

Ch 27 Electromagnetic Induction

Faraday's Law: $-\frac{d\Phi_B}{dt} = \mathcal{E}$ (induced voltage)

Magnetic flux: through a ~~the~~ surface $\Phi_B = \int \vec{B} \cdot d\vec{A}$

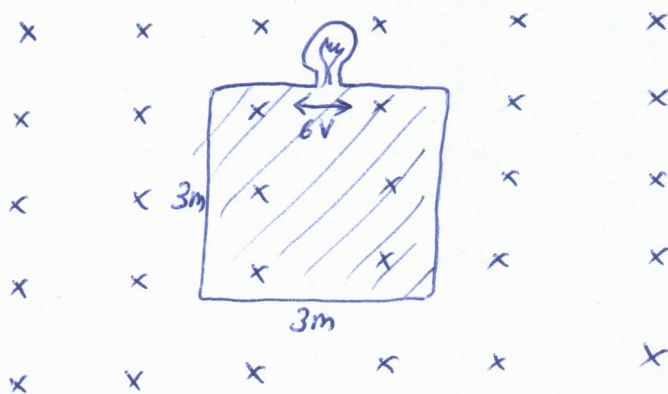
↳ any magnetic flux which varies over time creates an induced voltage

↳ Conservation of energy (Lenz's Law)

27.37

Region of uniform magnetic field \vec{B} into the page:

$B = 2T$
into page.
(reduces steadily
to 0T over time
 Δt)



Surface enclosed by loop is $9m^2$ constant over time, since B decreases over time $\rightarrow \Phi_B$ varies over time \rightarrow induced voltage \mathcal{E} in loop which turns on light bulb.

a) Find Δt so lightbulb will reach full brightness ($\mathcal{E} \rightarrow 6V$)

$$\text{Faraday's Law: } \mathcal{E} = - \underbrace{\frac{d\Phi_B}{dt}}_{\text{instantaneous}} = - \underbrace{\frac{\Delta\Phi_B}{\Delta t}}_{\text{average}} = - \frac{\Delta B \cdot A}{\Delta t} = - \frac{(0-2) \cdot 9}{\Delta t}$$

$$6 = \frac{18}{\Delta t} \rightarrow \Delta t = 3s : \text{ In } 3s \mathcal{E} \rightarrow 6V \text{ \& light bulb reaches full brightness!}$$

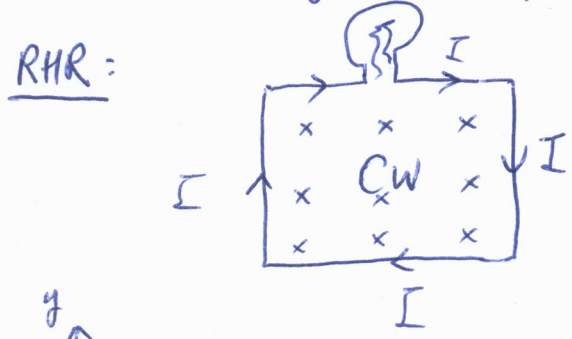
$$\boxed{\mathcal{E} = \frac{18}{\Delta t}}$$

b) Which way will loop current flow?

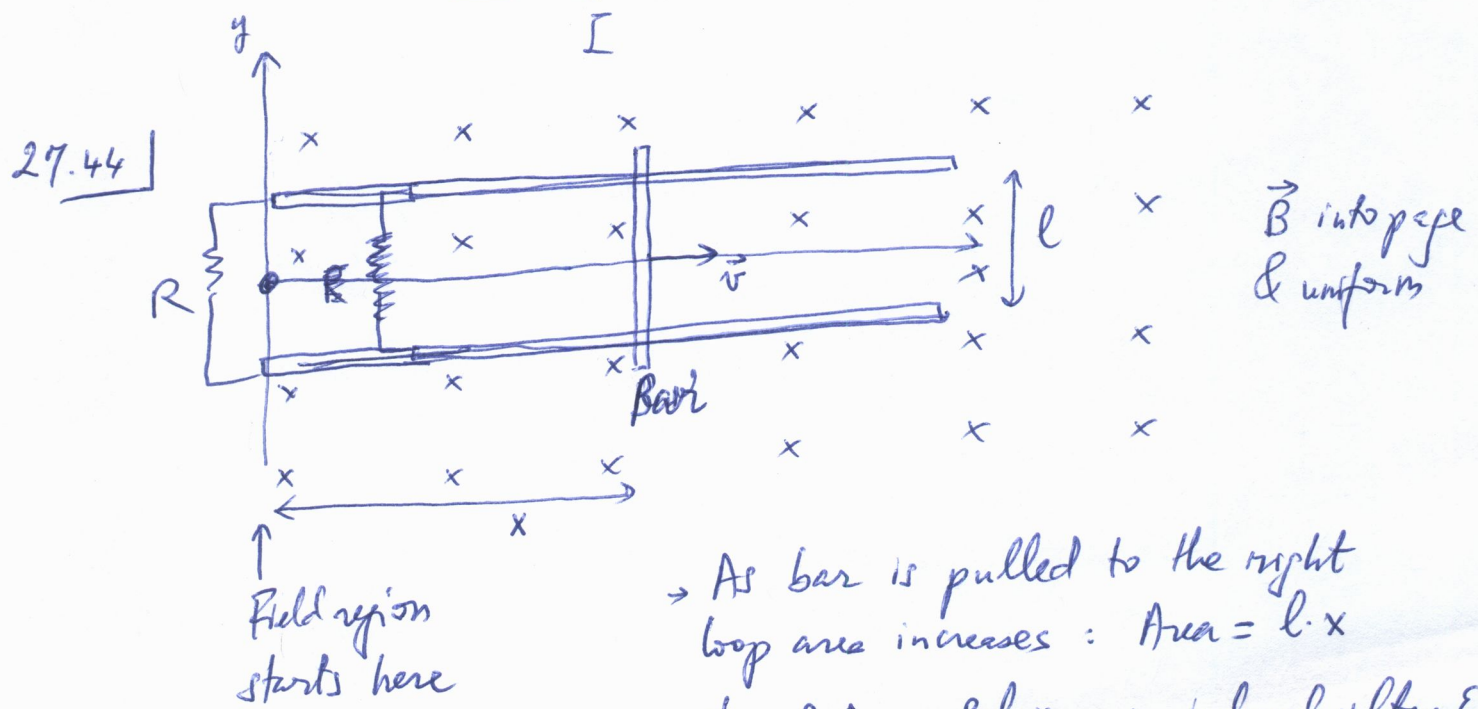
(i) Induced current flows in such a way to oppose the change in magnetic flux through the loop: due to the \ominus sign in Faraday's Law: $\mathcal{E} = \ominus \frac{d\Phi_B}{dt}$

(ii) What is the change in Φ_B ? Since B into page decreases over time, and $A = \text{constant} \rightarrow \Phi_B$ into page decreases.

\rightarrow Induced current will flow in such a way to create a magnetic field also into page to compensate for the reduction.



Current will flow in CW around loop!



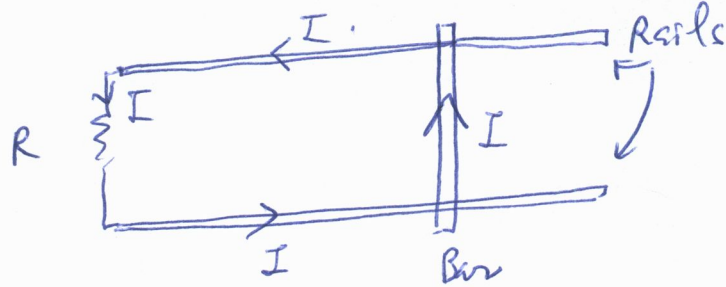
\rightarrow As bar is pulled to the right loop area increases: $\text{Area} = l \cdot x$
 $\Phi_B = B \cdot A = B \cdot l \cdot x \rightarrow$ induced voltage \mathcal{E}

Faraday's Law: $\mathcal{E} = \ominus \frac{d\Phi_B}{dt} = -B \cdot l \cdot \frac{dx}{dt} = -Blv$

a) Direction of induced current? It will flow in such a way to oppose the increase of Φ_B into page (as A increases with bar moving to the right)

That means induced current flows in a way to create a magnetic field out of page. (91)

RHR : current CCW to create magnetic field out of page



Current goes down @ R!

b) Rate of work (power) applied to move bar?

$$P = \frac{W}{t} = \frac{F_B \cdot x}{t} = F_B \cdot v = IlBv = \frac{\mathcal{E}}{R} lBv$$

Lorentz's force: $F_B = qvB$

$$= \left(\frac{q}{t} \right) l B = IlB$$

$$\mathcal{E} = -Blv$$

$$\rightarrow P = \ominus \frac{(Blv)^2}{R}$$

Bar does negative work

or it receives work (we need to apply work on bar to move it)

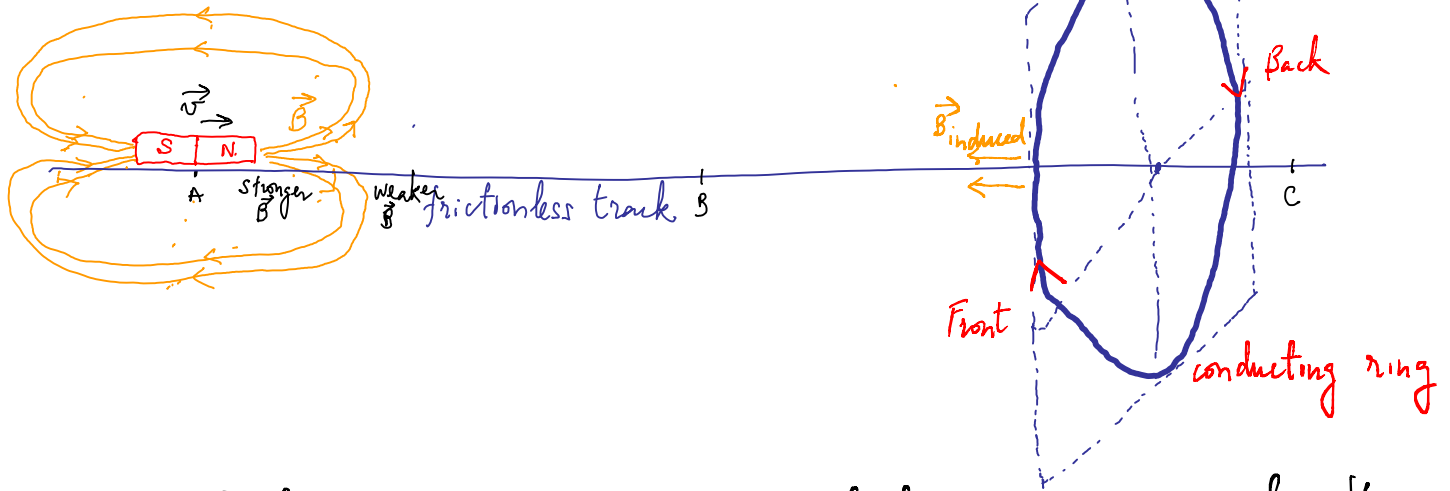
Alternative : $P = I \cdot V = \frac{\mathcal{E}^2}{R} = \frac{(Blv)^2}{R}$

$$\frac{\mathcal{E}}{R} \cdot \mathcal{E}$$

Ch.27(cont.): EM Induction & Conservation of Energy :

↳ Visual experiment: sliding magnet & conducting ring

↳ Can hold an induced current when there is an induced voltage.



1) As magnet slides from A to B @ constant speed v : magnetic flux Φ_B through the cross-sectional area enclosed by conducting ring increases over time. $\rightarrow \frac{d\Phi_B}{dt} \neq 0$: Faraday's Law of Induction this induces a voltage $\mathcal{E} = - \frac{d\Phi_B}{dt}$ in the conducting ring

↳ Lenz's Law: the induced voltage \mathcal{E} opposes the change in Φ_B : the induced current goes up in the front & down in the back to create a magnetic field in the opposite direction (so a magnetic flux in that direction) to counter the increase of the original Φ_B by the sliding magnet.

2) After the magnet is given a push, it slides from A to B @ speed v . As it approaches the ring the speed will decrease as some of its KE is transferred to the induced current in the ring. (A conducting ring has some electrical resistance, small but it's there)

3) When magnet passes the ring toward C: Φ_B by magnet is now decreasing, the induced current in the ring decreases to 0 then reverses direction to create a counter magnetic field pointing to the right (same direction

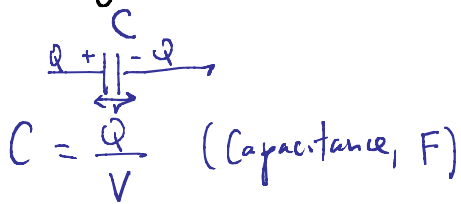
as original field by magnet) to compensate for the reductions in Φ_B . ⁽⁹³⁾
 (Induced \mathcal{E} and I always opposes changes in $\Phi_B \leftrightarrow$ minus sign in Faraday's Law)

The reversed current will disappear when $\frac{d\Phi_B}{dt}$ goes back to 0, when energy is returned to magnet which will pick up speed.

4) This electro-mechanical energy transfer is used in many technological applications: electric motor, invisible fence for supermarket cart, etc...

Inductance & Magnetic Energy

Capacitors
 (storing electric energy)



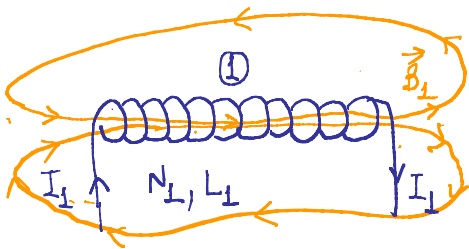
$$C = \frac{Q}{V} \quad (\text{Capacitance, F})$$

Inductors
 (storing magnetic energy)



- Self-inductance $L = \frac{\Phi}{I}$ (H) Henry
- Mutual-inductance $M = \frac{\Phi_2}{I_1}$ (H)
 (new in magnetic energy)

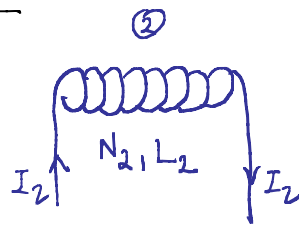
Two solenoids



$$B_1 = \mu_0 n_1 I_1$$

$$n_1 = \frac{N_1}{L_1} \quad (\# \text{ turns per unit length})$$

Also called an electromagnet
 (superconducting electromagnet to output stronger B)



$$B_2 = \mu_0 n_2 I_2$$

$$n_2 = \frac{N_2}{L_2} \quad (\# \text{ turns per unit length})$$

1) B_1 goes through cross-sectional area of solenoid 2 creating a magnetic flux

$$\Phi_2 = B_1 \cdot A_2 \cdot N_2 = \mu_0 n_1 I_1 A_2 N_2$$

So if I_1 changes over time \rightarrow so does $\Phi_2 \rightarrow$ Faraday's Law: $\mathcal{E}_2 = - \frac{d\Phi_2}{dt}$
(\mathcal{E}_2 is induced in #2 if current I_1 changes in #1 !)

$$-\mathcal{E}_2 = \frac{d\Phi_2}{dt} = \underbrace{\mu_0 n_1 N_2 A_2}_{\equiv M} \frac{dI_1}{dt}$$

$\equiv M$ (mutual inductance: relates induced voltage in #2 with a changing current in #1)

$$\Phi_2 = M I_1 \text{ or } M = \frac{\Phi_2}{I_1}$$

2) And viceversa: B_2 by solenoid #2 goes through cross-sectional area A_1 of solenoid #1 \rightarrow creates a magnetic flux through #1 or Φ_1

$$\Phi_1 = B_2 \cdot A_1 \cdot N_1 = \mu_0 n_2 I_2 A_1 N_1$$

If I_2 varies over time \rightarrow induces a voltage \mathcal{E}_1 in #1

$$-\mathcal{E}_1 = \frac{d\Phi_1}{dt} = \underbrace{\mu_0 n_2 N_1 A_1}_{\equiv M} \frac{dI_2}{dt}$$

$\equiv M$ (mutual inductance: relates induced voltage in #1 with a changing current in #2)

SI unit: $M = \frac{\text{Voltage}}{\text{Current} \cdot \text{time}} \xrightarrow{\text{units}} \frac{\text{V}}{\frac{\text{A}}{\text{s}}} = \frac{\text{V} \cdot \text{s}}{\text{A}} \equiv \text{H (Henry)}$

3) Also \vec{B}_1 goes through its own cross-sectional area A_1 (& \vec{B}_2 through A_2)

$$\Phi = B_1 \cdot A_1 \cdot N_1 = \mu_0 n_1 I_1 A_1 N_1$$

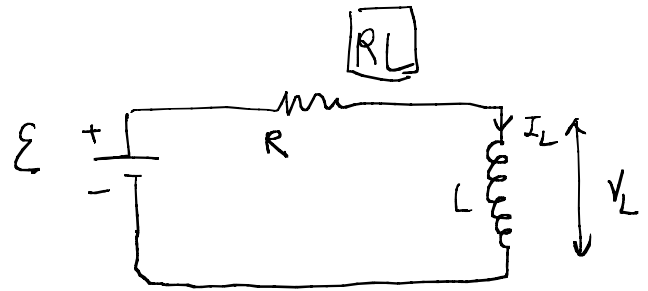
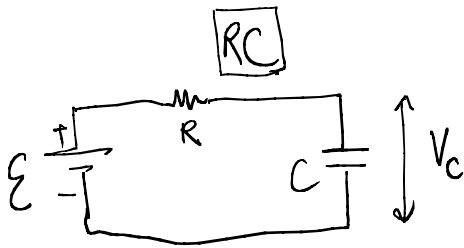
If I_1 varies over time, it will induce a voltage in the solenoid #1 (in addition to inducing an \mathcal{E}_2 in solenoid #2 !): self-induced voltage \mathcal{E}

$$-\mathcal{E} = \frac{d\Phi}{dt} = \underbrace{\mu_0 n_1 N_1 A_1}_{\equiv L} \frac{dI_1}{dt}$$

$\equiv L$ (self-inductance)

$$\Phi = L I_1 \rightarrow \boxed{L = \frac{\Phi}{I}} \text{ (SI unit: H)}$$

Electric & Magnetic Circuits



$t=0$ (switch is just closed)

C initially uncharged:
 $V_C=0 \rightarrow$ C acts like a short-circuit

L initially uncharged
 $I_L=0 \rightarrow$ L acts like an open-circuit

$t \rightarrow \infty$ (switch is closed sufficiently long)

C fully charged
 $I_C=0 \rightarrow$ C acts like an open-circuit

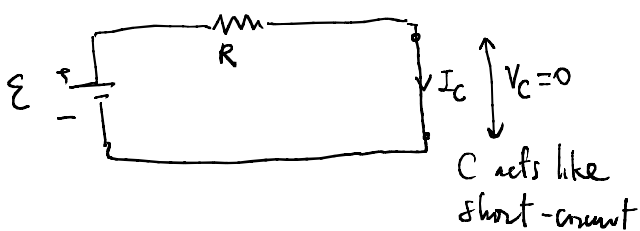
L fully charged
 $I_L = \text{max} \rightarrow V_L=0 \rightarrow$ L acts like a short-circuit

$0 < t < \infty$ (in between)

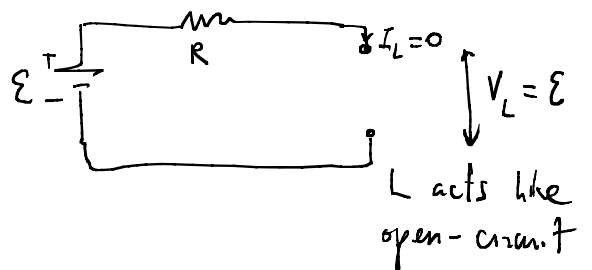
$$\begin{cases} I(t) = \frac{\epsilon}{R} e^{-\frac{t}{RC}} \\ \quad \quad \quad \underbrace{\frac{\epsilon}{R}}_{I(0)} \\ \quad \quad \quad \text{max when } t=0 \\ V_C(t) = \epsilon(1 - e^{-\frac{t}{RC}}) \\ \tau = RC \text{ time constant} \end{cases}$$

$$\begin{cases} V_L(t) = \epsilon e^{-\frac{t}{L/R}} \\ I_L(t) = \frac{\epsilon}{R} (1 - e^{-\frac{t}{L/R}}) \\ \tau = \frac{L}{R} \text{ time constant} \end{cases}$$

$t=0$



$t=0$



(i) As switch is closed: V_C which was 0 (C initially uncharged) stays at 0. Because of C, V_C doesn't change instantaneously (unlike V_R across R, which turns on instantaneously as switch is closed)

Capacitance = electric inertia to changes in voltage V_C

(i) As switch is closed, I_L which was 0, stays at 0. Because of L I_L doesn't change instantaneously (unlike current across R, which turns on instantaneously as switch is closed)

Inductance: magnetic inertia to changes in current I_L

(i) $U = \frac{1}{2} CV^2$

(ii) $U = \frac{1}{2} LI^2$

$\frac{1}{2} mv^2$

Mass m: gravitational inertia to changes in velocity v

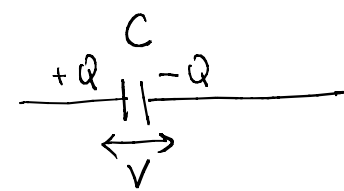
Something in common among these 3 interactions

- Grav. ↔ Newton's Univ. Gravitation law
- Electric ↔ Coulomb's Law
- Magnetic ↔ Biot-Savart's Law

↓
 $\propto \frac{1}{r^2}$
inverse square law

Magnetic Energy

Electric



$U_c = \frac{1}{2} CV^2$ (J)

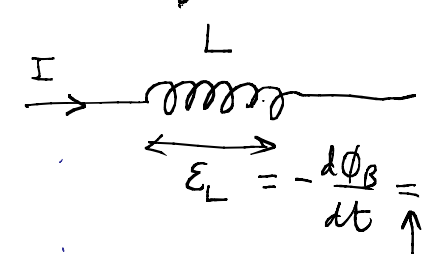
C (F)
V (V)

Electric energy density: $u_e = \frac{U_c}{vol}$

(i) vol: vol b/w parallel plates: A·d
(A cross-sectional area of plates, d: spacing b/w plates)

(ii) $C = \frac{A\epsilon_0}{d}$

Magnetic



$U_L = \int_0^t P_L dt = \int_0^t I \cdot |\epsilon_L| dt = \int_0^t I \frac{dI}{dt} dt$

energy stored per unit time

$= \frac{1}{2} L [I^2]_0^t = \frac{1}{2} LI^2$ (J)

I(0) = 0

Magnetic energy density $u_m = \frac{U_L}{vol}$

(i) vol: vol. inside solenoid: A·l
(A cross-sectional area of solenoid, l its length)

(ii) $L = \mu_0 \frac{N^2}{l} A$

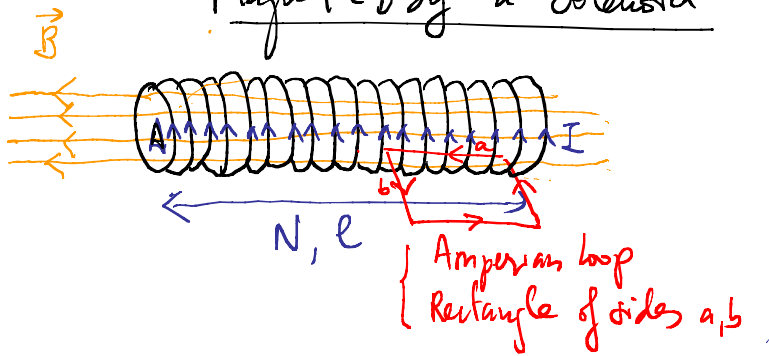
$$\rightarrow u_e = \frac{1}{2} \epsilon_0 E^2 \quad \left(\frac{\text{J}}{\text{m}^3} \right)$$

$$\rightarrow u_L = \frac{\frac{1}{2} L I^2}{A \cdot l} = \frac{\frac{1}{2} \mu_0 \frac{N^2}{l} I^2}{N \cdot l} = \frac{1}{2} \mu_0 \frac{N^2}{l^2} I^2 \quad (97)$$

$$(iii) \quad B = \mu_0 n I \\ = \mu_0 \frac{N}{l} I \quad \text{or} \quad \frac{N I}{l} = \frac{B}{\mu_0}$$

$$\rightarrow \left[u_L = \frac{1}{2} \mu_0 \frac{B^2}{\mu_0^2} = \frac{1}{2 \mu_0} B^2 \right]$$

Magnetic B by a solenoid



Ampere's Law:

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{\text{enclosed}}$$

Amperian Loop

by Amperian loop

$$B \cdot l = \mu_0 \frac{N I l}{l}$$

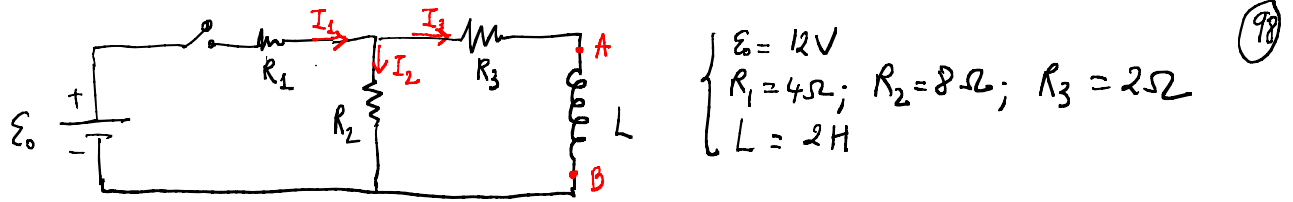
$$\left[B = \mu_0 \frac{N}{l} I = \mu_0 n I \right]$$

Self-inductance L by a solenoid:

$$\left[L = \frac{\Phi}{I} = \frac{B \cdot A \cdot N}{I} = \frac{\mu_0 n I A N}{I} = \mu_0 n N A = \mu_0 \frac{N^2}{l} A \right]$$

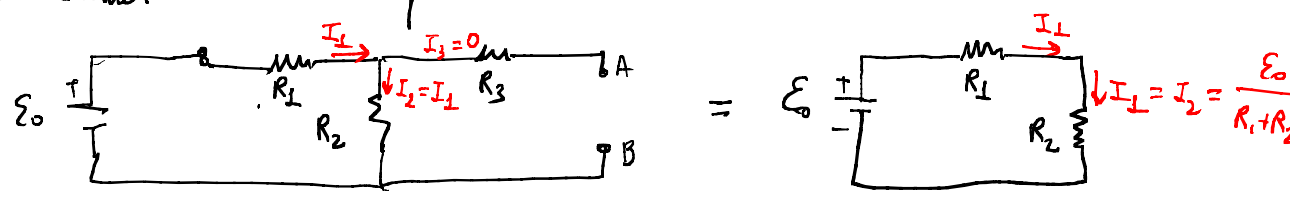
$n = \frac{N}{l}$

27.59



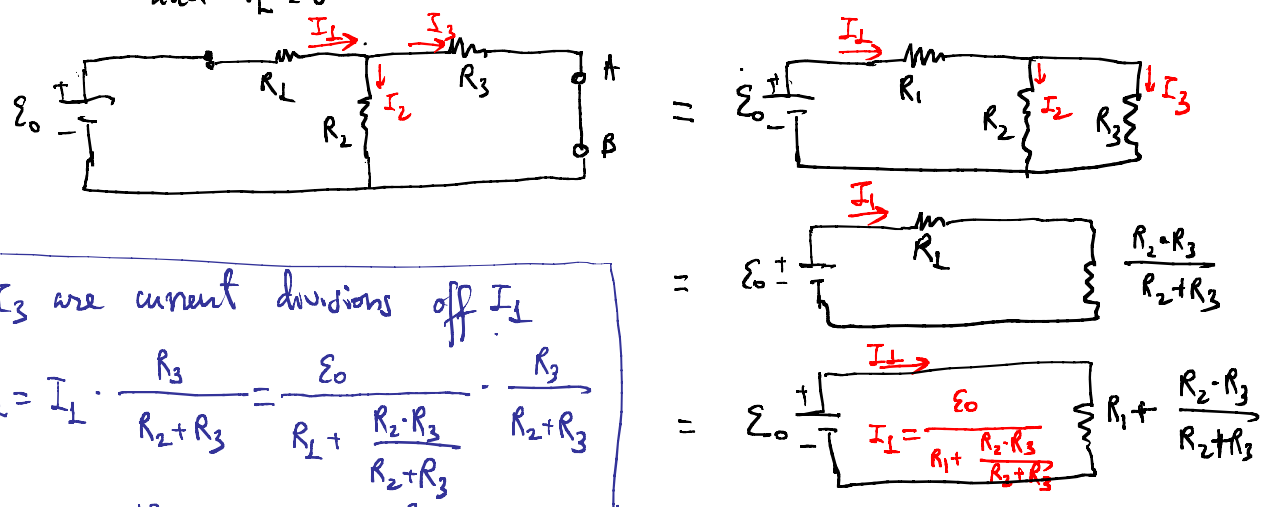
a) I_2 ? right after switch is closed is $I_1 = I_2 = \frac{\epsilon_0}{R_1 + R_2} = \frac{12}{4+8} = 1A$

Inductor L: ($U = \frac{1}{2}LI^2$: L inertia to changes in I) before switch is closed current I_3 through inductor was 0, it stays at 0 right after switch is closed. Inductor acts like open-circuit at time $t=0$.



b) I_2 ? long after switch is closed

Inductor L: $t \rightarrow \infty$ acts like short-circuit, \therefore current I_3 reaches max. value and $V_L = 0$



I_2 & I_3 are current divisions off I_1

$$I_2 = I_1 \cdot \frac{R_3}{R_2 + R_3} = \frac{\epsilon_0}{R_1 + \frac{R_2 \cdot R_3}{R_2 + R_3}} \cdot \frac{R_3}{R_2 + R_3}$$

$$I_2 = \frac{12}{4 + \frac{8 \cdot 2}{8+2}} \cdot \frac{2}{8+2}$$

$$I_2 = \frac{12}{5.6} \cdot \frac{2}{10} = 0.429A$$

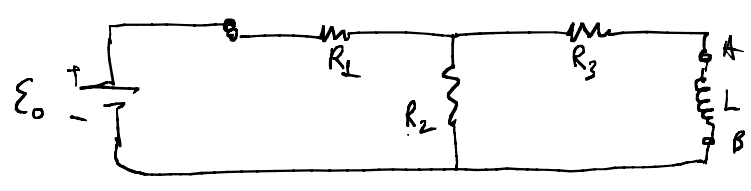
$I_1 = 2.14A$

Curiosity: current division: $I_3 = I_1 \cdot \frac{R_2}{R_2 + R_3} = 2.14 \cdot \frac{8}{8+2} = 1.71A$

check: $I_2 + I_3 = 0.429 + 1.71 = 2.14A = I_1$

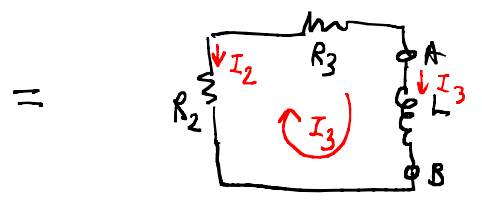
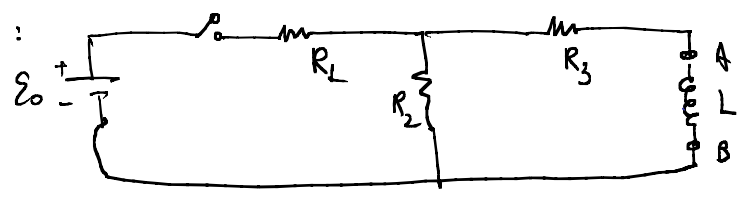
c) I_2 ? long after switch is closed it is now reopened.

L : inertia to changes in current: at $t \rightarrow \infty$ I_2 or I_3 was max., when switch is now reopened it will stay at that value using magnetic energy stored in the inductor. When U_L is depleted I_3 decreases back to 0.



$t \rightarrow \infty$ L acts like short-circuit but it is physically there.
 $I_2 = 0.429A$ (b)

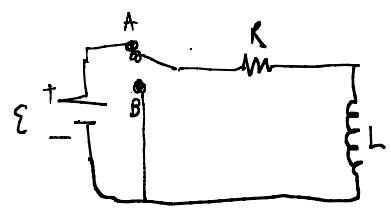
Switch is reopened:



Inductor tries to maintain current $I_3 = 1.71A$ from any sudden change $\Rightarrow I_2 = -1.71A$ until magnetic energy is depleted.

Application: this circuit is a delayed switch for R_3
 If R_3 is a light bulb it will stay on a little bit longer after switch is open.

27.66

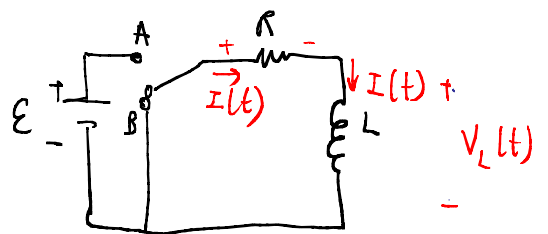


Switch to A: charging inductor:

$$I(t) = I_0 (1 - e^{-\frac{t}{\tau}})$$

$$I_0 = \frac{\mathcal{E}}{R}$$

$$\tau = \frac{L}{R}$$



Switch to B: discharging inductor

$$I(t) = I_0 e^{-\frac{t}{\tau}}$$

$$I_0 = \frac{\mathcal{E}}{R}$$

$$\tau = \frac{L}{R}$$

a) Power dissipation at R over time:

$$P(t) = I(t) \cdot V_R(t)$$

Loop: $-I(t) \cdot R - V_L(t) = 0$

$$\approx V_L(t) = -I(t) \cdot R$$

$$V_R(t) = -V_L(t) = I(t) \cdot R$$

$$\Rightarrow P_R(t) = I^2(t) \cdot R = R \cdot I_0^2 e^{-\frac{2t}{L/R}} = \frac{\Sigma^2}{R} e^{-\frac{2t}{L/R}}$$

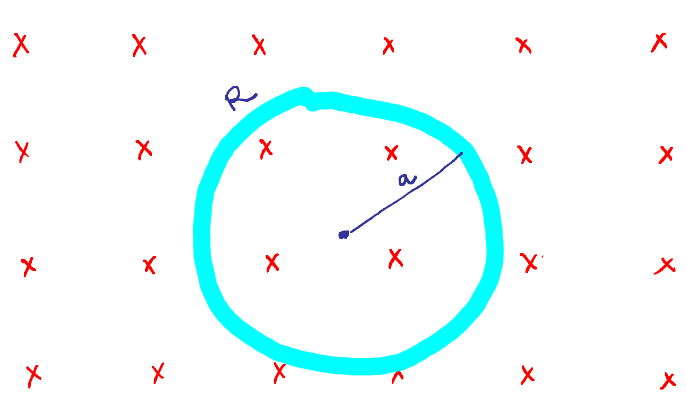
$$b) U_R = \int_0^\infty P_R(t) dt = \frac{\Sigma^2}{R} \int_0^\infty e^{-\frac{2t}{L/R}} dt = \frac{\Sigma^2}{R} \left[\frac{e^{-\frac{2t}{L/R}}}{-\frac{2}{L/R}} \right]_0^\infty = -\frac{\Sigma^2}{R} \cdot \frac{L}{2R} [0 - 1]$$

$$U_R = \frac{1}{2} \frac{\Sigma^2}{R^2} L = \frac{1}{2} L I_0^2 \quad \text{which was energy initially stored in inductor.}$$

\downarrow
 $\frac{\Sigma}{R} = I_0$

27.50

Circular wire loop resistance R , radius a , perpendicular to a uniform magnetic field \vec{B} (going into page, for example)



\vec{B} uniform, into page
Field strength to be increased from B_1 to B_2 ($B_2 > B_1$)

(i) Magnetic flux through wire loop: $\Phi_B = \oint \vec{B} \cdot d\vec{A} = B \int dA = BA = B\pi a^2$

If B stays constant over time $\rightarrow \Phi_B$ is constant over time: $\frac{d\Phi_B}{dt} = 0 = \mathcal{E}$

No induced voltage in loop \rightarrow no moving charges in loop

(ii) Lab: increase B from $B_1 \rightarrow B_2$: $\frac{d\Phi_B}{dt} \neq 0 \rightarrow \mathcal{E} \rightarrow$ moving charges in loop.

Faraday's Law: $\mathcal{E} = - \frac{d\Phi_B}{dt}$

Ohm's law \downarrow

$$I \cdot R = - \frac{d}{dt} (B\pi a^2)$$

$$\frac{dq}{dt} \cdot R = -\pi a^2 \frac{dB}{dt}$$

$$\boxed{dq = -\frac{\pi a^2}{R} dB}$$

Total charge moved: $\int_1^2 dq = -\frac{\pi a^2}{R} \int_1^2 dB$

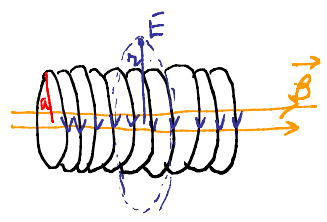
$$Q_2 - Q_1 = -\frac{\pi a^2}{R} (B_2 - B_1)$$

$$\Delta Q = Q_2 - Q_1 = \frac{\pi a^2}{R} (B_1 - B_2)$$

(iii) Does it matter how did you increase field strength b/w 1 & 2? (e.g. quickly or slowly)
 No! ΔQ only depends on the difference $B_1 - B_2$!

27.30

$a = 0.1 \text{ m}$
 $r = 0.12 \text{ m}$
 $E = 45 \frac{\text{V}}{\text{m}}$



Find $\frac{\partial B}{\partial t}$?

Faraday's Law:

$$\mathcal{E} = - \frac{d\Phi_B}{dt}$$

$$\oint \vec{E} \cdot d\vec{l} = - \frac{d}{dt} \int \vec{B} \cdot d\vec{A}$$

\vec{E} wraps around a circular loop of radius r centered at axis of solenoid!

$(\vec{E} \parallel d\vec{l})$ $\int E \cdot dl$

$$= - \int \frac{\partial B}{\partial t} \cdot dA$$

$(\vec{B} \parallel d\vec{A})$

$(\vec{E}$ constant along this loop)

$$E \int dl$$

$$= - \frac{\partial B}{\partial t} \int dA$$

$(\vec{B}$ uniform over cross-sectional area of solenoid)

$$E \cdot 2\pi r$$

$$= - \frac{\partial B}{\partial t} \cdot A$$

$(A = \pi a^2)$

$$\frac{\partial B}{\partial t} = - \frac{E 2\pi r}{\pi a^2} = - \frac{45 \cdot 2 \cdot 0.12}{0.1^2} = -1080 \frac{\text{T}}{\text{s}}$$

Ch 29 Maxwell's Equations:

Maxwell's equations

- 1) Gauss' Law (Ch 21): $\oint_{\text{Gaussian surface}} \vec{E} \cdot d\vec{A} = \frac{q_{\text{enclosed}}}{\epsilon_0}$
- 2) "Magnetic Gauss' Law": $\oint_{\text{closed surface}} \vec{B} \cdot d\vec{A} = 0$ (no magnetic monopole has been found)
- 3) Ampere's Law (Ch 26): $\oint_{\text{Amperian loop}} \vec{B} \cdot d\vec{l} = \mu_0 I_{\text{enclosed}} + \mu_0 I_{\text{displacement}}$
- 4) Faraday's Law (Ch 27): $\oint \vec{E} \cdot d\vec{l} = \mathcal{E} = -\frac{d\Phi_B}{dt} = -\int \left(\frac{\partial \vec{B}}{\partial t}\right) \cdot d\vec{A}$
 $\Phi_B = \int \vec{B} \cdot d\vec{A}$ magnetic flux

Observations:

- (i) A time-varying magnetic field $\left(\frac{\partial \vec{B}}{\partial t}\right)$ can create an electric field \vec{E}
 \hookrightarrow Important hint about connection b/w \vec{E} & \vec{B}
- (ii) Is there a viceversa to (i)? Can a time-varying electric field $\left(\frac{\partial \vec{E}}{\partial t}\right)$ create a magnetic field \vec{B} ?
 Maxwell researched about this & demonstrated this was possible if an extra term is added in Ampere's Law: "the displacement current term".

$$I_{\text{displacement}} = \epsilon_0 \frac{d\Phi_E}{dt} = \epsilon_0 \int \frac{\partial \vec{E}}{\partial t} \cdot d\vec{A}$$

$\Phi_E = \text{electric flux}$
 $= \int \vec{E} \cdot d\vec{A}$

Modified Ampere's Law: $\oint_{\text{Amperian loop}} \vec{B} \cdot d\vec{l} = \mu_0 I_{\text{enclosed}} + \mu_0 \epsilon_0 \int \left(\frac{\partial \vec{E}}{\partial t}\right) \cdot d\vec{A}$

\hookrightarrow gives the viceversa connections b/w \vec{E} & \vec{B} to Faraday's Law

Maxwell's displacement current term implications:

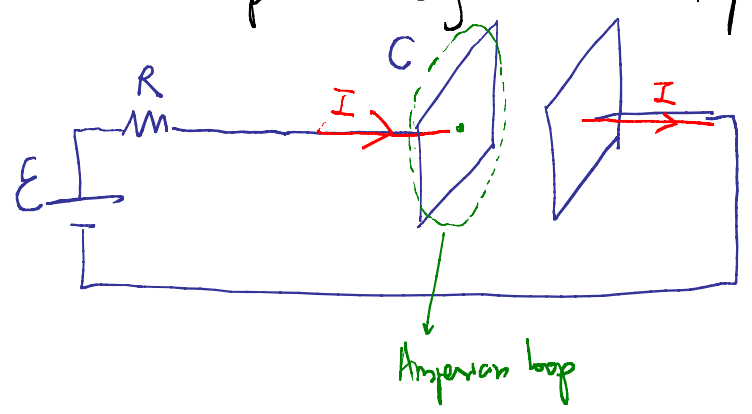
- (i) Ampere's Law is more symmetric to Faraday's Law
- (ii) Two-way connections b/w \vec{E} & \vec{B}
 - 1) Time-varying \vec{B} creates \vec{E}
 - 2) Time-varying \vec{E} creates \vec{B}

$\vec{B}(t) \rightarrow \vec{E}(t) \rightarrow \vec{B}(t) \rightarrow \vec{E}(t) \rightarrow \dots$ allows propagation of EM in vacuum

EM wave propagation w/o medium { Sun light, Space probe signals, Astronomy observations, Cellphone signals, etc..

wave propagation w/ medium { sound waves (medium: air molecules), water waves (medium: water molecules), etc...

Technicality: a magnetic field can be measured around the plates of a capacitor when it is charging. This could not be explained using the old Ampere's Law!



Current I does not cross the gap b/w the plates. So it does not cross the Amperean loop in plane with left plate as shown $\rightarrow I_{\text{enclosed}} = 0$

Old Ampere's Law: $\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{\text{enclosed}} = 0 \Rightarrow B l = 0 \Rightarrow B = 0$
 \rightarrow contradicts measurement of \vec{B} around plates.

Maxwell's displacement current explains this magnetic field:

$\mu_0 \int \frac{\partial \vec{E}}{\partial t} \cdot d\vec{A}$
 $\rightarrow \frac{\partial \vec{E}}{\partial t}$ creates \vec{B} happens in a parallel plate capacitor!
part of EM propagation in vacuum!

Summary: Maxwell's equations

- (1) Propagation of EM waves in vacuum $\vec{B}(t) \rightarrow \vec{E}(t) \rightarrow \vec{B}(t) \rightarrow \vec{E}(t) \rightarrow \dots$
- (2) Both \vec{E} & \vec{B} are vectors \rightarrow polarization of EM waves (Sun glasses!)

Maxwell's equations in vacuum:

→ No charges ($q_{\text{enclosed}} = 0$); no currents ($I_{\text{enclosed}} = 0$)

- 1) Gauss' Law: $\oint \vec{E} \cdot d\vec{A} = 0$
- 2) "Magnetic Gauss' Law": $\oint \vec{B} \cdot d\vec{A} = 0$
- 3) Ampere's Law (Modified): $\oint \vec{B} \cdot d\vec{l} = \mu_0 \epsilon_0 \int \frac{\partial \vec{E}}{\partial t} \cdot d\vec{A}$
- 4) Faraday's Law: $\oint \vec{E} \cdot d\vec{l} = - \int \frac{\partial \vec{B}}{\partial t} \cdot d\vec{A}$

Trivial equations

Does not involve materials
→ applies in vacuum!

Completely symmetric in vacuum (except for a constant $\mu_0 \epsilon_0$ & a minus sign)

Integral forms

Differential forms

3) Ampere's Law:

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 \epsilon_0 \int \frac{\partial \vec{E}}{\partial t} \cdot d\vec{A}$$

$$\rightarrow 3) \frac{\partial B}{\partial x} = -\mu_0 \epsilon_0 \frac{\partial E}{\partial t}$$

4) Faraday's Law:

$$\oint \vec{E} \cdot d\vec{l} = - \int \frac{\partial \vec{B}}{\partial t} \cdot d\vec{A}$$

$$\rightarrow 4) \frac{\partial E}{\partial x} = - \frac{\partial B}{\partial t}$$

$$\frac{\partial}{\partial t} 3) \rightarrow \frac{\partial^2 B}{\partial x \partial t} = -\mu_0 \epsilon_0 \frac{\partial^2 E}{\partial t^2}$$

$$\frac{\partial}{\partial x} 4) \rightarrow \frac{\partial^2 E}{\partial x^2} = - \frac{\partial^2 B}{\partial x \partial t}$$

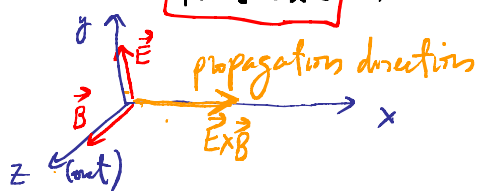
$$\frac{\partial^2 E}{\partial x^2} = \mu_0 \epsilon_0 \frac{\partial^2 E}{\partial t^2}$$

Electro field wave equation
(N mechanical wave equations in Physic 113)
transverse

$$\left. \begin{array}{l} \frac{\partial}{\partial x} 3) \\ \frac{\partial}{\partial t} 4) \end{array} \right\} \rightarrow \frac{\partial^2 B}{\partial x^2} = \mu_0 \epsilon_0 \frac{\partial^2 B}{\partial t^2}$$

Magnetic field wave equation

(i) They are both similar to transverse wave equations on a string
→ Both \vec{E} & \vec{B} are transverse to direction of propagation



However $\vec{E}(t) \rightarrow \vec{B}(t) \rightarrow \vec{E}(t) \rightarrow \dots$ makes EM waves propagate in vacuum unlike mechanical wave in the string!

(ii) Mechanical wave equation: $\frac{\partial^2 y}{\partial x^2} = k \frac{\partial^2 y}{\partial t^2}$
 $\left\{ \begin{array}{l} y: \text{transverse perturbation} \\ x: \text{direction of propagation} \end{array} \right.$
 \hookrightarrow perturbation y was a scalar

EM wave equation \rightarrow perturbations \vec{E} & \vec{B} are vectors! \rightarrow polarization!

(iii) Similar solutions to mechanical wave equations:

$$\begin{cases} \vec{E}(x, t) = E_p \sin(kx - \omega t) \hat{j} \\ \vec{B}(x, t) = B_p \sin(kx - \omega t) \hat{k} \end{cases}$$

E_p & B_p : amplitudes

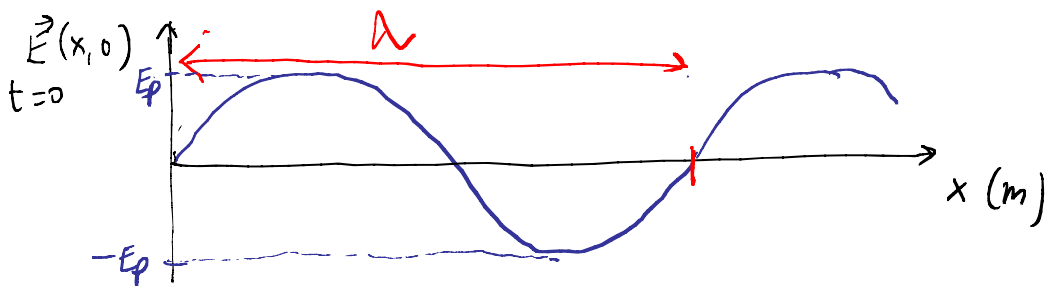
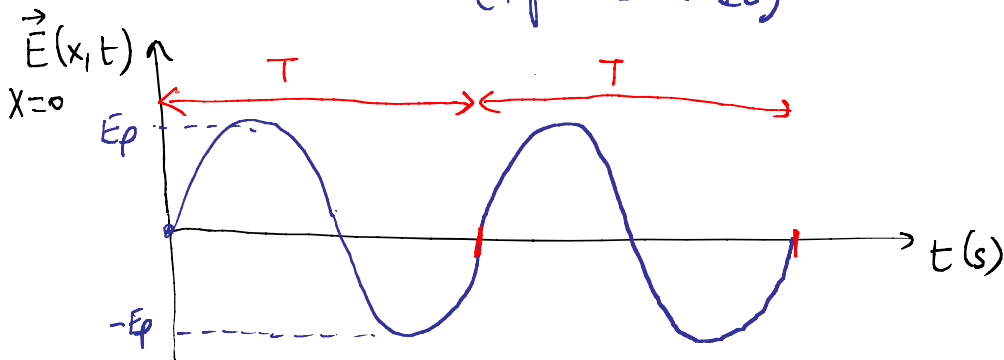
k : wave number $= \frac{2\pi}{\lambda}$ (m^{-1})
 (# wavelengths in 2π)

λ : wavelength (m)

ω : angular frequency $= \frac{2\pi}{T}$ (s^{-1})
 (# periods in 2π)

T : wave period (s)

f : linear frequency $= \frac{1}{T}$ (Hz for Hertz)
 (# periods in 1s)



Electromagnetic Wave Speed in Vacuum:

(i) Wave speed = $v = \frac{\lambda}{T} = \frac{\frac{2\pi}{k}}{\frac{2\pi}{\omega}} = \frac{\omega}{k}$
 (for any wave mechanical or EM)

(ii) What is v for EM waves? From Faraday's & Ampere's Laws in differential forms (in vacuum)

4) $\frac{\partial E}{\partial x} = -\frac{\partial B}{\partial t}$ $\left\{ \begin{array}{l} E(x,t) = E_p \sin(kx - \omega t) \rightarrow \frac{\partial E}{\partial x} = k E_p \cos(kx - \omega t) \\ B(x,t) = B_p \sin(kx - \omega t) \rightarrow \frac{\partial B}{\partial t} = -\omega B_p \cos(kx - \omega t) \end{array} \right.$

Faraday's Law: $k E_p = \omega B_p \rightarrow \boxed{v = \frac{\omega}{k} = \frac{E_p}{B_p}}$ Faraday's

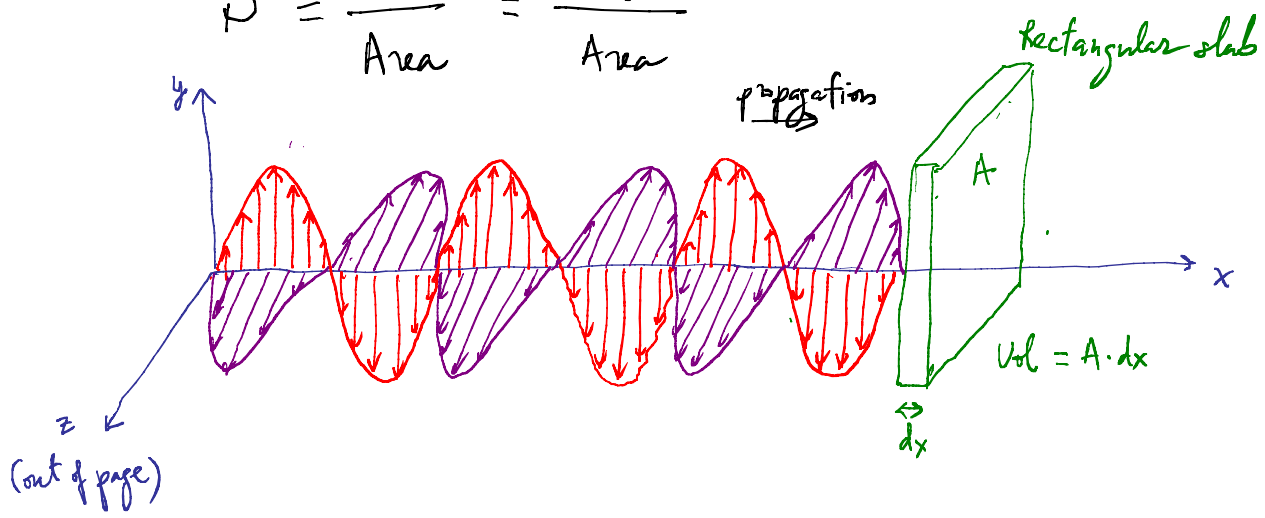
3) $\frac{\partial B}{\partial x} = -\mu_0 \epsilon_0 \frac{\partial E}{\partial t}$ $\left\{ \begin{array}{l} \frac{\partial B}{\partial x} = k B_p \cos(kx - \omega t) \\ -\mu_0 \epsilon_0 \frac{\partial E}{\partial t} = +\mu_0 \epsilon_0 \omega E_p \cos(kx - \omega t) \end{array} \right. \left\{ \begin{array}{l} k B_p = \mu_0 \epsilon_0 \omega E_p \\ \boxed{\frac{E_p}{B_p} = \frac{k}{\mu_0 \epsilon_0 \omega}}$ Ampere's

$$\frac{\omega}{k} = \frac{k}{\mu_0 \epsilon_0 \omega} \Rightarrow \frac{\omega^2}{k^2} = \frac{1}{\mu_0 \epsilon_0} \rightarrow v = \frac{\omega}{k} = \frac{1}{\sqrt{\mu_0 \epsilon_0}} = \frac{1}{\sqrt{4\pi \cdot 10^{-7} \cdot 8.85 \cdot 10^{-12}}} = 2.999 \cdot 10^8 \frac{m}{s} = c$$

c = speed of light (and of any EM wave in vacuum)
 Max speed for any object including EM waves: Einstein's Special Theory of Relativity.

Intensity of EM waves: $\rightarrow \vec{E} = E \hat{j}; \vec{B} = B \hat{k};$ propagation along $\vec{E} \times \vec{B}$ (i) by RHR

$\hookrightarrow S \equiv \frac{P}{\text{Area}} = \frac{dU}{dt \cdot \text{Area}}$



S through the rectangular slab of cross-sectional area A , thickness dx

Rate of change of energy through slab:

$$\frac{dU}{dt} = \frac{d(u \cdot \text{vol})}{dt} = \frac{d(u \cdot A \cdot dx)}{dt} = uA \frac{dx}{dt}$$

wave speed $\rightarrow EM \rightarrow v = c$

U : total energy

u : energy per unit volume or energy density

$$S = \frac{\frac{dU}{dt}}{\text{Area}} = \frac{uAc}{A} = uc = \left(\underbrace{\frac{1}{2} \epsilon_0 E^2}_{\text{electric}} + \underbrace{\frac{1}{2} \mu_0 B^2}_{\text{magnetic}} \right) c$$

$$c^2 = \frac{1}{\mu_0 \epsilon_0} \rightarrow \epsilon_0 = \frac{1}{c^2 \mu_0}$$

$$\epsilon_0 c^2 = \frac{1}{\mu_0}$$

$$c = \frac{E}{B}$$

$$B = \frac{E}{c}$$

$$S = \left(\frac{1}{2} \epsilon_0 E^2 + \frac{1}{2} \epsilon_0 c^2 B^2 \right) c = \frac{1}{2} \epsilon_0 (E^2 + \cancel{c^2} \frac{E^2}{\cancel{c^2}}) c = \epsilon_0 E^2 c$$

$$= \frac{1}{\mu_0 c^2} E^2 c$$

$$S = \frac{1}{\mu_0} E \frac{E}{c} = \frac{1}{\mu_0} EB$$

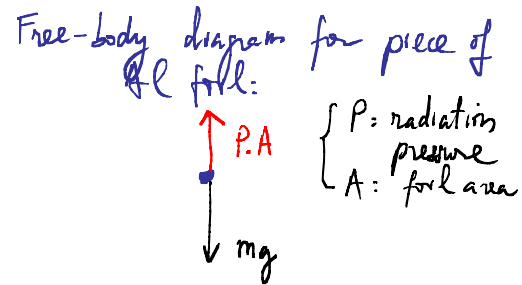
more generally: $\vec{S} = \frac{\vec{E} \times \vec{B}}{\mu_0}$

(SI unit: $\frac{W}{m^2}$)

Radiation Pressure: P

What laser power is need to hold a piece of Aluminum foil of $m = 30 \mu g$ in the air?

Hovering piece of Al foil:



$$P \cdot A = mg$$

$$\text{Power} = \frac{W_{\text{work}}}{\text{time}} = \frac{F \cdot x}{t} = F \cdot v$$

$$S = \frac{\text{Power}}{\text{Area}} = \frac{F}{A} v = \underset{\substack{\uparrow \\ \text{Pressure}}}{P} \cdot v \rightarrow \text{Radiation: } S = P \cdot c$$

\uparrow Pressure \downarrow wave speed

$$2 \frac{S}{c} \cdot A = mg$$

\downarrow b/c Al foil reflects all lights: light comes back at same speed c but

in opposite direction after reflecting off foil

Similar situation: gas molecule reflecting off container wall
 bouncing off \leftrightarrow elastic collisions
 momentum transfer was $2mv$ to the wall

$\rightarrow 2 \frac{S}{c} A = mg \quad \rightarrow \quad \underbrace{S \cdot A}_{\text{Power}} = \frac{mgc}{2}$

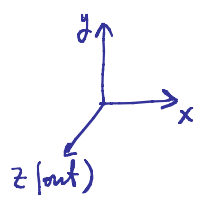
$\text{Power} = \frac{mgc}{2} = \frac{30 \cdot 10^{-6} \cdot 10^{-3} \cdot 9.81 \cdot 3 \cdot 10^8}{2} = 44.1 \text{ W}$

29.43

EM waves: 2 important properties

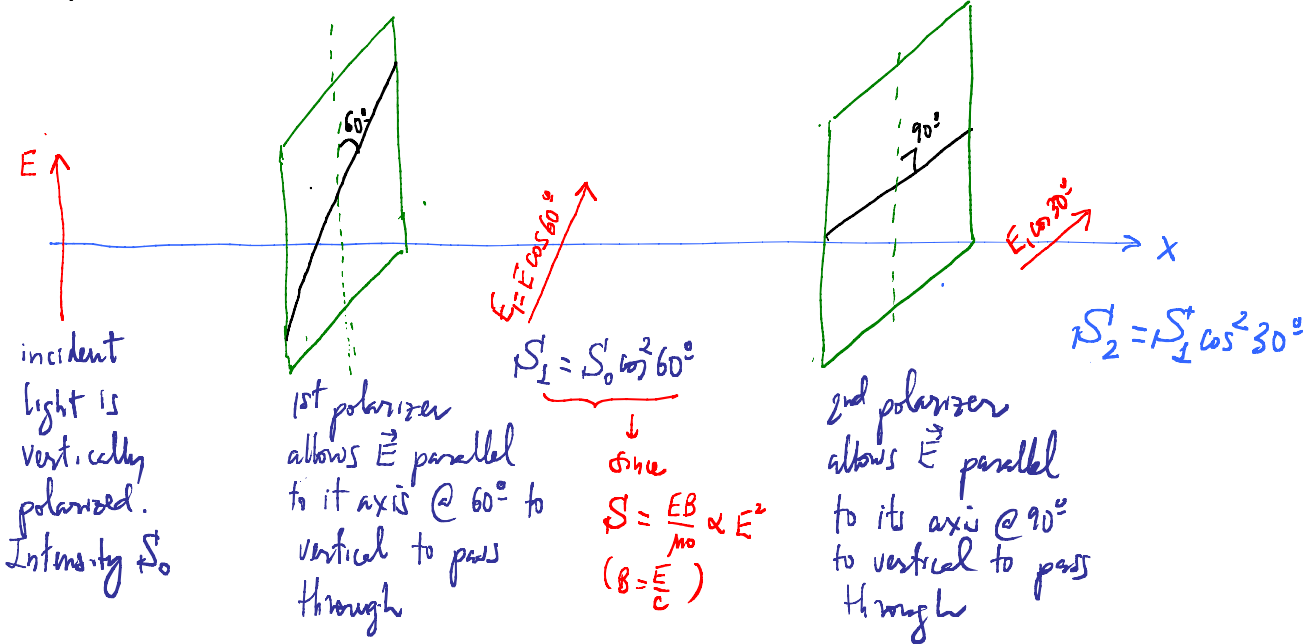
- (i) Can create one another: $E(t) \rightarrow B(t) \rightarrow E(t) \rightarrow \dots$ to propagate in vacuum
- (ii) Vector nature of \vec{E} & $\vec{B} \rightarrow$ Polarization

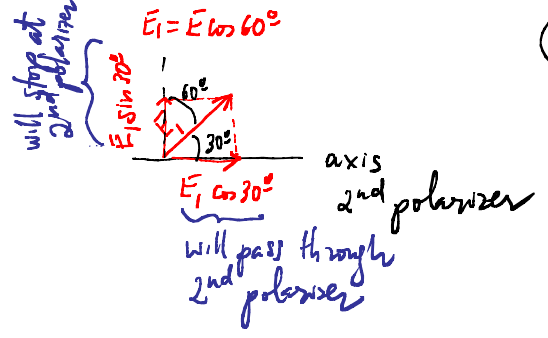
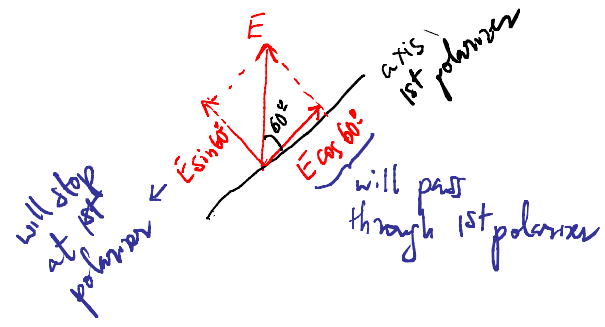
Polarizer: a type of material that only allows EM fields along certain directions to pass through.



\hookrightarrow set by the polarizer's axis
Vertically polarized light: where \vec{E} points along the vertical axis
 (Sun light is unpolarized: \vec{E} points along all possible directions)

- 1st polarizer: axis 60° to vertical
- 2nd polarizer: axis 90° to vertical





Summary { Incident: S_0
 After 1st polarizer: $S_1 = S_0 \cos^2 60^\circ$
 After 2nd polarizer: $S_2 = S_1 \cos^2 30^\circ = S_0 \cos^2 60^\circ \cos^2 30^\circ$

Fraction of light that passes through both is $\frac{S_2}{S_0} = \cos^2 60^\circ \cdot \cos^2 30^\circ = 0.1875$ or 18.75%

Curiosity: (i) with only one polarizer would we get more light through?
 → Not necessarily! With only the 2nd polarizer we get no light through or 0%!
 (ii) If we started out with only polarizer #2 (no light through):
 "illusion of creating light" by inserting polarizer #1!