e^{jk\frac{2\pi}{N}n}$$

$k = \langle N \rangle$ ← linear systems

→ It is equivalent to apply $x[n]$ or $a_k e^{jk\frac{2\pi}{N}n} \forall k$ and then sum over k . Since a_k is a constant:

$$e^{jk\frac{2\pi}{N}n} * h[n] = \sum_{m=-\infty}^{\infty} h[m] e^{jk\frac{2\pi}{N}(n-m)}$$

since this involves $h[m]$

$$= e^{jk\frac{2\pi}{N}n} \sum_{m=-\infty}^{\infty} h[m] e^{-jk\frac{2\pi}{N}m}$$

$$y[n] = \sum_{k=-N}^N a_k e^{jk\frac{2\pi}{N}n} * h[n] = \sum_{k=-N}^N a_k e^{jk\frac{2\pi}{N}n} \underbrace{\sum_{m=-\infty}^{\infty} h[m] e^{-jk\frac{2\pi}{N}m}}_{\text{Discrete-time Fourier Transform of } h[n]}$$

Linear system.

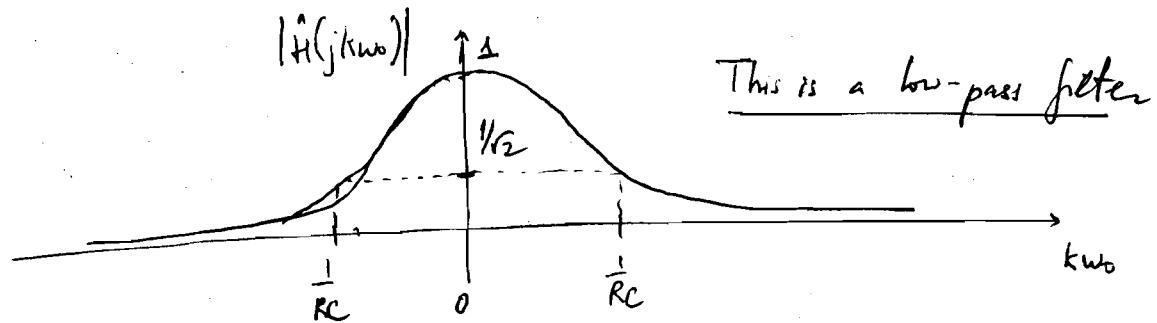
$$= \sum_{k=-N}^N a_k \hat{H}(e^{jw}) e^{jk\frac{2\pi}{N}n}$$

$\hat{H}(e^{jw})$

$$\text{or } \hat{H}(e^{jw}) \quad (\omega = \frac{2\pi}{N})$$

$$\Rightarrow b_k = a_k \hat{H}(e^{jw})$$

b_k



⇒ In general: a system governed by $\frac{dy}{dt} + ay(t) = bx(t)$ is a low-pass filter.

Discrete-time: a discrete-time low-pass filter would be represented by the discrete-time version of $\frac{dy}{dt} + ay = bx$:

Using finite-difference replacement for time derivative:

$$\frac{dy}{dt} = \lim_{\Delta \rightarrow 0} \frac{y(t) - y(t-\Delta)}{\Delta} \approx \frac{y(t) - y(t-\Delta)}{\Delta}$$

$$\text{or } \frac{y[n] - y[n-1]}{\Delta}$$

$$\frac{y[n] - y[n-1]}{\Delta} + ay[n] = bx[n]$$

$$\left(\frac{1}{\Delta} + a\right)y[n] - \frac{1}{\Delta}y[n-1] = bx[n] \quad \alpha \boxed{\frac{1}{\Delta}\left(\frac{1}{\Delta} + a\right)y[n]} - \boxed{\frac{1}{\Delta}y[n-1]} = x[n]$$

$$= x[n]$$

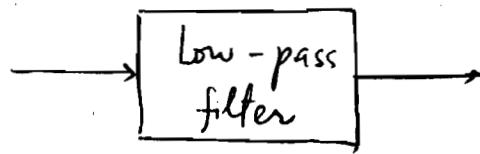
$$\Rightarrow \boxed{\beta y[n] + \alpha y[n-1] = x[n]}$$

In general represents a discrete-time low-pass filter

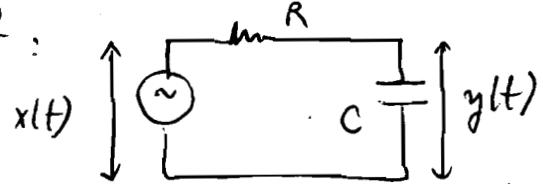
Complex numbers: $\hat{z} = a + jb \rightarrow z \equiv |\hat{z}| = \sqrt{\hat{z}\hat{z}^*} = \sqrt{(a+jb)(a-jb)} = \sqrt{a^2 + b^2}$

Linear systems : Filters.

What is a low-pass filter?



Continuous-time: e.g. RC circuit:



$$RC \frac{dy}{dt} + y(t) = x(t)$$

(input/output D.E. representing our system)

$$\text{Solution: } y(t) = \frac{1}{RC} \int_0^t d\lambda x(\lambda) e^{-\frac{1}{RC}(t-\lambda)}$$

$$= \boxed{\frac{1}{RC} \int_0^\infty d\lambda x(\lambda) e^{-\frac{1}{RC}(t-\lambda)} u(t-\lambda)} = x(t) * h(t)$$

$$= \boxed{\int_0^\infty d\lambda x(\lambda) h(t-\lambda)}$$

$$\hookrightarrow \text{Comparison: } h(t) = \boxed{\frac{1}{RC} e^{-\frac{1}{RC} t} u(t)}$$

What is the Fourier Transform of this impulse-response:

$$\hat{h}(j\omega_0) \equiv \int_0^\infty dt h(t) e^{-j\omega_0 t} = \frac{1}{RC} \int_0^\infty dt e^{-(j\omega_0 + \frac{1}{RC})t}$$

$$= \left[\frac{e^{-(j\omega_0 + \frac{1}{RC})t}}{-(j\omega_0 + \frac{1}{RC})} \right]_0^\infty = \frac{0 - 1}{-(1 + j\omega_0 RC)} = \boxed{\frac{1}{1 + j\omega_0 RC}}$$

3.28

a) Fig. P3.28 a) : Pulse width $N_1 = 4$; train of rectangular pulses of period $N = 7 \rightarrow$ find: F.S. coeffs $a_k =$

From notes: $a_k = \begin{cases} \frac{1}{N} \frac{\sin \frac{k2\pi}{N} (N_1 + \frac{1}{2})}{\sin \frac{k2\pi}{2N}} & k \neq 0, 2N, 4N, \text{etc.} \\ \frac{2N+1}{N} & k = 0, 2N, 4N, \text{etc.} \end{cases}$

$$a_k = \begin{cases} \frac{1}{7} \frac{\sin(\frac{5\pi k}{7})}{\sin(\frac{\pi k}{7})} e^{-j\frac{k2\pi}{7}2} & k \neq 0, 14, 28, \text{etc.} \\ \frac{9}{7} e^{-j\frac{k4\pi}{7}} & k = 0, 14, 28, \text{etc.} \end{cases}$$

Table 3-1 for
a time shift of 2

$\xrightarrow{x(t-t_0)}$
 $\hookrightarrow a_k e^{-j\frac{k2\pi}{N}t_0}$