

1.10

Determine fundamental period of T

$$x(t) = \underbrace{2 \cos(10t+1)}_{\#1} - \underbrace{\sin(4t-1)}_{\#2}$$

$$10T_1 = n_1 2\pi$$

$$T_1 = n_1 \frac{2\pi}{10} = \left\{ \frac{2\pi}{10}, \frac{4\pi}{10}, \frac{6\pi}{10}, \frac{8\pi}{10}, \frac{10\pi}{10}, \frac{12\pi}{10}, \dots \right\}$$

$n_1=1 \quad n_1=2 \quad \dots \quad n_1=5$

$$4T_2 = n_2 2\pi$$

$$T_2 = n_2 \frac{2\pi}{4} = n_2 \frac{\pi}{2} = \left\{ \frac{\pi}{2}, \pi, \frac{3\pi}{2}, \dots \right\}$$

$$T = \pi$$

1.11

Fundamental period N of

$$x[n] = 1 + \underbrace{e^{j\frac{4\pi n}{7}}}_{\#1 \text{ periodic}} - \underbrace{e^{j\frac{2\pi n}{5}}}_{\#2 \text{ periodic}}$$

Please check

$$N_1 = n_1 \frac{7}{2}$$

$$= \left\{ 7, 14, 21, 28, 35, 42 \right\}$$

$$N_2 = n_2 \frac{1}{5}$$

$$\left\{ \frac{1}{5}, \frac{2}{5}, \frac{3}{5}, \frac{4}{5}, \frac{5}{5}, \frac{6}{5}, \frac{7}{5}, \dots \right\}$$

$1, 2, 3, 4, 5, 6, 7$

$$N \neq 7$$

$$N = 35$$

Both signals need to come back to some value for total signal to have its first repetition (or one period)

(6)

$$x[n] = 1 + \underbrace{e^{j\frac{4\pi n}{7}}}_{\text{Period } N_1} - \underbrace{e^{j\frac{2\pi n}{5}}}_{\text{Period } N_2}$$

$$e^{j\frac{4\pi n}{7}} \cdot e^{j\frac{4\pi N_1}{7}} = e^{j\frac{4\pi n}{7}}$$

$$\Rightarrow e^{j\frac{4\pi N_1}{7}} = 1 \quad \longrightarrow \quad e^{j\frac{2\pi N_2}{5}} = 1 \quad (\text{if } N_2 \text{ is the period})$$

$$\frac{2 \cdot 4\pi N_1}{7} = n_1 2\pi$$

$$\Rightarrow N_1 = n_1 \frac{7}{2}$$

$$= \{7, 14, 21, 28, 35, 42, \dots\}$$

$$\frac{2\pi N_2}{5} = n_2 2\pi$$

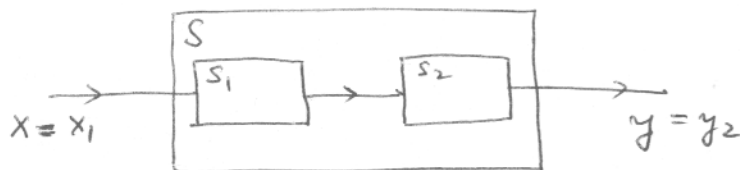
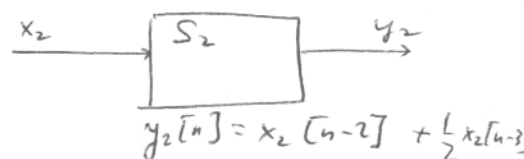
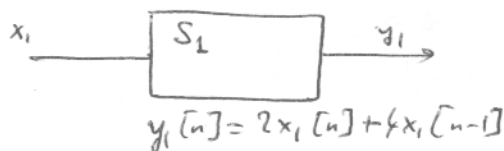
$$N_2 = n_2 5 = \{5, 10, 15, 20, 25, 30, 35, 40, 45, \dots\}$$

$$e^{j\alpha} = \cos \alpha + j \sin \alpha$$

$$\text{if } \alpha = n 2\pi \rightarrow \begin{cases} \cos \alpha = 1 \\ \sin \alpha = 0 \end{cases}$$

$$\rightarrow e^{j 2\pi n} = 1$$

1.15



We are asked for an equation relating y to x : $y[n] = \dots$

Output of S_1 is input of S_2 : $x_2[n] = y_1[n]$

$$y[n] = y_2[n] = \underbrace{y_1[n-2]}_{\uparrow} + \frac{1}{2} \underbrace{y_1[n-3]}_{\uparrow} = 2x_1[n-2] + 4x_1[n-3] + \frac{1}{2} 2x_1[n-3] + \frac{1}{2} 4x_1[n-4]$$

$$\Rightarrow y[n] = 2x[n-2] + 5x[n-3] + 2x[n-4]$$

1-16

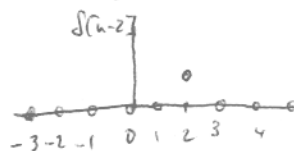
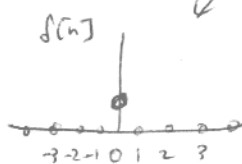
$$y[n] = x[n]x[n-2]$$



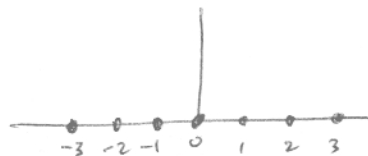
- a) Memoryless? b) Find output y when input $x[n] = A\delta[n]$
- c) Is the system invertible?

a) No, $y[n]$ depends on $x[n-2]$ (past input)

$$b) y[n] = \underbrace{A\delta[n]}_{x[n]} \cdot \underbrace{A\delta[n-2]}_{x[n-2]} = A^2 \delta[n]\delta[n-2] = 0$$



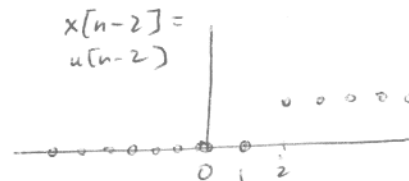
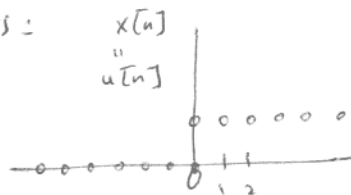
Product: $\delta[n]\delta[n-2]$



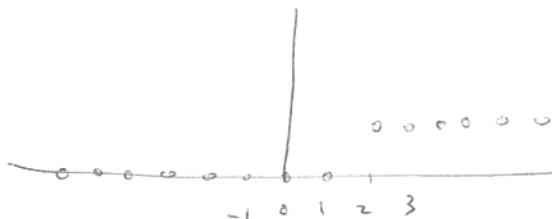
- c) What is the inverse system S^{-1} : input/output equation?

No.

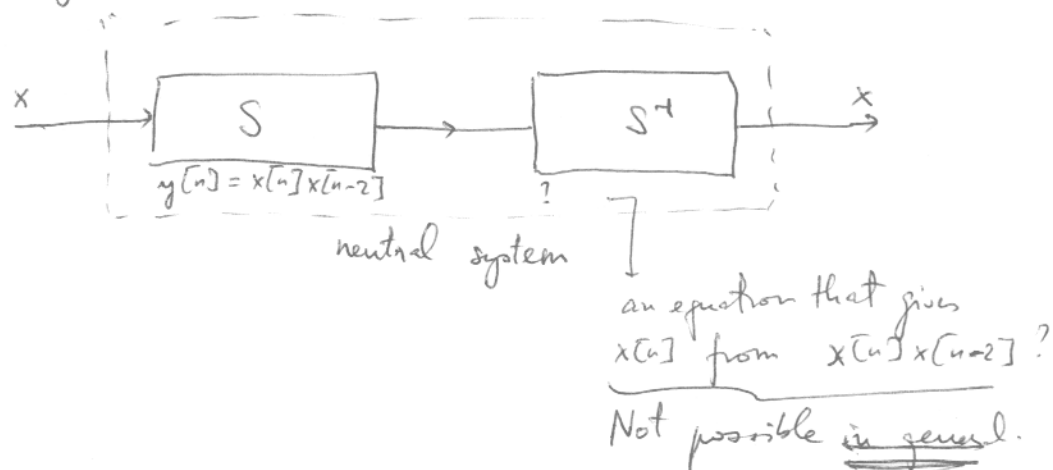
For other inputs:



Product: $u[n] \cdot u[n-2]$



inverse system S^{-1} :



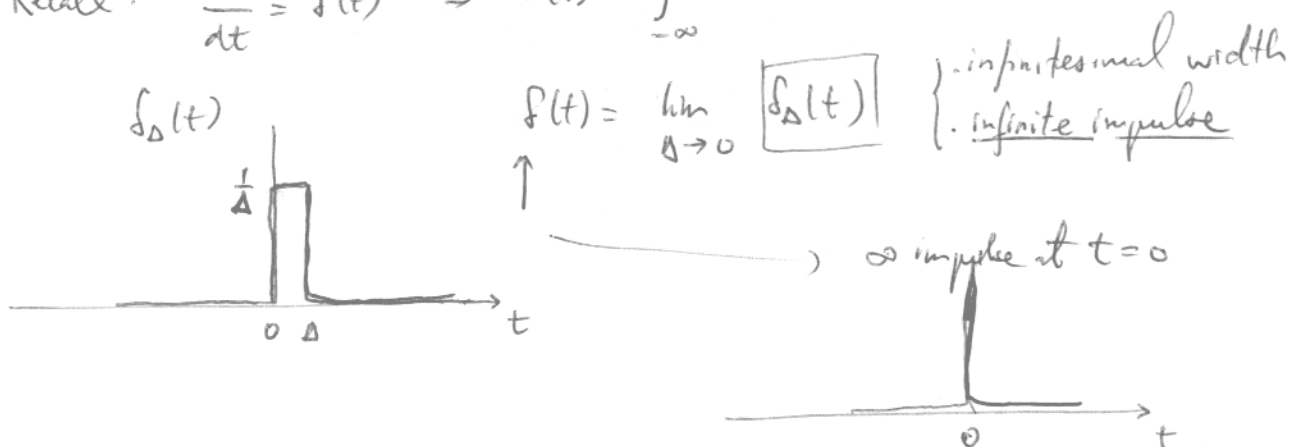
→ No S^{-1}

1.39

step function $u(t)$, impulse function $\delta(t)$

1.38 $\hookrightarrow u_{\Delta}(t) = \int_{-\infty}^t \delta_{\Delta}(\tau) d\tau$; $u(t) = \lim_{\Delta \rightarrow 0} u_{\Delta}(t)$

Recall: $\frac{du}{dt} = \delta(t) \rightarrow u(t) = \int_{-\infty}^t \delta(\tau) d\tau$



Prove:

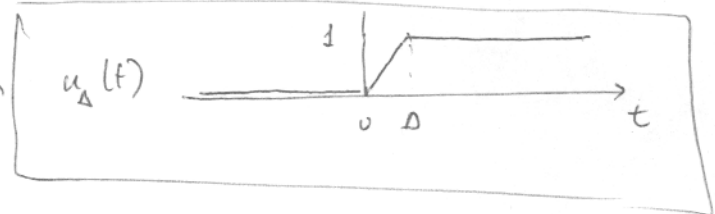
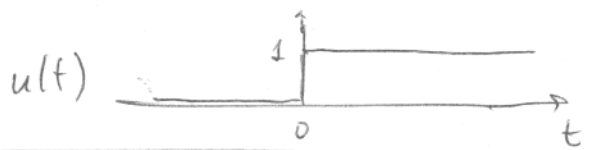
$\lim_{\Delta \rightarrow 0} [u_{\Delta}(t) \delta(t)] = 0 \checkmark \parallel \lim_{\Delta \rightarrow 0} [u_{\Delta}(t) \delta_{\Delta}(t)] = \frac{1}{2} \delta(t)$

$\lim_{\Delta \rightarrow 0} \left[\delta(t) \int_{-\infty}^t \delta_{\Delta}(\tau) d\tau \right]$

$\left\{ \begin{array}{l} t=0 \rightarrow \delta(t) \times 0 \rightarrow 0 \\ t < 0 \rightarrow 0 \times 0 \rightarrow 0 \\ t > 0 \rightarrow \delta(t) \times 1 \rightarrow 0 \end{array} \right.$

$$\lim_{\Delta \rightarrow 0} [u_{\Delta}(t) \delta_{\Delta}(t)] = \lim_{\Delta \rightarrow 0} \left[\frac{1}{\Delta} \text{rect}_{[0, \Delta]}(t) \times \int_{-\infty}^t \delta_{\Delta}(\tau) d\tau \right]$$

}



$$\lim_{\Delta \rightarrow 0} [u_{\Delta}(t) \delta_{\Delta}(t)] = \lim_{\Delta \rightarrow 0} \left[\text{graph of } u_{\Delta}(t) \times \text{graph of } \delta_{\Delta}(t) \right]$$

→ Recall:

$$\lim_{\Delta \rightarrow 0} \left[\frac{1}{\Delta} \text{rect}_{[0, \Delta]}(t) \right] = \delta(t)$$

So $\left(\frac{1}{2} \delta(t) \right)$ → half area. vs

1.27) a) $y(t) = x(t-2) + x(2-t)$

1) Memoryless : Not. b/c current output depends on previous inputs.

2) Time-inv. : Yes : if time is shifted $\rightarrow$ system still works.

3) Linear : Yes : $ax \rightarrow \boxed{S} \rightarrow ay$

4) Causal : No : current output depends on future inputs.

5) Stable : Yes.

$$\left. \begin{array}{l} \rightarrow t \rightarrow t+a \end{array} \right\} \begin{array}{l} \text{inputs: } x(t) \rightarrow x(t+a) \\ x(t+a-2) + x(2-a-t) = y(t+a) \\ \text{output: } y(t+a) \end{array}$$

f) $y(t) = x\left(\frac{t}{3}\right)$

1) Memoryless ? Not ($y(t) = 2x(t)$ = memoryless)

2) Time inv. ? No : $t \rightarrow t+a \left\{ \begin{array}{l} \text{input: } t \rightarrow \frac{t+a}{3} \\ \text{output: } t \rightarrow t+a \end{array} \right.$

$t = 30s$: output at 30s is input at 10s

+60s $\uparrow$ 20s not 60s

$t = 30+60s$: output at 90s is input at 30s.

Shift of 60s for outputs corresponds to a shift of only 20s for input. $\rightarrow$ No time-inv.

3) Linear, Yes.

4) Causal Yes

5) Stable Yes.