

Ch 1 Doing PhysicsDimensional Analysis:

$$\text{Speed } v = \frac{\Delta s}{\Delta t}$$

$\rightarrow \boxed{\text{Dimension of speed } [v] = \frac{[\Delta s]}{[\Delta t]} = \frac{L}{T}}$  { "Dimension of speed is length over time"}

$\Delta s$  "change of space" or "increment of space" or distance  
 $\Delta$  "delta"

$\Delta t$  "increment of time" or time

$$\text{Acceleration } a = \frac{\Delta v}{\Delta t}$$

$\rightarrow \boxed{\text{Dimension of acceleration } [a] = \frac{[\Delta v]}{[\Delta t]} = \frac{L}{T} = \frac{L}{T^2}}$

$$\text{Kinetic energy K.E.} = \frac{1}{2}mv^2$$

Intuition  $\left\{ \begin{array}{l} \uparrow v \Rightarrow \uparrow \text{K.E.} \\ \uparrow m \Rightarrow \uparrow \text{K.E.} \end{array} \right\}$  we will derive in Ch. 6

$$\rightarrow \boxed{\text{Dimension of K.E. } [K.E.] = \left[ \frac{1}{2}mv^2 \right] = \left[ \frac{1}{2} \right] \cdot [m] \cdot [v]^2 = \frac{M L^2}{T^2}}$$

numbers  
have no  
dimension

$\rightarrow$  Use dimensional analysis to check physics formulae :

Which one is a  
concrete formula for  
speed ?

$$\left\{ \begin{array}{l} v_1 = \frac{1}{2}gh^2 \rightarrow [v_1] = [g] \cdot [h]^2 = \frac{L}{T^2} \cdot L^2 = \frac{L^3}{T^2} \neq \frac{L}{T} \\ v_2 = \sqrt{g \cdot h} \rightarrow [v_2] = [g]^{\frac{1}{2}} \cdot [h]^{\frac{1}{2}} = \frac{L^{\frac{1}{2}}}{T} \cdot L^{\frac{1}{2}} = \frac{L}{T} \end{array} \right.$$

$g$ : acceleration of gravity  
 $h$ : height or vertical position

Conclusion:  $v_2$  is concrete formula for speed  
 Limitation: except for a multiplicative constant

(2)

Units { S.I. : international system  
British :

<u>Dimension</u>	<u>SI</u>	<u>British</u>
L	m (meter)	ft (foot)
T	s (second)	s
M	kg (kilogram)	lbs (pounds)
[Area] = $L^2$	$m^2$	$ft^2$
[Volume] = $L^3$	$m^3$	$ft^3$
[Energy] = $\frac{ML^2}{T^2}$	$\frac{kg \cdot m^2}{s^2} \equiv J$ (Joule)	$\frac{lb \cdot ft^2}{s^2} \rightarrow Btu$

### Sub & super units :

nano	milli	μm	mm	cm	m	km	light-year
$10^{-9} m$	$10^{-6} m$	$10^{-3} m$	$10^{-2} m$	$1m$	$10^3 m$	$10^6 m$	$9.46 \cdot 10^{15} m$

$nm^2$	$\mu m^2$	$mm^2$	$cm^2$	$m^2$	$km^2$	...	in	ft	mi
$10^{-18} m^2$	$10^{-12} m^2$	$10^{-6} m^2$	$10^{-4} m^2$	$1m^2$	$10^6 m^2$	...	$2.54 cm$	$0.3048 m$	$1609 m$
...	$cm^3$	$m^3$	$km^3$	$10^{-6} m^3$	$1m^3$	$10^9 m^3$	...	...	...

femtos	ps	μs	ms	s	min	hr	day	---
$10^{-15} s$	$10^{-12} s$	$10^{-6} s$	$10^{-3} s$	$1s$	$60s$	$3600s$	$86400s$	---

μg	mg	g	kg
$10^{-9} kg$	$10^{-6} kg$	$10^{-3} kg$	$1kg$

(3)

## Accuracy & Significant Figures:

- . Scientific notation: use powers of 10 & coefficient which is less than 10

$$\Delta s = 6176000 \text{ m} = 6.176 \cdot 10^6 \text{ m} = \underbrace{6.176}_{\text{coefficient}} \cdot 10^6 \text{ m}$$

$$\Delta t = 3000 \text{ s} = 3 \cdot 10^3 \text{ s} = 3E3 \text{ s}$$

$$\text{speed } v = \frac{\Delta s}{\Delta t} = \frac{6.176 \cdot 10^6}{3 \cdot 10^3} = \frac{6.176}{3} \cdot 10^{6-3} = 2.059 \cdot 10^3 \frac{\text{m}}{\text{s}}$$

- . Accuracy (addition & subtraction)

$$\pi - 1.14 = 3.1416 - 1.14 = 2.0016$$

(assume  $\pi = 3.1416$ )

↓ only up to least accuracy of two terms  
2.00

- . Significant figures s.f.'s (multiplication & division)

s.f.'s  $\underbrace{6370000}_{3} \text{ m}$   
end zeros don't count

$\underbrace{6370001}_{7} \text{ m}$   
middle zeros do count

$$\text{Circumference of Earth} = 2\pi R_E = 2 \cdot 3.1416 \cdot 6.37 \cdot 10^6 \text{ m}$$

$$R_E = 6.37 \cdot 10^6 \text{ m}$$

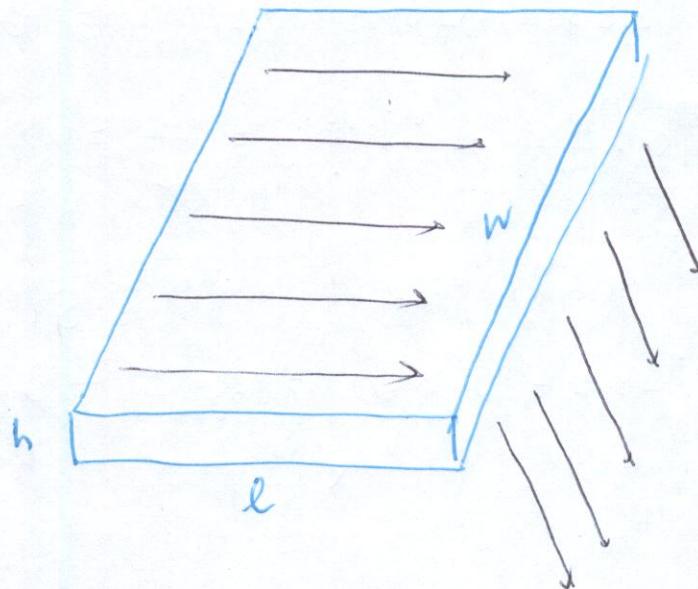
$$= 4.002398 \cdot 10^7 \text{ m}$$

↓ only up to least # of significant figures of the factors involved  
 $4.00 \cdot 10^7 \text{ m}$

- 1.41 a) Estimate volume of water going over Niagara Falls in 1s

Guess:  $6420 \frac{m^3}{s}$

Estimation: water over Falls modeled as a rectangular slab.



$$\text{Volume per second or flow rate} = \frac{h \cdot l \cdot w}{t}$$

$$1) \frac{h}{t} \cdot l \cdot w$$

$$2) h \cdot \frac{l}{t} \cdot w \quad \checkmark$$

$$3) h \cdot l \cdot \frac{w}{t}$$

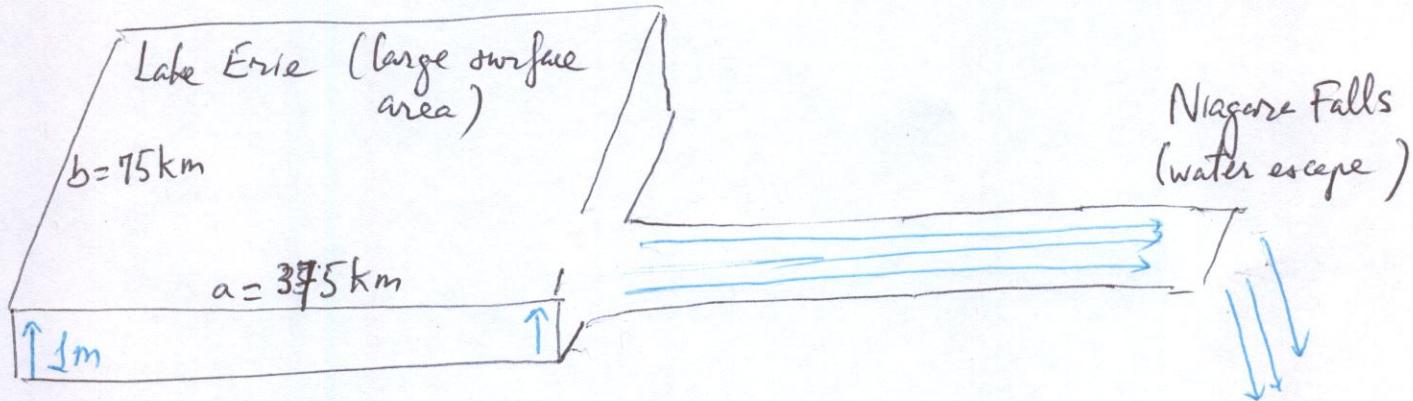
Numerical values  $\left\{ \begin{array}{l} \frac{h}{t} \\ \frac{l}{t} \\ w \end{array} \right. \text{ speed of water} : \begin{array}{l} = 1m, 10m, 100m \\ = 1\frac{m}{s}, 10\frac{m}{s}, 100\frac{m}{s} \\ = 100m, 1000m, 10000m \end{array}$

$$\rightarrow \text{Flow rate: } 1m \cdot 1\frac{m}{s} \cdot 1000m = \frac{1000 m^3}{s}$$

- b) If Niagara Falls are shut off, water level at Lake Erie will rise (Why?) How long does it take for it to rise 1m?

(5)

Niagara Falls serve as an escape for additional water (rains) etc.  
in Lake Erie  $\Leftrightarrow$  Flow rate over Falls = water increase rate in Lake Erie



$\Rightarrow$  How long does it take ( $t$ ) to accumulate  $V = 375 \cdot 10^3 \cdot 75 \cdot 10^3 \cdot 1 \text{ m}^3$

$$t = \frac{\text{Vol } V}{\text{Flow rate}} = \frac{375 \cdot 75 \cdot 10^3 \text{ m}^3}{10^8 \frac{\text{m}^3}{\text{s}}} = 28125 \times 10^3 \text{ s} \cdot \frac{1 \text{ day}}{86400 \text{ s}} = 326 \text{ days}$$

Flow rate

$$10^3 \frac{\text{m}^3}{\text{s}}$$

$$10^4 \frac{\text{m}^3}{\text{s}}$$

$t$

$$326 \text{ days} \sim 1 \text{ year}$$

$$32.6 \text{ days} \sim 1 \text{ month}$$

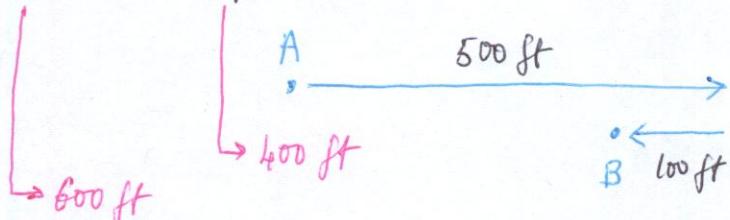
## Ch 2 Motion in a Straight Line

either horizontal or vertical

- Average & instantaneous motion
- Speed & velocity

$$\hookrightarrow \frac{\text{distance}}{\text{time}} \quad \hookrightarrow \frac{\text{displacement}}{\text{time}}$$

• distance & displacement:



• If we travel Boston - NYC - Boston  $\left\{ \begin{array}{l} \text{distance } \sim 500 \text{ mi} \\ \text{displacement } \sim 0 \text{ mi} \end{array} \right.$

• Between A & B  $\left\{ \begin{array}{l} \text{speed} = 100 \text{ ft/min} \\ t_{AB} = 6 \text{ min} \end{array} \right.$

$$\text{velocity} = \frac{400 \text{ ft}}{6 \text{ min}} = 66.67 \frac{\text{ft}}{\text{min}}$$

• Velocity takes consideration of direction (more general)

→ Average velocity:  $\overline{v} = \frac{\Delta x}{\Delta t}$   $(\frac{\text{m}}{\text{s}})$   $\left\{ \begin{array}{l} \Delta x: \text{change of position or displacement} \\ \Delta t: \text{change of time or time} \end{array} \right.$

→ Instantaneous velocity:  $v = \lim_{\Delta t \rightarrow 0} \frac{\Delta x}{\Delta t} = \frac{dx}{dt}$  "time derivative of position x"  
Calculus

e.g.:  $x = a \cdot t^3 \rightarrow v = \frac{dx}{dt} = 3at^2$   
 $\left( \frac{dt^n}{\Delta t} = nt^{n-1} \right) \quad \boxed{\frac{dx}{dt}}$

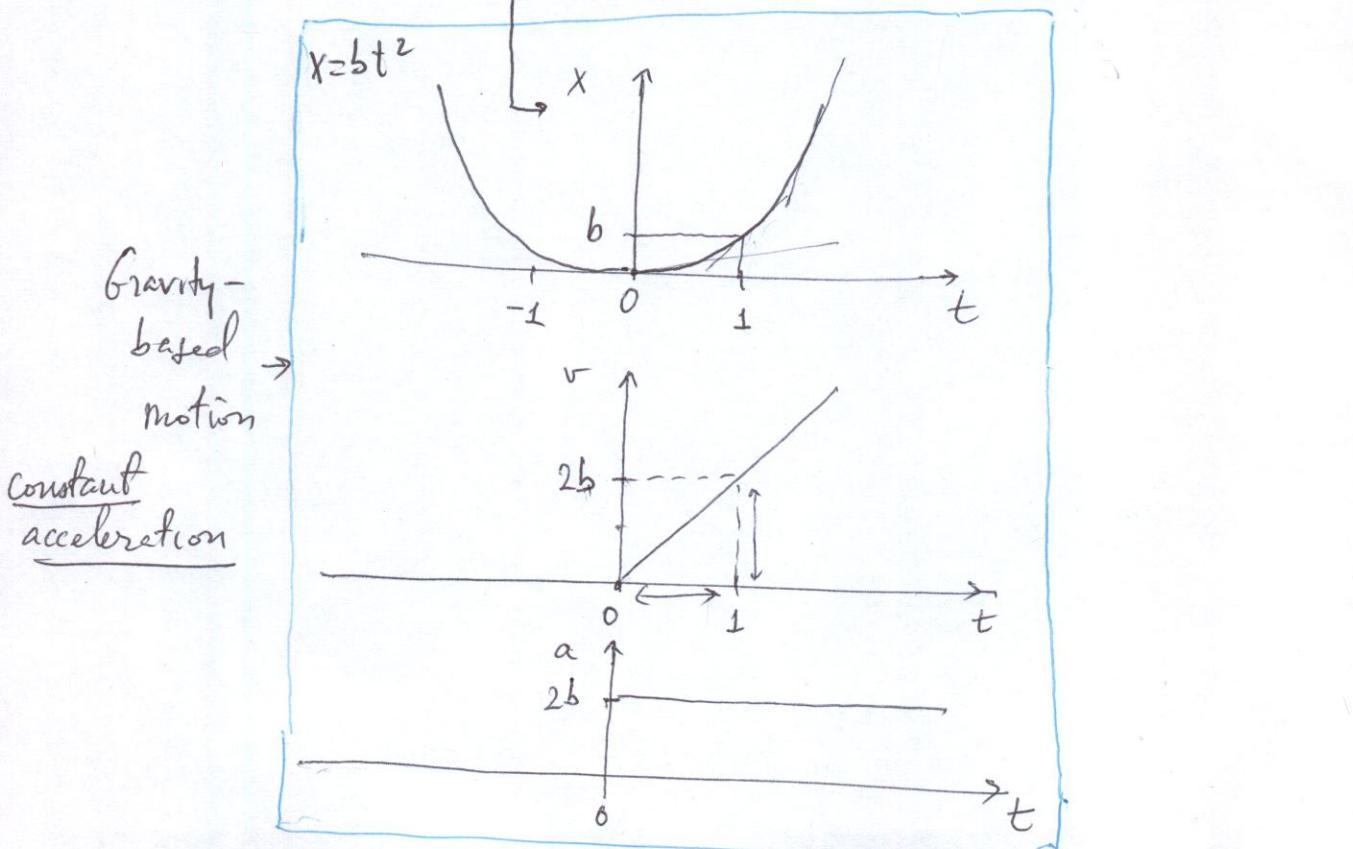
Acceleration: change of velocity over time

Average acceleration:  $\bar{a} = \frac{\Delta v}{\Delta t}$   $\left( \frac{m}{s^2} \right)$

$\Delta v$  = change of velocity  
 $\Delta t$  = change of time

Instantaneous acceleration:  $a = \lim_{\Delta t \rightarrow 0} \frac{\Delta v}{\Delta t} = \frac{dv}{dt}$  "time derivative of velocity v"  
 $\left( \frac{m}{s^2} \right)$  calculus

e.g.:  $x = bt^3 \rightarrow v = 3bt^2 \rightarrow a = 6bt$  (acceleration increases linearly with time)  
gravity  $\rightarrow$  constant acceleration  $a = g = 9.81 \frac{m}{s^2}$   
Which  $x = f(t)$  describes gravity-based motion?  
 $\hookrightarrow x = bt^2 \rightarrow v = 2bt \rightarrow a = 2b$  constant



From the previous intuitive definitions of  $\bar{v}$ ,  $v$ ,  $\bar{a}$ ,  $a$  we will derive kinematic equations for a constant acceleration in 1D (straight line)

Constant acceleration:  $\bar{a} = a$

$$a = \bar{a} = \frac{\Delta v}{\Delta t} = \frac{v - v_0}{t - 0} \Rightarrow v - v_0 = a \cdot t$$

current velocity  
initial velocity  
current time  
initial time

$$\rightarrow v = v_0 + a \cdot t \quad (1) \quad \text{Kinematic eq. #1}$$

Kinematic eq. #2:  $\bar{v}$  current position  
initial position

$$\left\{ \begin{array}{l} \bar{v} = \frac{\Delta x}{\Delta t} = \frac{x - x_0}{t - 0} \rightarrow x = x_0 + \bar{v} \cdot t \quad (\text{A}) \\ \bar{v} = \frac{\int_0^t dt \ v}{t - 0} \stackrel{(1)}{=} \frac{1}{t} \int_0^t dt (v_0 + a \cdot t) \\ \qquad \qquad \qquad \text{mathematical average} \\ \qquad \qquad \qquad = \frac{1}{t} \left[ v_0 t + \frac{1}{2} a \cdot t^2 \right]_0^t = \frac{1}{t} [v_0 t + \frac{1}{2} a t^2] \end{array} \right.$$

Math review

$$\left\{ \begin{array}{l} \int v_0 dt = v_0 \underbrace{\int dt}_t = v_0 \cdot t \\ \int t dt = \frac{1}{2} t^2 \\ \int t^n dt = \frac{t^{n+1}}{n+1} \end{array} \right. \quad \downarrow \quad \bar{v} = v_0 + \frac{1}{2} a \cdot t = \frac{1}{2} v_0 + \underbrace{\frac{1}{2} v_0 + \frac{1}{2} a \cdot t}_{\frac{1}{2} (v_0 + a \cdot t)}$$

$$\bar{v} = \frac{1}{2} (v_0 + v) \quad (\text{B})$$

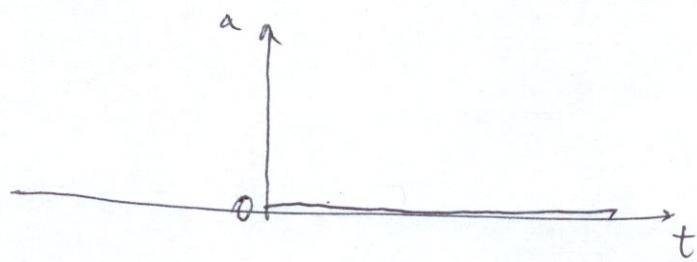
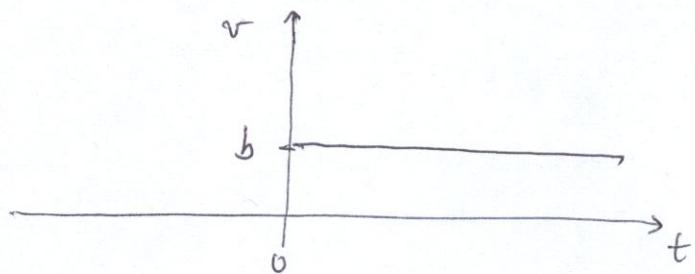
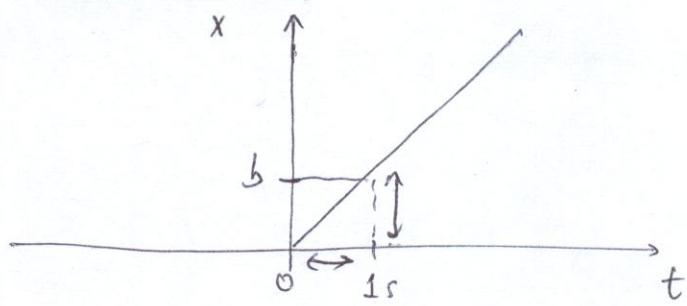
$$(A) = x = x_0 + \bar{v} \cdot t = x_0 + \frac{1}{2} (v_0 + v) \cdot t = x_0 + \frac{1}{2} (v_0 + v_0 + a \cdot t) \cdot t$$

$$(B) = \bar{v} = \frac{1}{2} (v_0 + v) \quad \uparrow \quad (1)$$

⑧

$$\text{If } x = bt \rightarrow \boxed{v = b} \rightarrow a = 0$$

↓  
Uniform motion



$$x = x_0 + v_0 \cdot t + \frac{1}{2} a \cdot t^2 \quad (2) \quad \text{Kinematic eq. #2}$$

Summary: to describe a **constant acceleration** motion in 1D:

$$1) \quad v = v_0 + a \cdot t$$

$$2) \quad x = x_0 + v_0 \cdot t + \frac{1}{2} a \cdot t^2$$

$$3) \quad \text{Eliminating time from 1) \& 2): } \frac{v^2 - v_0^2}{x - x_0} = 2a$$

- When time is not given or asked for  $\rightarrow$  start with kinematic Eq. #3. Otherwise use 1) or 2) or both!

$x_0$ : initial position (m);  $x$ : current position (m)

$v_0$ : " velocity (m/s);  $v$ : " velocity

$a$ : constant acceleration ( $\frac{m}{s^2}$ ) ;  $t$ : current time (s);  $t_0 = 0$  initial time

$$\bar{a} = a$$

Example: 2.33

- After reading it carefully, write down information

$$v_0 = 50 \frac{\text{mi}}{\text{h}}$$

"Begins slowing down @ constant rate 100 ft short of a stop light"

$$\begin{cases} x - x_0 = 100 \text{ ft} \\ a = \text{constant}(a?) \end{cases}$$

"Car comes to a stop just @ light"  $v = 0$

- Time is not involved  $\leftrightarrow$  eq#3  $\frac{v^2 - v_0^2}{x - x_0} = 2 \cdot a$

- Units are in S.I.  $\begin{cases} v_0 = 50 \frac{\text{mi}}{\text{h}} \cdot \frac{1609 \text{ m}}{\text{mi}} \cdot \frac{1 \text{ h}}{3600 \text{ s}} = 22.35 \frac{\text{m}}{\text{s}} \\ x - x_0 = 100 \text{ ft.} \cdot \frac{0.3048 \text{ m}}{1 \text{ ft}} = 30.48 \text{ m} \end{cases}$

$$a = \frac{1}{2} \frac{0 - 22.35^2}{30.48} = -8.192 \frac{\text{m}}{\text{s}^2}$$

Negative acceleration: makes sense since  
 ↳ or deceleration

$$\left\{ \begin{array}{l} v_0 = 22.35 \frac{\text{m}}{\text{s}} \\ v = 0 \end{array} \right.$$

2.59]

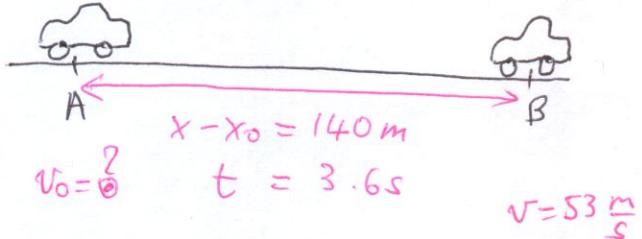
1) Read carefully, then write down information.

$$\left\{ \begin{array}{l} a = \text{constant} \\ x - x_0 = 140 \text{ m} \\ t = 3.6 \text{ s} \end{array} \right.$$

$$\left\{ \begin{array}{l} v = 53 \frac{\text{m}}{\text{s}} \\ v_0 ? \end{array} \right.$$

$$a = \text{constant}$$

Recommend: a diagram



2) Selecting equation to start:

Alternative #1

$$\text{Eq#2: } x - x_0 = v_0 t + \frac{1}{2} a t^2$$

Eliminate  $v_0$  using eq#1:  $v_0 = v - a \cdot t$

$$\rightarrow x - x_0 = (v - a \cdot t) \cdot t + \frac{1}{2} a \cdot t^2 = v \cdot t - \frac{1}{2} a \cdot t^2$$

$$\hookrightarrow \text{Solve for } a: a = \frac{[v \cdot t - (x - x_0)]}{t^2}$$

$$[a = \frac{[53 \cdot 3.6 - 140]}{3.6^2} = 7.83 \frac{\text{m}}{\text{s}^2}]$$

3)

$$\text{Now use eq#1 to find } [v_0 = v - a \cdot t = 53 - 7.83 \cdot 3.6 = 24.8 \frac{\text{m}}{\text{s}}]$$

Alternative #2

Start with Eq#1 :  $v = v_0 + a \cdot t$   $\rightarrow a = \frac{v - v_0}{t}$

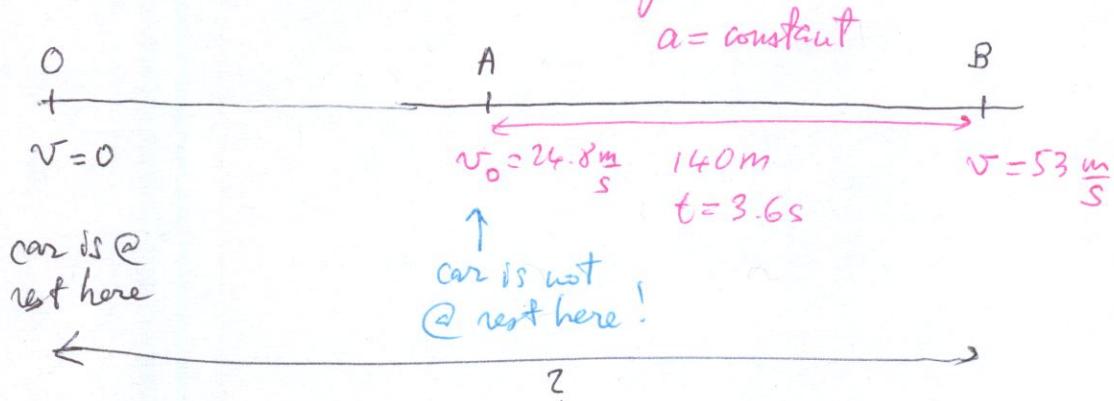
$\rightarrow$  Use Eq#2 :  $x - x_0 = v_0 t + \frac{1}{2} a \cdot t^2$   $\leftarrow v_0 \cdot t + \frac{1}{2} \frac{v - v_0}{t} \cdot t^2$   
 $= v_0 \cdot t + \frac{1}{2} (v - v_0) \cdot t$   
 $= \frac{(v + v_0)}{2} \cdot t$

$$x - x_0 = \frac{(v + v_0)}{2} \frac{t}{2} \quad \rightarrow \text{Solve for } v_0 :$$

3)  $v_0 = (x - x_0) \frac{2}{t} - v = 140 \cdot \frac{2}{3.6} - 53 = \underline{\underline{24.8 \frac{m}{s}}}$

b) How far did it travel from rest to end of 140 m distance?

↳ Make sense with a diagram



Continuing with Alternative #1 :  $OB = OA + 140m$

Find  $OA$ ,  $a = 7.83 \frac{m}{s^2}$ , should be same from O to A to B

$$\rightarrow \text{Eq#3} : \frac{v_A^2 - v_0^2}{(x - x_0)_{OA}} = 2 \cdot a \Rightarrow (x - x_0)_{OA} = \frac{v_A^2 - v_0^2}{2 \cdot a} = \frac{24.8^2 - 0}{2 \cdot 7.83}$$

$$= 39.4m \Rightarrow \boxed{OB = 179.4m}$$

Continuing with alternative #2 :

$$\text{Calculate } a = \frac{v - v_0}{t} = \frac{53 - 24.8}{3.6} = 7.83 \frac{m}{s^2}$$

Find  $OB$  = Eq#3 :

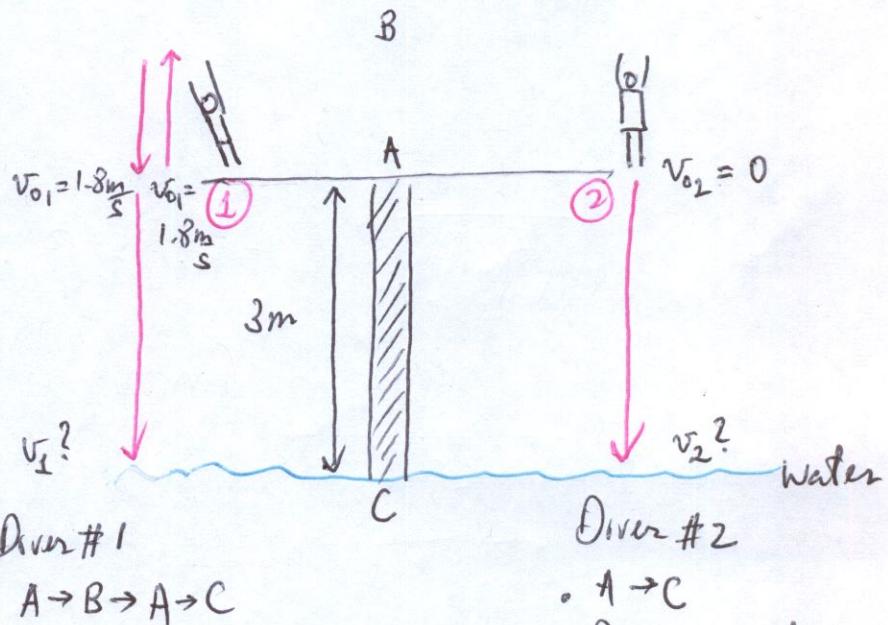
(13)

$$\text{Find } OB: \frac{\sqrt{v_B^2 - v_0^2}}{(x-x_0)_{OB}} = 2 \cdot a \rightarrow (x-x_0)_{OB} = \frac{\sqrt{v_B^2 - v_0^2}}{2 \cdot a} = \frac{53^2 - 0}{2 \cdot 7.83}$$

$OB = 179.4 \text{ m}$

2.69

1) Given information:



questions:

- (a)  $v_1$  &  $v_2$
- (b) which diver enters water first & by how much time?

- $A \rightarrow C$
- Diver #2 steps off when #1 comes back down by A

2) Equation to solve for  $v_1$  &  $v_2$ :

→ Predictions or quick answer i) diver #1 will enter water first since he has an initial downward velocity @ A.

$$\text{ii) } v = v_0 + a \cdot t = v_0 + g \cdot t$$

same  $a=g$  for both  $\rightarrow v_1 > v_2$

→ Constant acceleration: no time info or request in a)  $\Rightarrow$  Eq#3

Diver #1

$$\frac{v_1^2 - v_{01}^2}{x - x_0} = 2 \cdot g$$

Diver #2

$$\frac{v_2^2 - 0}{x - x_0} = 2 \cdot g$$

3) Numeric solution with correct units:

$$v_1 = \sqrt{2g(x-x_0) + v_{01}^2}$$

$$v_1 = \sqrt{2 \cdot 9.81 \cdot 3 + 1.8^2} = 7.88 \frac{m}{s} > v_2 = \sqrt{2 \cdot 9.81 \cdot 3} = 7.67 \frac{m}{s}$$

$$\left\{ \begin{array}{l} x - x_0 = 3 \text{ m} \\ v_{01} = 1.8 \frac{m}{s} \end{array} \right.$$

$$v_2 = \sqrt{2g(x-x_0)}$$

5) To find time : Eq#1 =  $v = v_0 + a \cdot t$

Diver #1

$$t_1 = \frac{v_f - v_{01}}{g}$$

$$t_1 = \frac{7.88 - 1.8}{9.81} = 0.62\text{s}$$

Diver #2

$$t_2 = \frac{v_2}{g}$$

$$t_2 = \frac{7.67}{9.81} = 0.78\text{s}$$

$$\rightarrow [t_2 - t_1 = 0.78 - 0.62 = 0.16\text{s}]$$

Just for fun : If we include time diver #1 takes to go up then down (A  $\rightarrow$  B  $\rightarrow$  A):

$$\text{Eq#1 : } v = v_0 + a \cdot t$$

upward motion :  $\left\{ \begin{array}{l} v=0 \\ v_{01} = 1.8 \frac{\text{m}}{\text{s}} \\ a=-g \end{array} \right.$

$t_{\text{down}}$  |  $t_{\text{up}}$

$v_{01} = 1.8 \frac{\text{m}}{\text{s}}$  A

$$0 = 1.8 - 9.81 \cdot t_{\text{up}} \rightarrow t_{\text{up}} = \frac{1.8}{9.81} = 0.183\text{s}$$

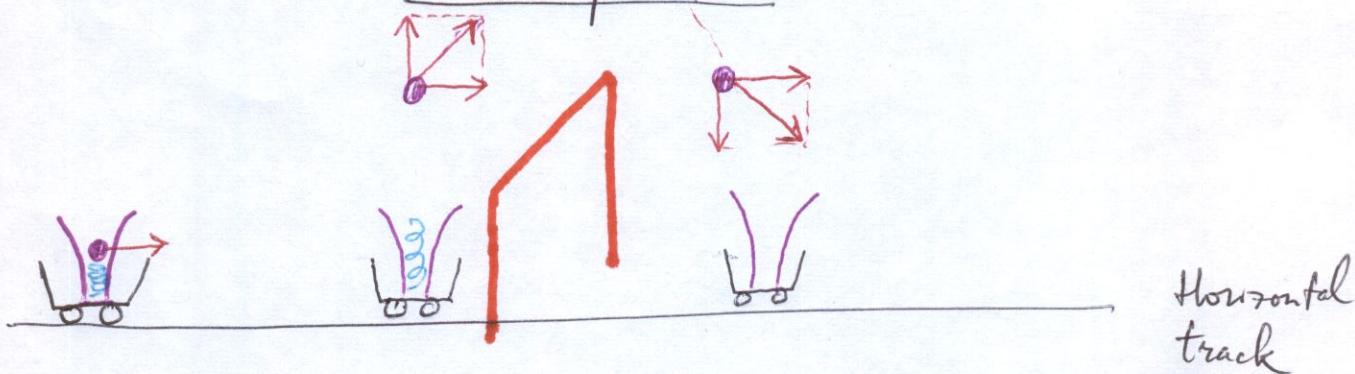
$$A \rightarrow B \rightarrow A \rightarrow 2 \cdot t_{\text{up}} = 0.366\text{s}$$

## Ch 3 Motion in Two & Three Dimensions

Note:  $\left\{ \begin{array}{l} \text{Ch 2: 1D} \\ \text{horizontal: motion of a car} \\ \text{or} \\ \text{vertical: divers} \end{array} \right.$   
 $\left\{ \begin{array}{l} \text{Ch 3: 2D} \\ \text{horizontal and vertical simultaneous motion} \end{array} \right.$

Need a very important assumption

↓  
Visual experiment:



Horizontal track

1) Negligible friction b/w wheels & track

$$\rightarrow v_{\text{cart}} = \text{constant} \& \text{horizontal}$$

Direction is important in 2D & 3D

→ Use vectors (Velocity vector, position vector, acceleration vector)

2) Negligible air resistance (smaller front surface)

3) In cart: a funnel with a compressed spring, a ball sitting on top of it.

4) Gate about middle of long track with a sensor, when cart approaches gate it will release the spring, launching ball **vertically upward**

5) Before spring is released **ball** travels with cart in uniform horizontal motion. After spring is released **ball**

acquires an additional constant-acceleration vertical motion in addition to the original uniform horizontal motion!

So after being launched upward by the spring, ball has simultaneous horizontal & vertical motion resulting in a parabola.

- 6) After gate will ball goes {  
 Behind cart  
 Into cart  
 Beyond cart}

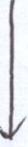
- 7) Brg conclusion for this to happen:

The vertical launch by spring did not affect the ball's (force)  
 horizontal uniform motion. (ball was always above cart traveling @ same uniform horizontal velocity!)

→ Motion along perpendicular directions are independent!

Mathematical descriptions of motion in 2D & 3D

↳ Add & Subtract vectors

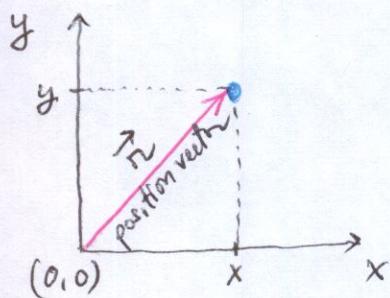


- {  
 1) Graphically  
 2) Mathematically using unit vectors

	<u>1D</u>	<u>2D</u>	<u>3D</u>	Theta phi
position	$x$	$\vec{r} = (x, y) = (r, \theta)$	$\vec{r} = (x, y, z) = (r, \theta, \psi)$	
velocity	$v$	$\vec{v} = (v_x, v_y) = (v, \theta_v)$	$\vec{v} = (v_x, v_y, v_z) = (v, \theta_v, \psi_v)$	
acceleration	$a$	$\vec{a} = (a_x, a_y) = (a, \theta_a)$	$\vec{a} = (a_x, a_y, a_z) = (a, \theta_a, \psi_a)$	

*Cartesian Polar  
coordinates coordinates*

*Cartesian Spherical*

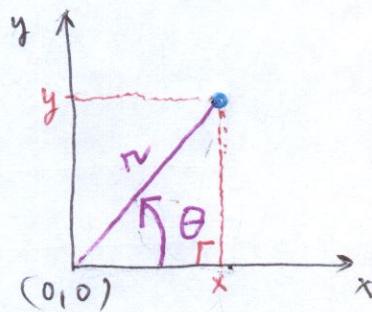
2DCartesian

- Position vector  $\vec{r}$  starts @ origin  $(0,0)$ , ends @ object position
- Projection of  $\vec{r}$  onto the x-axis is the x-component; onto the y-axis is y-component

$$\vec{r} = (x, y)$$

$$\text{Cartesian } (x, y) \longrightarrow \text{Polar } (r, \theta)$$

$$\text{Polar } (r, \theta) \longrightarrow \text{Cartesian } (x, y) \quad \left\{ \begin{array}{l} x = r \cos \theta \\ y = r \sin \theta \end{array} \right. \quad \begin{array}{l} r = \sqrt{x^2 + y^2} \\ \theta = \tan^{-1} \left( \frac{y}{x} \right) \end{array} \quad \begin{array}{l} \text{Pythagorean Theorem} \\ \text{Trigonometry} \end{array} \quad \begin{array}{l} \text{Trigonometry} \end{array}$$

Polar

- We can also locate the same object by knowing its radius  $r$  from the origin  $(0,0)$  and its angle  $\theta$  from the x-axis (CCW)

(19)

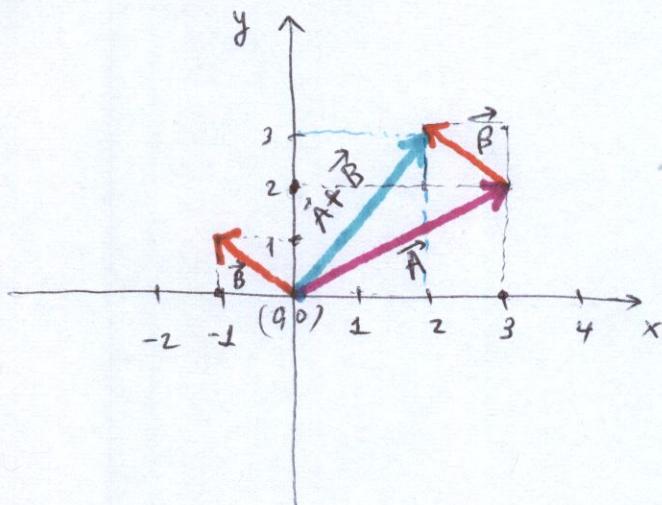
## Add & Subtract vectors

$$\vec{v} = \vec{v}_0 + \vec{a} \cdot t$$

$$\vec{r} = \vec{r}_0 + \vec{v}_0 \cdot t + \frac{1}{2} \vec{a} \cdot t^2$$

- 1) Graphical addition & subtraction  
 $\vec{A} + \vec{B}$ ?       $\vec{A} - \vec{B}$ ?

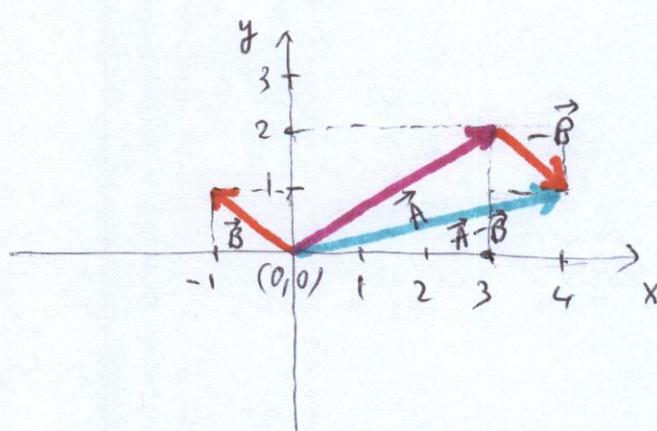
two vectors  $\begin{cases} \vec{A} = (3, 2) \\ \vec{B} = (-1, 1) \end{cases}$



$\vec{A} + \vec{B}$  : i) Draw a copy of  $\vec{B}$  starting @ tip of  $\vec{A}$

ii)  $\vec{A} + \vec{B}$  starts from origin of  $\vec{A}$  to the tip of the copy of  $\vec{B}$

$$\vec{A} + \vec{B} = (2, 3)$$



$\vec{A} - \vec{B}$  : i) Draw a copy of  $-\vec{B}$  starting @ tip of  $\vec{A}$

ii)  $\vec{A} - \vec{B}$  from origin of  $\vec{A}$  to tip of copy of  $-\vec{B}$

$$\vec{A} - \vec{B} = (4, 1)$$

- 2) Mathematical addition & subtraction using unit vectors  
 (3D, or other complex situations)

Unit vectors:  $\left\{ \begin{array}{l} \text{length or magnitude is 1} \\ \text{direction} : \left\{ \begin{array}{l} x \rightarrow \hat{i} \quad ("i \text{ hat}") \\ y \rightarrow \hat{j} \quad ("j \text{ hat}") \\ z \rightarrow \hat{k} \quad ("k \text{ hat}") \end{array} \right. \end{array} \right.$

Cartesian unit vectors

Fixed or constant  
in time

$\hat{i}$   
 $\hat{j}$   
 $\hat{k}$

Spherical unit  
vectors

Not fixed nor  
constant in time  
(they can change  
direction)

Using Cartesian unit vectors:

$$\vec{A} = (3, 2) = 3\hat{i} + 2\hat{j} \rightarrow \text{In general } \vec{A} = (A_x, A_y) = A_x\hat{i} + A_y\hat{j}$$

$$\vec{B} = (-1, 1) = -\hat{i} + \hat{j} \rightarrow \text{In general } \vec{B} = (B_x, B_y) = B_x\hat{i} + B_y\hat{j}$$

$$\text{Addition: } \vec{A} + \vec{B} = 3\hat{i} + 2\hat{j} - \hat{i} + \hat{j} = 2\hat{i} + 3\hat{j} = (2, 3)$$

$$\text{Subtraction: } \vec{A} - \vec{B} = 3\hat{i} + 2\hat{j} - (-\hat{i} + \hat{j}) = 4\hat{i} + 1\hat{j} = (4, 1)$$

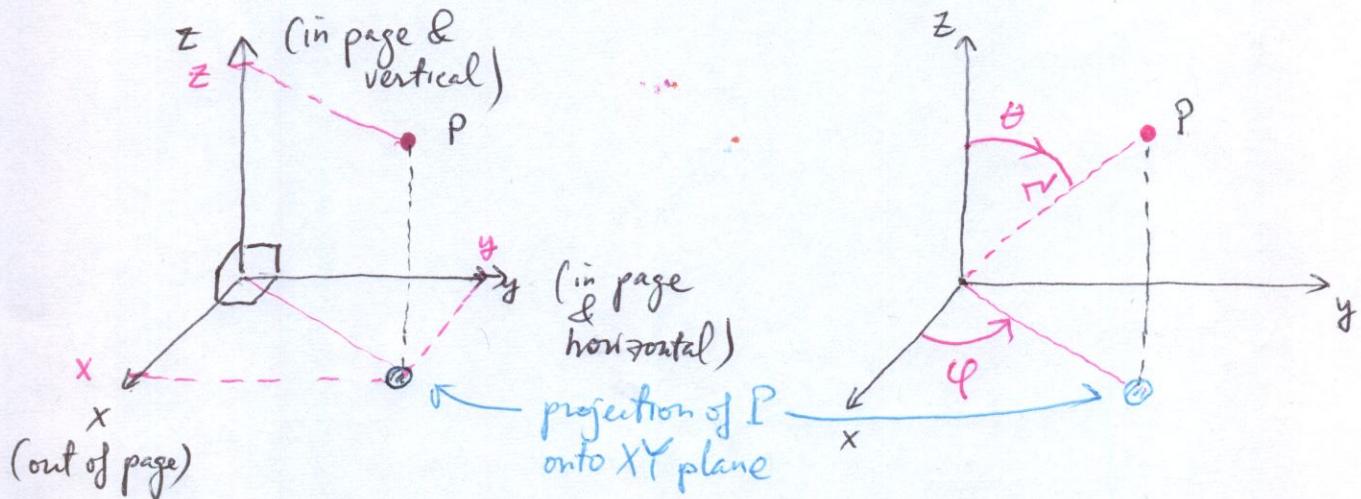
3D

Cartesian

$$\vec{r} = (x, y, z)$$

Spherical

$$\vec{r} = (r, \theta, \varphi)$$



Note: all 3 axes are perpendicular to each other