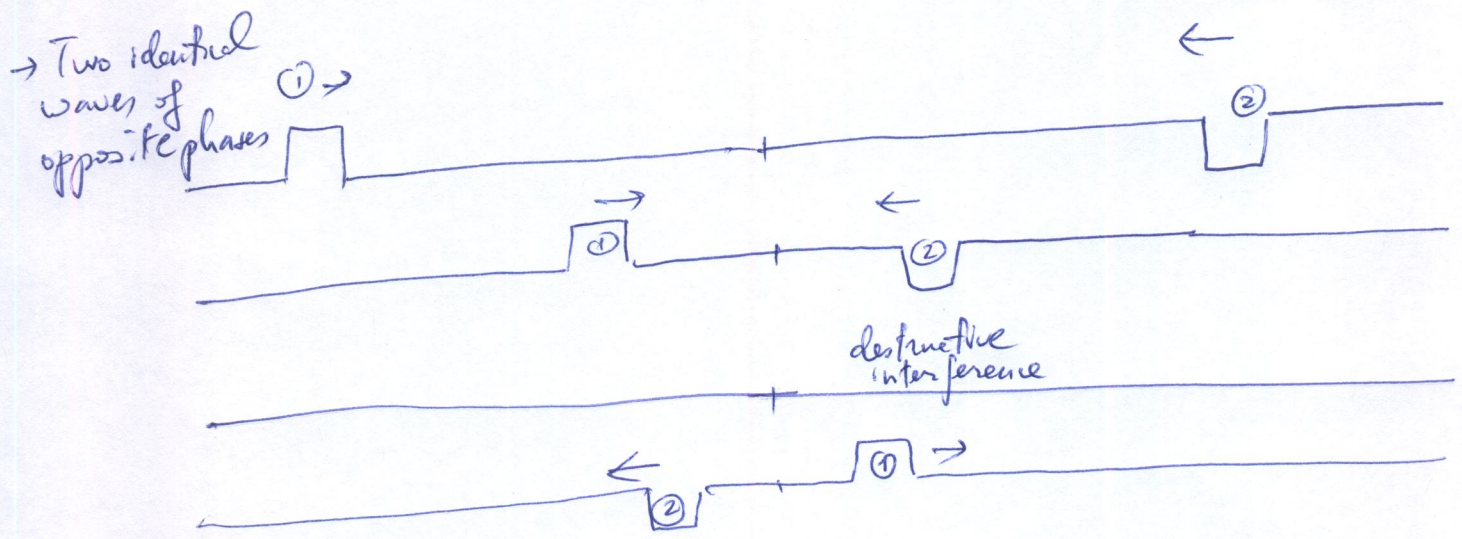
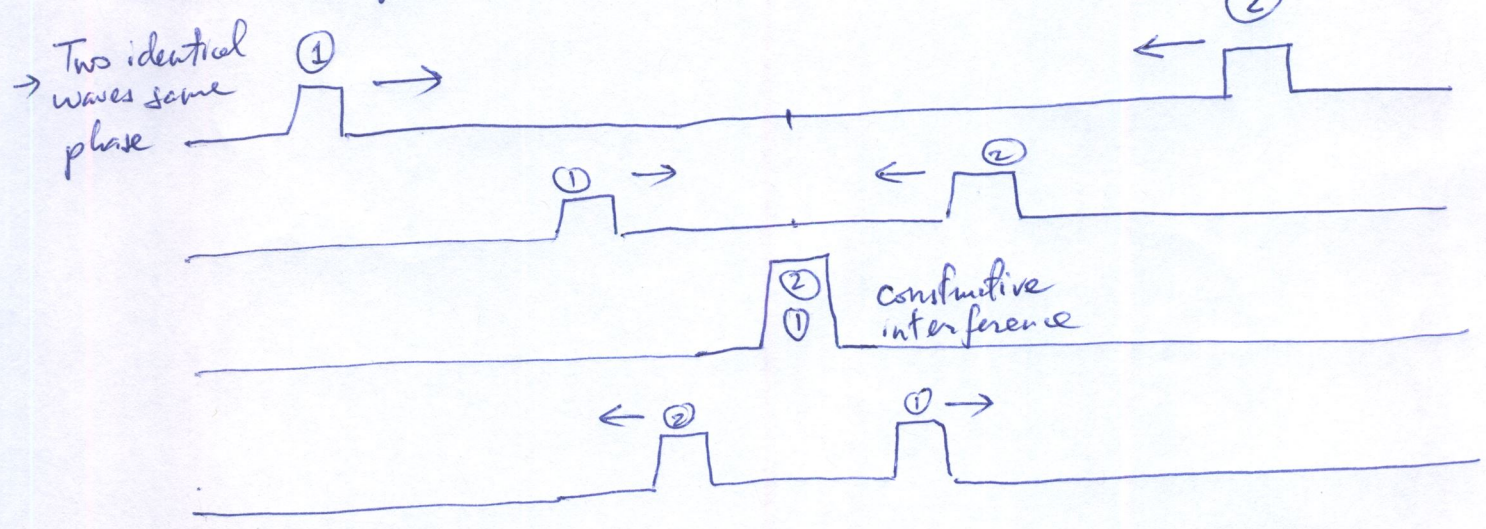


Wave Superposition →

- 1) Beats : tuning of string instruments; engines etc.
- 2) Standing waves : pipes, flutes, etc.
- 3) Wave interference : { constructive
destructive

Doppler effect : speed measurement

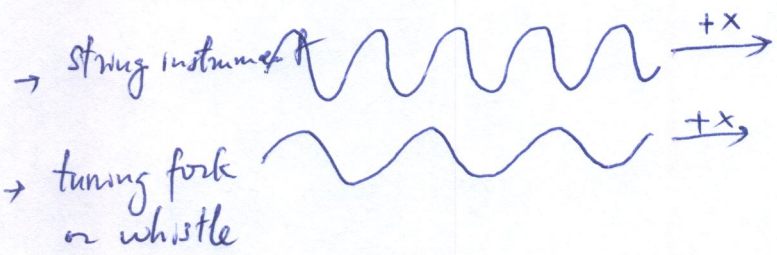
Wave superposition :



* Energy is conserved, where does it go when at the instant waves 1 & 2 cancel each other? (To the medium)

1) Math description of wave superposition: \rightarrow Beat phenomenon

Two transverse waves ^{with} ~~of~~ the same amplitude but different frequencies ω_1 & ω_2 traveling toward each other in the same direction:



$$y_1(x,t) = A \sin(k_1 x - \omega_1 t)$$

$$y_2(x,t) = A \sin(k_2 x - \omega_2 t)$$

Superposition of these two waves @ a fixed location $x=0$ (our ear): $y(0,t) = y_1(0,t) + y_2(0,t)$

$$= -A [\sin(\omega_1 t) + \sin(\omega_2 t)]$$

Trigonometry: $\sin \alpha + \sin \beta = 2 \sin\left(\frac{\alpha+\beta}{2}\right) \sin\left(\frac{\alpha-\beta}{2}\right)$

$$= -2A \left[\sin\left(\frac{\omega_1 - \omega_2}{2} t\right) \sin\left(\frac{\omega_1 + \omega_2}{2} t\right) \right]$$

Modulated amplitude

average of the two frequencies

small frequency (if $\omega_1 \sim \omega_2$)

slowly varying amplitude.

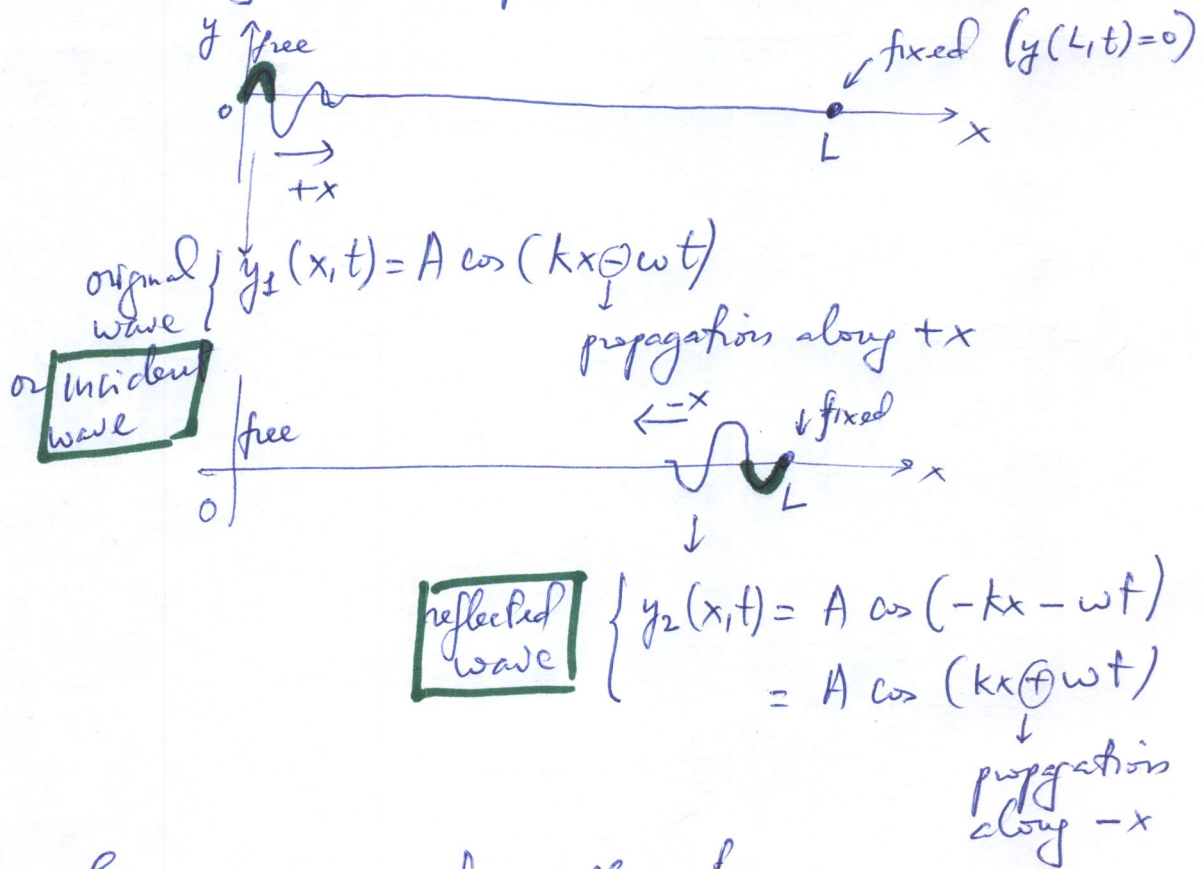
Beat.



Beats can be easily noticed as they are slowly varying.

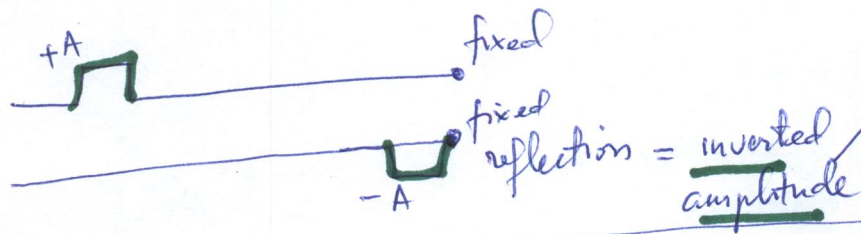
2) Wave superposition: a wave in +x & its reflection in -x
 → Standing Waves

pipes, flutes, string with one fixed end (zero oscillation there)



When both y_1 & y_2 are present in the string:

$$y(x,t) = y_1(x,t) + y_2(x,t) = A \cos(kx - \omega t) + A \cos(kx + \omega t)$$



Trigonometry: $\cos \alpha - \cos \beta = -2 \sin \left(\frac{\alpha + \beta}{2} \right) \sin \left(\frac{\alpha - \beta}{2} \right)$

$$y(x,t) = -2A \sin(kx) \cdot \sin(-\omega t) = 2A \sin(kx) \sin \omega t$$

superposition of incident + reflected waves

Fixed end @ $x=L \Rightarrow y(L,t) = 0 = 2A \sin kL \sin \omega t$

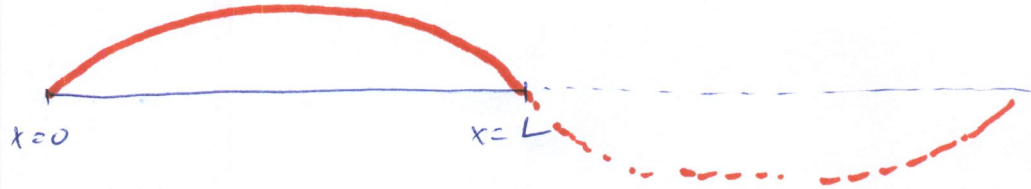
$\sin(kL) = 0 \Rightarrow \boxed{KL = n\pi \quad (n=1, 2, 3, \dots)}$ Standing Waves

$$k \cdot L = n\pi \quad (n=1, 2, 3, \text{etc.})$$

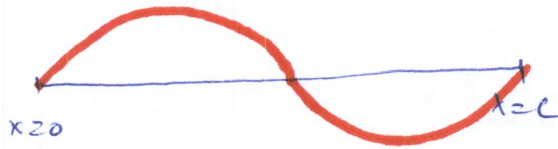
$$\frac{2\pi}{\lambda} \cdot L = n\pi \Rightarrow \lambda = \frac{2L}{n} \Rightarrow \lambda_n = \frac{2L}{n} = \left\{ \begin{array}{l} \lambda_1 = 2L \\ \lambda_2 = L \\ \lambda_3 = \frac{2L}{3} \\ \lambda_4 = \frac{L}{2} \\ \text{etc.} \end{array} \right.$$

String with fixed end @ $x=L$

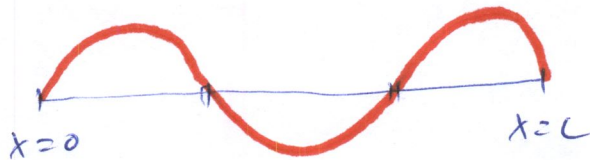
$$\lambda_1 = 2L:$$



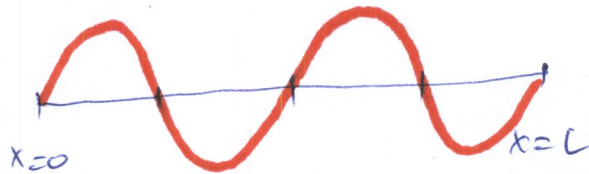
$$\lambda_2 = L$$



$$\lambda_3 = \frac{2L}{3}$$

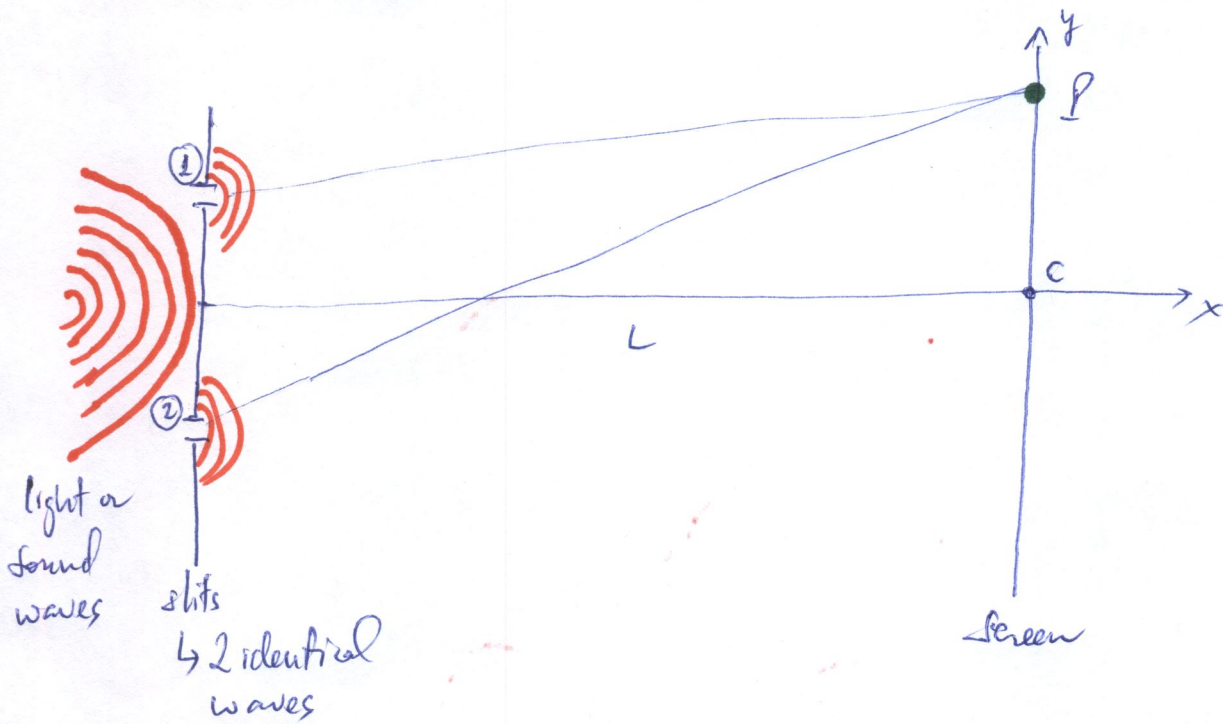


$$\lambda_4 = \frac{L}{2}$$



As λ decreases, the # oscillations in the standing waves increases

3) Superposition of two identical waves traveling different paths then arriving at a same point in space \rightarrow Wave interference



Waves ① & ② are identical at the slits, travel different paths to P
 \rightarrow arrive at P with different phases (they will arrive @ C with same phases!)

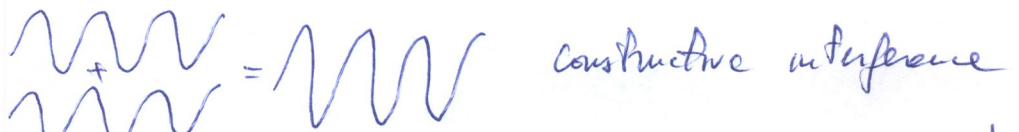
\rightarrow @ C



\rightarrow @ P

a) Phase difference is a multiple of the wavelength λ :

$$\Delta \text{path} = n\lambda \quad (n=1, 2, 3, \text{etc.} \dots)$$



b) Phase difference is an odd multiple of half wavelength $\frac{\lambda}{2}$

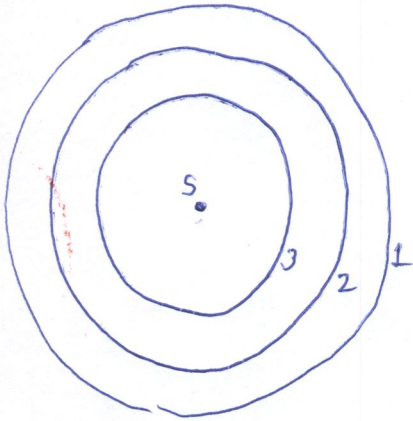
$$\Delta \text{path} = \frac{(2n+1)\lambda}{2} \quad (n=0, 1, 2, 3, \text{etc.} \dots)$$



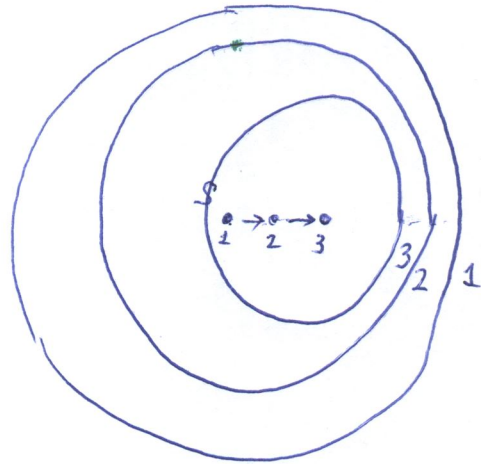
c) Phase difference some value in between.

Doppler Effect:

due to a moving source of wave



Source is @ rest
emitting waves of fronts 1, 2, 3



Source is moving to the right

- ↳ Wavefront ① centered at initial position
- ↳ Wavefront ② is centered at source position 2
- ↳ Wavefront ③ centered at source position 3

Doppler effect

Wave is { compressed in front of it (shorter λ)
spaced out behind it (longer λ)

Source is approaching

$$\lambda' = \lambda - uT$$

\downarrow \downarrow \downarrow \downarrow
 original wavelength source speed wave period

$$f' = \frac{f}{1 - \frac{u}{v}}$$

\downarrow \downarrow
 wave speed $v = \frac{\lambda}{T}$

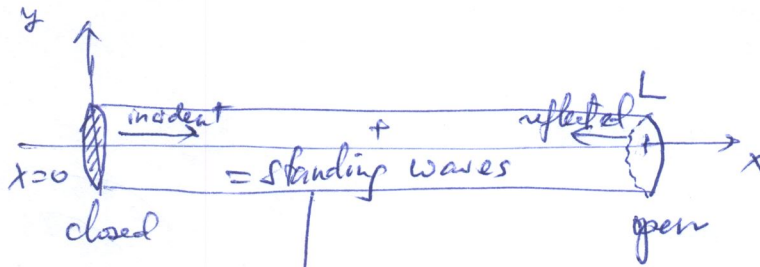
Receding source

$$\lambda' = \lambda + uT$$

$$f' = \frac{f}{1 + \frac{u}{v}}$$

14.76

Pipe $L = 1.5\text{m}$ one end open (oscillation at max amplitude there)



$$\left. \begin{aligned} f_n &= 225 \text{ Hz} \\ f_{n+1} &= 375 \text{ Hz} \end{aligned} \right\} \rightarrow f_0 \text{ or fundamental frequency}$$

Similar equation as for string with fixed end but condition at $x=L$ is max!

$$y(x,t) = 2A \sin kx \sin \omega t \xrightarrow{x=L} 2A \underbrace{\sin kL} \sin \omega t = \text{max} = \pm 2A$$

$$\Rightarrow \sin kL = \pm 1 \Rightarrow kL = \frac{\pi}{2}, \frac{3\pi}{2}, \frac{5\pi}{2}, \frac{7\pi}{2}, \text{etc.}$$

$$kL = (2n+1) \frac{\pi}{2} \quad (n=0, 1, 2, 3, \text{etc.})$$

standing waves in pipe with one open end.

$$\frac{2\pi}{\lambda} L = (2n+1) \frac{\pi}{2} \quad (n=0, 1, 2, 3, \text{etc.})$$

$$\lambda_n = \frac{4L}{2n+1} \quad (n=0, 1, 2, 3, \text{etc.})$$

Frequencies: $v = \frac{\lambda}{T} = \lambda \cdot f \Rightarrow f = \frac{v}{\lambda} \rightarrow$ wave speed.

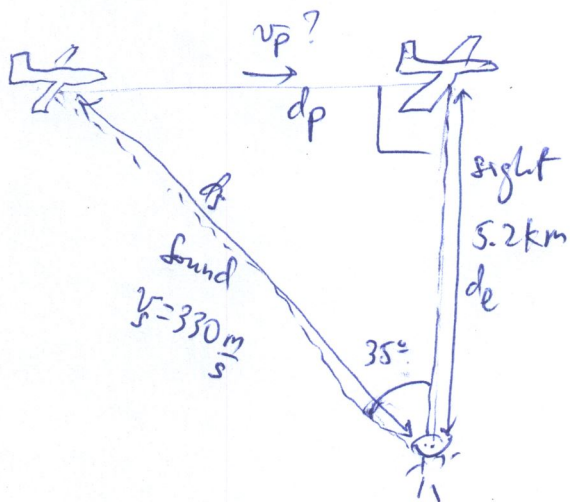
$$a) \frac{f_{n+1}}{f_n} = \frac{\frac{v}{\lambda_{n+1}}}{\frac{v}{\lambda_n}} = \frac{\lambda_n}{\lambda_{n+1}} = \frac{\frac{4L}{2n+1}}{\frac{4L}{2n+3}} = \frac{2n+3}{2n+1} = \frac{375}{225} = \frac{15}{9} = \frac{5}{3}$$

$$\frac{2n+3}{2n+1} = \frac{5}{3} \Rightarrow n=2 \Rightarrow \left\{ \begin{aligned} f_1 &= 225 \text{ Hz} \\ f_2 &= 375 \text{ Hz} \end{aligned} \right\} f_0 = ?$$

$$c) \left. \begin{aligned} f_0 &= \frac{v}{\lambda_0} = \frac{v}{4L} \\ f_1 &= \frac{v}{\frac{4L}{3}} = 3 \frac{v}{4L} = 3f_0 \end{aligned} \right\} \Rightarrow \left[f_0 = \frac{f_1}{3} = \frac{225}{3} = 75 \text{ Hz} \right]$$

$$d) \text{ find } v = \frac{4L}{3} f_1 = \frac{4 \times 1.5}{3} \cdot 225 = 450 \frac{\text{m}}{\text{s}} \rightarrow f_0 = \frac{v}{4L} = \frac{450}{4 \times 1.5} = 75 \text{ Hz.}$$

14-63

Speed of airplane $v_p?$

$$\left(\begin{aligned} \frac{d_s \cos 35^\circ}{\Delta t} &= \frac{d_e}{\Delta t} \\ v_s \cos 35^\circ &= v_e \end{aligned} \right)$$

$$\frac{d_s \sin 35^\circ}{\Delta t} = \frac{d_p}{\Delta t}$$

$$v_s \sin 35^\circ = v_p$$

$$\boxed{330 \sin 35^\circ = v_p} = 189 \frac{\text{m}}{\text{s}}$$

$$189 \frac{\text{m}}{\text{s}} \cdot \frac{1 \text{ km}}{1000} \cdot \frac{3600}{1 \text{ h}} = 189 \cdot 3.6 \frac{\text{km}}{\text{h}}$$

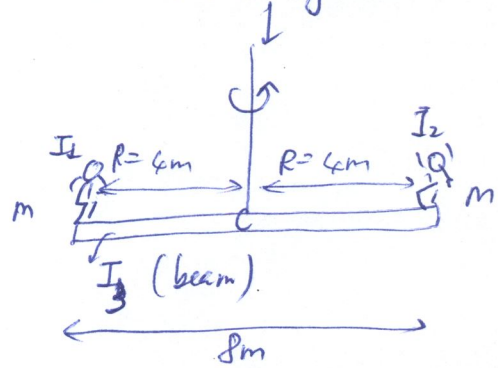
$$= \frac{189 \cdot 3.6}{1.609} \frac{\text{mi}}{\text{h}}$$

$$= 424 \frac{\text{mi}}{\text{h}}$$

$$(iii) \quad f_0 \quad f_1 \quad f_2 \quad \left\{ \begin{array}{l} f_2 - f_1 = 375 - 225 = 150 \text{ Hz} \\ f_1 - f_0 = 150 \text{ Hz} \rightarrow f_0 = \cancel{f_1} - 150 \\ \quad \quad \quad \quad \quad \quad \quad = 225 - 150 = 75 \text{ Hz} \end{array} \right.$$

13.59

Torsional pendulum: $\omega = \sqrt{\frac{K}{I}}$
 \downarrow
 wt axis of rotation



$$(no \text{ workers}) \quad \omega_0 = \sqrt{\frac{K}{I_3}}$$

$$(w/ \text{ workers}) \quad \omega = \sqrt{\frac{K}{I_3 + 2mR^2}} = 0.8 \omega_0$$

$$I_1 = I_2 = mR^2 \quad \downarrow \text{diminishes by } 20\%$$

$$I_3 = \frac{1}{12} ML^2$$

$$\sqrt{\frac{K}{\frac{1}{12} ML^2 + 2mR^2}} = 0.8 \sqrt{\frac{K}{\frac{1}{12} ML^2}} \Rightarrow \frac{\frac{1}{12} ML^2}{\frac{1}{12} ML^2 + 2mR^2} = 0.8^2$$

$$\frac{1}{12} ML^2 (1 - 0.8^2) = 2 \times 0.8^2 \cdot 75 \cdot 4^2$$

$$M = \frac{12 \times 2 \times 0.8^2 \times 75 \times 16}{8^2 (1 - 0.8^2)} \text{ kg}$$

13.60

$$2D \text{ SHM} = \begin{cases} x(t) = a \sin \omega t \\ y(t) = b \sin(\omega t + \frac{\pi}{2}) = b \cos \omega t \end{cases}$$

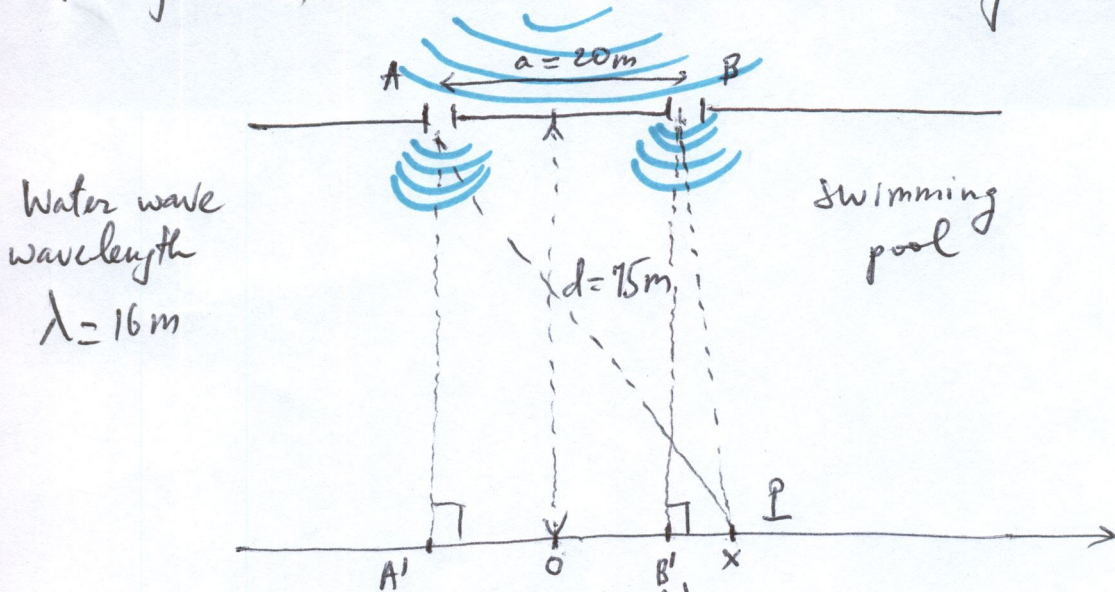
$$\vec{r} = x\hat{i} + y\hat{j} \rightarrow r^2 = x^2 + y^2 = \text{out of phase by } \frac{\pi}{2}$$

$$\left[\frac{x^2}{a^2} + \frac{y^2}{b^2} = \sin^2 \omega t + \cos^2 \omega t = 1 \right] \text{ equation of ellipse}$$

semi major / minor axes $a, b \rightarrow$ amplitude of SHM is x, y , respectively

Wave Interference:

Swimming pool with two breakwater openings on one side (water waves), separated a distance $a = 20\text{m}$. We observe water wave interference the other side at a distance $d = 75\text{m}$. Find locations of maxima (constructive interference) or minima (destructive interference).



of water waves: 2 (identical)

They combine at each point P along the other side, after traveling different paths AP & BP . If $\Delta\text{path} = AP - BP = n\lambda$ ($n = 1, 2, 3, \text{etc}$)
 @ $P \rightarrow$ constructive interference (maxima). If $\Delta\text{path} = AP - BP = (2n+1)\frac{\lambda}{2}$
 ($n = 0, 1, 2, \text{etc}$) @ $P \rightarrow$ destructive interference (minima)

Maxima: $\triangle AA'P$ is a right triangle: $AP = \sqrt{75^2 + (x+10)^2}$

$$A'P = A'O + x = 10 + x$$

$$BP = \sqrt{75^2 + (x-10)^2}$$

$\triangle BB'P$ is also a right triangle

$$B'P = x - OB' = x - 10$$

$$AP - BP = \sqrt{75^2 + (x+10)^2} - \sqrt{75^2 + (x-10)^2} = n\lambda$$

$$\text{1st max: } n=1 : \sqrt{75^2 + (x+10)^2} - \sqrt{75^2 + (x-10)^2} = \lambda = 16$$

$$\text{2nd max: } n=2$$

etc.

Get rid of $\sqrt{\quad}$; $(\sqrt{\quad} - \sqrt{\quad})^2 = 16^2 = 256$

$$256 = 75^2 + (x+10)^2 + 75^2 + (x-10)^2 - 2\sqrt{75^2 + (x+10)^2}\sqrt{75^2 + (x-10)^2}$$

$$2\sqrt{75^2 + (x+10)^2}\sqrt{75^2 + (x-10)^2} = 11250 - 256 + 2x^2 + 200 = 11194 + 2x^2$$

$$\sqrt{75^2 + (x+10)^2}\sqrt{75^2 + (x-10)^2} = 5597 + x^2$$

$$[75^2 + (x+10)^2][75^2 + (x-10)^2] = x^4 + 11194x + 5597^2$$

$$5625^2 + 5625[(x-10)^2 + (x+10)^2] + \frac{[(x+10)(x-10)]^2}{(x^2-100)^2} = x^4 + 11194x + 5597^2$$

$$5625^2 + 11250x^2 + 11250 \times 100 + x^4 + 10^4 - 200x^2 = x^4 + 11194x + 5597^2$$

$$11050x^2 - 11194x + \underbrace{5625^2 - 5597^2 + 11250 \times 10^2 + 10^4}_{1449216} = 0$$

$$x = \frac{11194 \pm \sqrt{11194^2 - 4 \times 11050 \times 1449216}}{2 \times 11050}$$

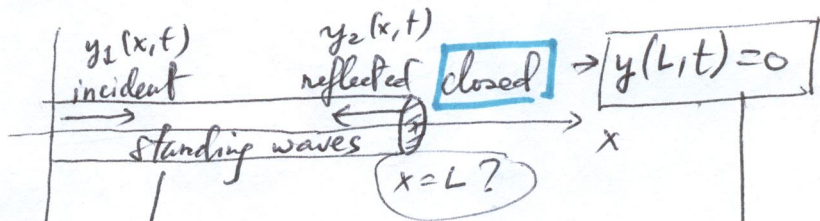
$$x = \pm 33 \text{ m}$$

First minima: $AP - BP = \frac{\lambda}{2}$

2nd minima: $AP - BP = \frac{3\lambda}{2}$

14.43

Vocal tract = pipe with a closed end $\begin{cases} f_0 = 620 \text{ Hz} \\ v = 354 \frac{\text{m}}{\text{s}} \end{cases}$



$$y(x,t) = \underbrace{A \cos(kx - \omega t)}_{\text{incident } y_1(x,t)} - \underbrace{A \cos(kx + \omega t)}_{\text{reflected } y_2(x,t)} = 2A \sin kx \sin \omega t$$

$$y(L,t) = 2A \sin kL \sin \omega t = 0$$

$$\rightarrow \sin(kL) = 0 \rightarrow kL = n\pi \quad (n=1, 2, 3, \text{ etc.})$$

$$\frac{2\pi}{\lambda_n} L = n\pi \rightarrow \boxed{\lambda_n = \frac{2L}{n}} \quad (n=1, 2, 3, \text{ etc.})$$

$$v = \frac{\lambda}{T} = \lambda f \rightarrow \begin{cases} \text{lowest freq} = 620 \text{ Hz} = f \\ \text{longest wave length} = 2L = \lambda \end{cases}$$

$$v = 2L \cdot f$$

$$354 = 2L \cdot 620 \rightarrow L = \frac{354}{2 \cdot 620} \text{ m} = 0.29 \text{ m}$$

14.54

Laser beam projection:

beam intensity $I = \frac{P}{\text{Area}}$ (power per unit area)

laser

$$P = 5 \text{ mW}$$

$$d_1 = 0.1 \text{ cm (laser opening)}$$

$$I_1 ?$$

$$I_1 = \frac{5 \times 10^{-3}}{\pi \times (0.05 \times 10^{-2})^2} = 6.37 \frac{\text{kW}}{\text{m}^2}$$

$$d_2 = 3.6 \text{ cm (wall)}$$

$$I_2 ?$$

$$I_2 = \frac{5 \times 10^{-3}}{\pi \times (1.8 \times 10^{-2})^2} = 4.91 \times 10^{-3} \frac{\text{kW}}{\text{m}^2}$$

(more than 1000 times lower)

Ch 15 Fluid Motion:

Gas: density ρ (ρ_{ho}) can be variable (compressible)
Liquid: density ρ is constant (incompressible)

Density ρ : mass per unit volume = $\frac{M}{\text{vol}} \rightarrow \frac{dM}{dV} \left(\frac{\text{kg}}{\text{m}^3} \right)$
($\rho_{\text{liquid}} > \rho_{\text{gas}}$) $\rho_{\text{H}_2\text{O}} = 1000 \frac{\text{kg}}{\text{m}^3}$ (normal conditions)
 $\rho_{\text{air}} \approx 1 \frac{\text{kg}}{\text{m}^3}$

Pressure P = normal force per unit area = $\frac{F}{\text{Area}} \rightarrow \frac{dF}{d\text{Area}} \left(\frac{\text{N}}{\text{m}^2} \right)$

$$\left\{ \begin{array}{l} \frac{\text{N}}{\text{m}^2} = \text{Pa (Pascal)} \\ \text{Atm (Atmosphere)} \rightarrow 1 \text{Atm} = 1.013 \times 10^5 \text{ Pa} \end{array} \right.$$

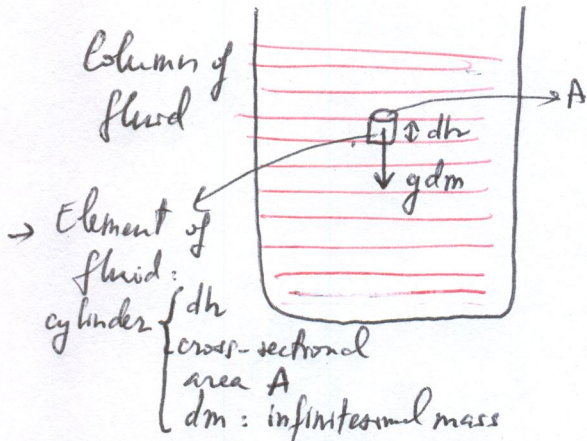
- Fluid motion equations
- 1) Hydrostatic equilibrium: $\boxed{\frac{dP}{dh} = \rho g}$
 $g = 9.81 \frac{\text{m}}{\text{s}^2}$; ρ (ρ_{ho}) density of fluid
 P pressure; h = height.
 \rightarrow slope of $P(h)$ is a constant or P varies linearly with height \rightarrow pressure increases linearly with depth of fluid.
 - 2) Conservation of mass: $v \cdot \text{Area} = \text{constant}$
(v : speed of fluid; Area: cross sectional area)
 - 3) Conservation of energy: Bernoulli's eq.
 $\frac{1}{2} \rho v^2 + \rho g y + P = \text{constant}$

Fluid Motion Equations

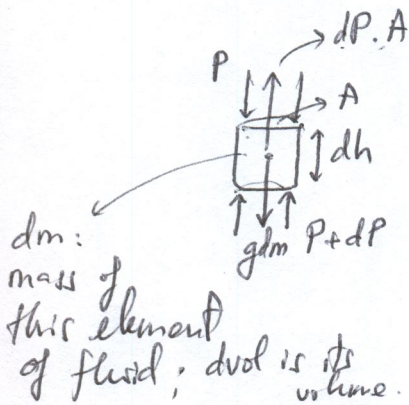
1) Hydrostatic equilibrium:

$$\frac{dP}{dh} = \rho g \quad \left(P \text{ varies linearly with height/depth} \right)$$

Why? → From 2nd Newton's Law



- The infinitesimal element of fluid (dh, A, dm) feels its weight of gdm
- When this column of fluid is in equilibrium
- tiny element of fluid is static → what is holding it up? → buoyant force
- Origin of buoyant force: density of fluid varies with height ↔ high pressure at bottom & low pressure at top → even for our tiny cylinder of fluid!



$$F_{net} = 0 \quad (\text{static equilibrium})$$

$$\underbrace{(P + dP)A - P \cdot A - dm \cdot g}_0 = 0$$

$$dP \cdot A - dm \cdot g = 0$$

$$dP \cdot A = dm \cdot g$$

$$dP \cdot A = \rho \cdot A \cdot dh \cdot g$$

$$\boxed{\frac{dP}{dh} = \rho \cdot g}$$

Pressure increases linearly with h (height or depth) being the slope: $\rho \cdot g$ for gas & liquid.

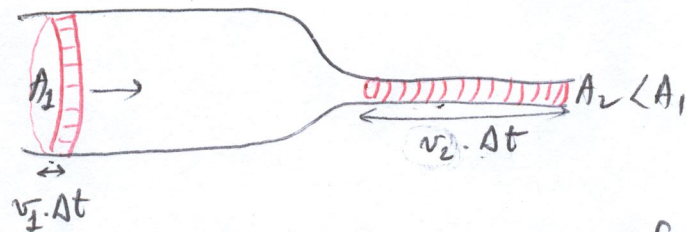
→ Since $\rho_{liquid} \sim 10^3 \rho_{gas}$ → scuba diving requires proper training to withhold ~~the~~ steep change of pressure

$\rho = \frac{dm}{dvol} = \frac{dm}{A \cdot dh} \rightarrow dm = \rho \cdot A \cdot dh$

ρ (density)

2) Conservation of mass: no leaking of fluid

Fluid moving in a pipe with different cross-sectional areas:



If fluid motion is continuous (no traffic bottle neck effect) fluid necessarily moves at higher speed v_2 at smaller cross-sectional area:

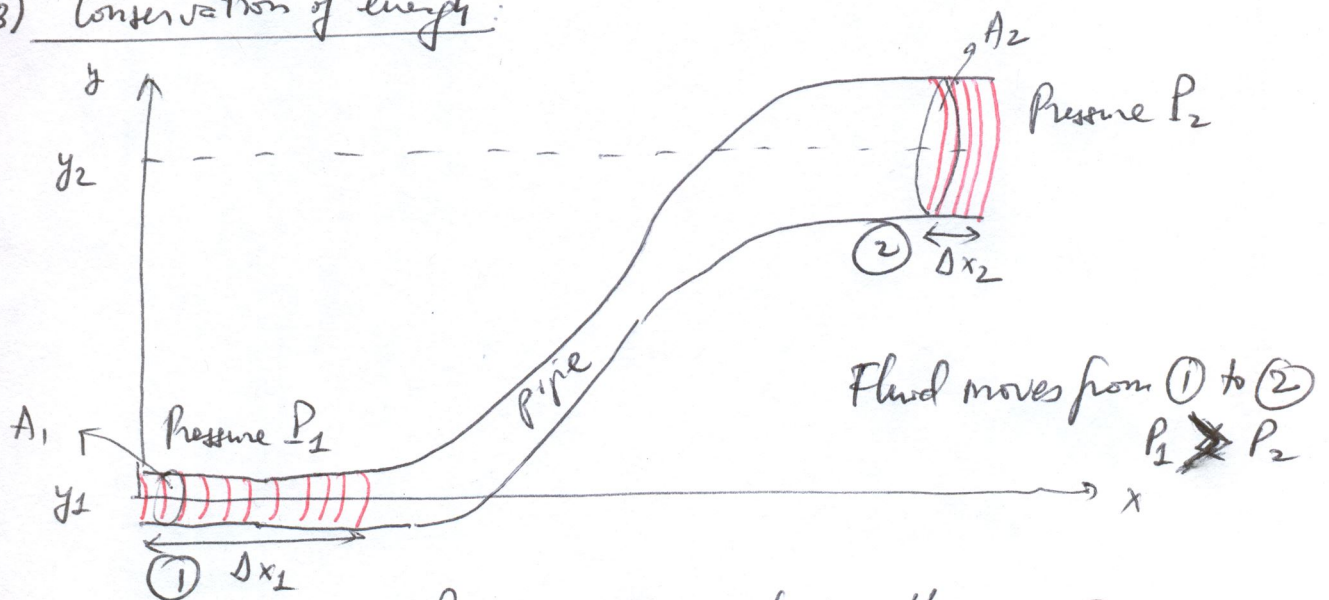
$$m_1 = \rho V_1 = \rho \cdot v_1 \cdot \Delta t \cdot A_1 = m_2 = \rho V_2 = \rho \cdot v_2 \cdot \Delta t \cdot A_2$$

$$\rho v_1 \Delta t A_1 = \rho v_2 \Delta t A_2 \Rightarrow v_1 A_1 = v_2 A_2$$

$$\text{or } \boxed{v \cdot A = \text{constant}}$$

(in traffic v is constant \rightarrow bottleneck effect!)
even if a lane is blocked

3) Conservation of energy:



Pressure @ ① is higher than @ ② \rightarrow
Work done to push fluid from ① \rightarrow ②.
by pressure

$$\Delta W = \Delta KE + \Delta PE$$

$$\Delta W = P_1 A_1 \cdot \Delta x_1 - P_2 A_2 \cdot \Delta x_2 = \frac{1}{2} m v_2^2 - \frac{1}{2} m v_1^2 + m g y_2 - m g y_1$$

$$W = F \cdot d$$

Conservation of energy.

$$\frac{1}{2} m v_1^2 + m g y_1 + P_1 A_1 \Delta x_1 = \frac{1}{2} m v_2^2 + m g y_2 + P_2 A_2 \Delta x_2$$

$$\Rightarrow \left[\frac{1}{2} m v^2 + m g y + P A \Delta x = \text{constant} \right] \times \frac{1}{\text{vol}} = \frac{1}{A \cdot \Delta x}$$

$$\boxed{\frac{1}{2} \rho v^2 + \rho g y + P = \text{constant}} \quad \text{Bernoulli's eq.}$$

$$\frac{m}{\text{vol}} = \rho$$

ch 10: Rotational Motion & Conservation of Angular Momentum
 & ch 11

1) New quantities involving cross product

$$\left\{ \begin{array}{l} \vec{\tau} = \vec{r} \times \vec{F} \\ \vec{L} = \vec{r} \times \vec{p} \\ = I \cdot \vec{\omega} \end{array} \right\} \begin{array}{l} \text{should defined center of rotation} \\ \text{or pivot} \\ \text{general} \\ \text{for rotations} \end{array}$$

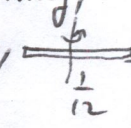
2) RHR to find direction for $\vec{\tau}$ & \vec{L}

3) Analog of Newton's 2nd Law

$$\left\{ \begin{array}{l} \vec{F}_{\text{net}} = m \cdot \vec{a} \\ \vec{\tau}_{\text{net}} = I \cdot \vec{\alpha} \quad (I = c m R^2) \end{array} \right.$$

Most general versions:

$$\left\{ \begin{array}{l} \vec{F}_{\text{net}} = \frac{d\vec{p}}{dt} = 0 \rightarrow \vec{p}_i = \vec{p}_f \\ \vec{\tau}_{\text{net}} = \frac{d\vec{L}}{dt} = 0 \rightarrow \vec{L}_i = \vec{L}_f \end{array} \right.$$

$\uparrow \frac{1}{2}$ disk, ring, sphere, 
 $\frac{2}{5}$ $\frac{1}{2}$

ch 12: Static Equilibrium:

$$\left\{ \begin{array}{l} \sum_i \vec{F}_i = 0 \\ \sum_i \vec{\tau}_i = 0 \end{array} \right. \rightarrow \text{(with a selection of pivot among the force application points)}$$

$\rightarrow \vec{\tau} = \vec{r} \times \vec{F} = r F \sin \theta (\hat{e})$ RHR

\downarrow
 from pivot to where \vec{F} is applied
 θ angle b/w \vec{r} & \vec{F}
 \hat{e} direction of $\vec{\tau}$, given RHR

ch 13: SHM $\rightarrow \frac{d^2 z}{dt^2} = -\frac{a}{b} z \Rightarrow z(t) = A \cos \omega t, \omega = \sqrt{\frac{a}{b}}$

pendulum	a	g	L	ω	$\sqrt{\frac{g}{L}}$
torsional pendulum	K	I	I	ω	$\sqrt{\frac{K}{I}}$
spring-mass	k	m	m	ω	$\sqrt{\frac{k}{m}}$

\Leftrightarrow Total energy stays constant

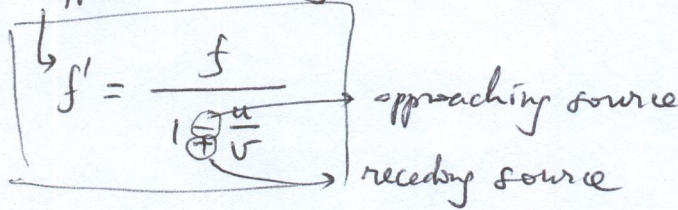
$$\frac{1}{2} m v^2 + \frac{1}{2} k x^2 = \frac{1}{2} k A^2$$

Ch 14: Wave Motion

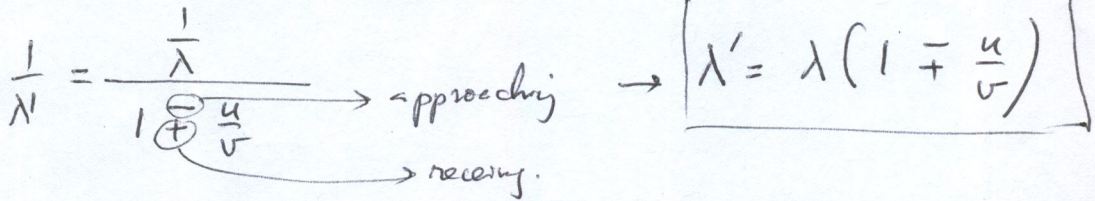
Wave superposition

- Beats: 2 waves, same direction & A, different k 's & ω 's
 $y_T(x,t) = -2A \cos\left(\frac{\omega_1 - \omega_2}{2}t\right) \sin\left(\frac{\omega_1 + \omega_2}{2}t\right)$
 low freq \rightarrow Beats
- Standing waves: 2 waves, incident + reflected going in opposite directions (same A, k, ω)
 $y_T(x,t) = 2A \sin kx \sin \omega t$
 - Fixed @ $x=L$: $\sin kL = 0 \rightarrow kL = n\pi$ ($n=1, 2, 3, \text{etc.}$)
 - Open @ $x=L$: $\sin kL = 1 \rightarrow kL = (2n+1)\frac{\pi}{2}$ ($n=0, 1, 2, 3, \text{etc.}$)
- Interference: $\Delta \text{path} = n\lambda$ ($n=0, 1, 2, 3, \text{etc.}$)
 Constructive/Destructive
 $\Delta \text{path} = (2n+1)\frac{\lambda}{2}$ ($n=0, 1, 2, 3, \text{etc.}$)

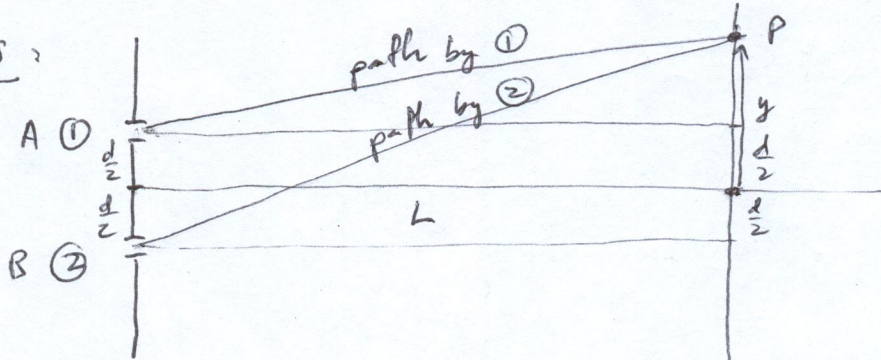
Doppler effect: moving source



$$v = \lambda \cdot f \rightarrow \lambda = \frac{v}{f} \rightarrow f = \frac{v}{\lambda}$$



Two slits:



1st Maxima $\Delta \text{path} = BP - AP = \sqrt{L^2 + \left(y + \frac{d}{2}\right)^2} - \sqrt{L^2 + \left(y - \frac{d}{2}\right)^2} = \lambda$ (1st max.)
 $= 2\lambda$ (2nd max.)

Minima: $\Delta \text{path} = BP - AP = \sqrt{L^2 + \left(y + \frac{d}{2}\right)^2} - \sqrt{L^2 + \left(y - \frac{d}{2}\right)^2} = \frac{\lambda}{2}$ (1st min.)
 $= \frac{3\lambda}{2}$ (2nd min.)
 $= \frac{5\lambda}{2}$ (3rd min.)

Ch 15 Fluid Motion

3 equations

→ Hydrostatic equilibrium ↔ buoyancy

$$\frac{dP}{dh} = \rho g \quad \text{or} \quad F_b = \rho g h \cdot \text{Area}$$

↓
vol. of fluid displaced
↓
displaced fluid density

→ Conservation of mass of fluid → $v \cdot \text{Area} = \text{constant}$

↓
speed of fluid
↓
cross-sectional area

→ Conservation of energy or Bernoulli's eq:

$$\frac{1}{2} \rho v^2 + \rho g h + P = \text{constant}$$

$$\frac{1}{2} \rho v_i^2 + \rho g h_i + P_i = \frac{1}{2} \rho v_f^2 + \rho g h_f + P_f$$