

Ch1 Doing Physics

Dimensional Analysis:

Speed: $[v] = \frac{[\Delta s]}{[\Delta t]} = \frac{L}{T}$ } "Dimension of speed is length over time"

"dimension of speed"

Δs "increment of space" or distance : $[\Delta s] = L$ (length)
 "delta s"

Δt "increment of time" or travel time $[\Delta t] = T$ (time)

Acceleration: $[a] = \frac{[\Delta v]}{[\Delta t]} = \frac{\frac{L}{T}}{T} = \frac{L}{T^2}$

Energy → Kinetic energy : $[K.E] = [\frac{1}{2}mv^2] = [\frac{1}{2}] \cdot [m] \cdot [v]^2$
 $= 1 \cdot M \cdot \frac{L^2}{T^2} = M \frac{L^2}{T^2}$

Application: which of the following two formulas for speed is correct?

$v_1 = \frac{1}{2}gh^2 \rightarrow [v_1] = [g][h]^2 = \frac{L}{T^2} \cdot L^2 = \frac{L^3}{T^2}$ (not a speed!)

$v_2 = \sqrt{gh} \rightarrow [v_2] = [g]^{\frac{1}{2}} \cdot [h]^{\frac{1}{2}} = ([g] \cdot [h])^{\frac{1}{2}} = (\frac{L}{T^2} \cdot L)^{\frac{1}{2}} = (\frac{L^2}{T^2})^{\frac{1}{2}} = \frac{L}{T} \checkmark$

g = acceleration of gravity
 h = height or vertical position

Limitation: $v_3 = \frac{1}{2}\sqrt{gh}$: $[v_3] = \frac{L}{T} \rightarrow$ Dimensional analysis can't determine the constant.

Units : { SI : international system
British :

<u>Quant. ty / Dimension</u>	<u>SI unit</u>
L	m (meter)
T	s (second)
M	kg (kilogram)
Area	m ²
Volume	m ³
Energy	$\frac{\text{kg} \cdot \text{m}^2}{\text{s}^2} = \text{J (Joule)}$

Conversions :

Other	"micro"						light-year	1 mi	1 ft	in
	nm	μm	mm	cm	km					
SI	10 ⁻⁹ m	10 ⁻⁶ m	10 ⁻³ m	10 ⁻² m	10 ³ m	9.46 × 10 ¹⁵ m	1609 m	0.3048 m	2.54 cm	

1 lb = 0.454 kg

1 min = 60s ; 1 hr = 3600s ; 1 day = 86400s ; etc..

1 km² = (10³ m)² = 10⁶ m²

1 cm² = (10⁻² m)² = 10⁻⁴ m²

1 mm² = 10⁻⁶ m²

1 km³ = (10³ m)³ = 10⁹ m³

1 cm³ = (10⁻² m)³ = 10⁻⁶ m³

1 mm³ = 10⁻⁹ m³

1 km³ = 10¹⁸ mm³

1 mm³ = 10⁻¹⁸ km³

Accuracy & Significant Figures:

- Scientific Notation: uses powers of 10

$$\Delta s = 6\,176\,000\text{ m} = 6.176 \times 10^6\text{ m} = \underbrace{6.176}_{\substack{\text{Coefficient} \\ (<10)}} E6\text{ m}$$

$$\Delta t = 3000\text{ s} = 3E3\text{ s}$$

$$\text{speed} = \frac{\Delta s}{\Delta t} = \frac{6.176 \times 10^6}{3 \times 10^3} = \frac{6.176}{3} \times 10^{6-3} = 2.059 \times 10^3 \frac{\text{m}}{\text{s}}$$

$$= 2.059 E3 \frac{\text{m}}{\text{s}}$$

- Accuracy: (addition & subtraction)

$$\pi - 1.14 = 3.1416 - 1.14$$

(assume π is 3.1416)

$$\left. \begin{array}{l} 2.0016 \\ 2.00 \checkmark \end{array} \right\}$$

best accuracy is limited by the least accurate quantity in the equation.

- Significant figures (s.f.'s) (multiplication & division).

$$\underline{6\,370\,000\text{ m}}$$

3 s.f.'s

(end zeroes don't count)

$$\underline{6\,370\,001\text{ m}}$$

7 s.f.'s

(middle zeroes do count)

$$\text{Circumference of Earth: } 2\pi R_E = 2 \times 3.1416 \times (6.37 \times 10^6)$$

$$R_E = 6.37 E6\text{ m}$$

$$= 4.002398 \times 10^7\text{ m}$$

$$= 4.00 \times 10^7\text{ m}$$

least # of s.f.'s →
is 3

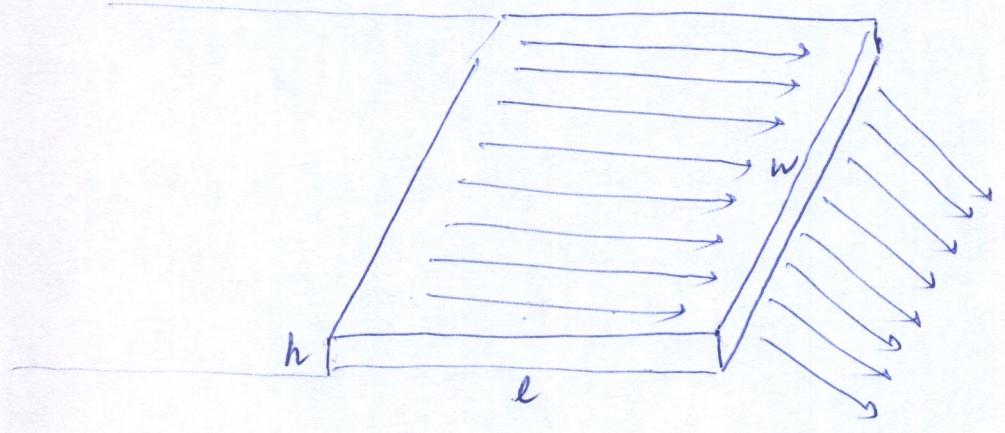
1.41

a) Estimate volume of water going over Niagara Falls in 1s. (m³)

Guesses: } 3E6 $\frac{m^3}{s}$

Estimation: simple geometrical shape

top level: rectangular slab $h \times l \times w = \text{Volume}$



Volume per second or flow rate = $\frac{\text{volume}}{t} = \frac{h l w}{t}$
 { 1) $\frac{h}{t} l w$
 2) $\frac{l}{t} h w$
 3) $\frac{w}{t} h l$

Estimation
 { $\frac{l}{t}$: speed of water : 1 $\frac{m}{s}$, 10 $\frac{m}{s}$, 100 $\frac{m}{s}$
 h : slab thickness : 1m, 10m, 100m
 w : : 100m, 1000m, 10000m

Flow rate: $\frac{l}{t} \cdot h \cdot w = 10 \frac{m}{s} \cdot 1m \cdot 1000m = \frac{10,000 m^3}{s}$

b)

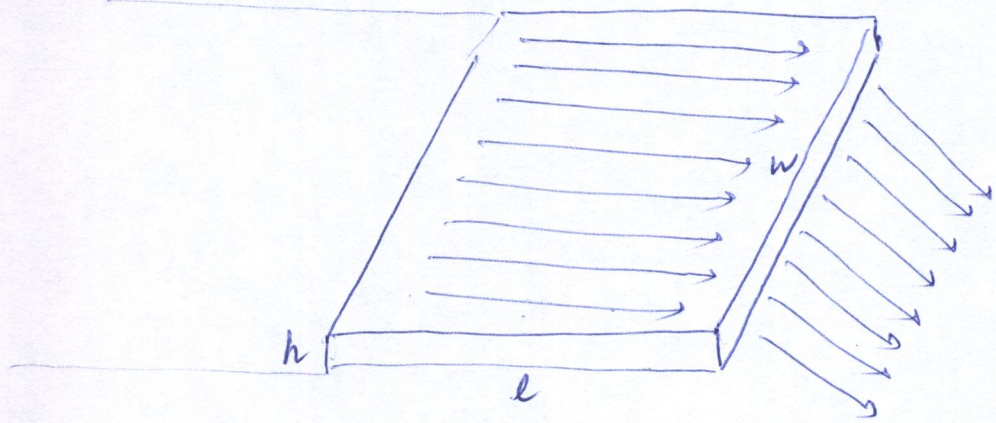
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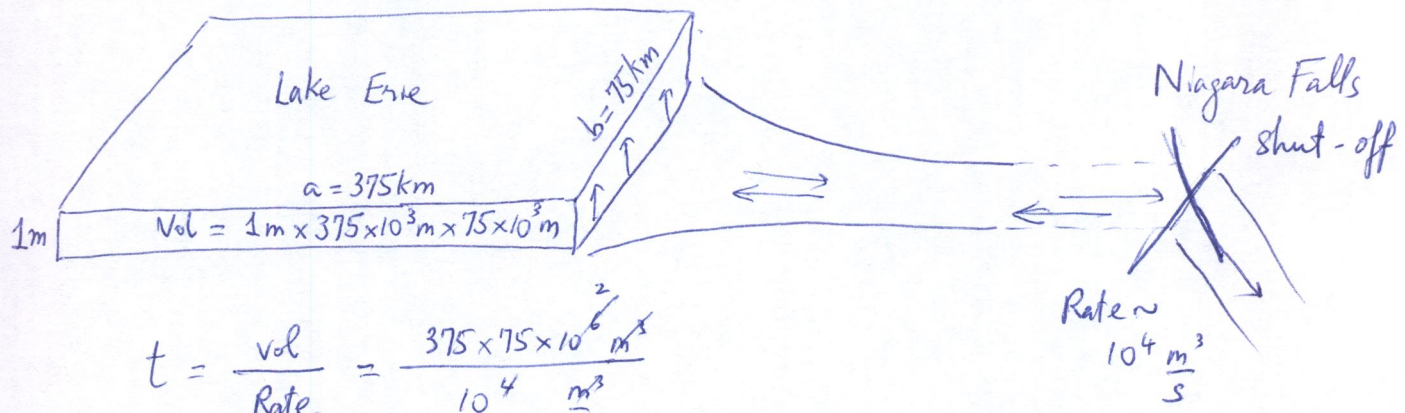
$\left\{ \begin{array}{l} 1) \frac{h}{t} l w \\ 2) \left(\frac{l}{t}\right) h w \\ 3) \frac{w}{t} h l \end{array} \right.$

Estimation $\left\{ \begin{array}{l} \frac{l}{t} = \text{speed of water} : 1 \frac{m}{s}, 10 \frac{m}{s}, 100 \frac{m}{s} \\ h = \text{slab thickness} : 1m, 10m, 100m \\ w : 100m, 1000m, 10000m \end{array} \right.$

Flow rate: $\frac{l}{t} \cdot h \cdot w = 10 \frac{m}{s} \cdot 1m \cdot 1000m = \frac{10,000 m^3}{s}$

b)

b) If Niagara Falls are shut-off, water level at Lake Erie will rise, how long does it take to rise 1m?



$$t = \frac{\text{vol}}{\text{Rate}} = \frac{375 \times 75 \times 10^6 \text{ m}^3}{10^4 \frac{\text{m}^3}{\text{s}}}$$

$$= 28125 \times 10^2 \text{ s} \cdot \frac{1 \text{ day}}{86400 \text{ s}} = 32.6 \text{ days}$$

$\approx 1 \text{ month}$

ch 2 Motion in a Straight Line (horizontal or vertical) ⑥

Average Motion = average velocity & average acceleration.

$$\begin{aligned} \text{Speed } \left(\frac{m}{s}\right) \\ = \frac{\text{distance}}{\text{time}} \end{aligned}$$

$$\begin{aligned} \text{Velocity } v \left(\frac{m}{s}\right) \\ = \frac{\text{displacement}}{\text{time}} \end{aligned}$$

$$= \frac{600ft}{6min} = 100 \frac{ft}{min}$$

$$= \frac{400ft}{6min} = 66.67 \frac{ft}{min}$$

velocity is lower than speed because direction of motion counts

Average velocity: $\bar{v} = \frac{\Delta x}{\Delta t}$
↓
($\frac{m}{s}$)

Δx : increment or change of position x or displacement
 Δt : increment of time or time

Instantaneous velocity: $v = \lim_{\Delta t \rightarrow 0} \frac{\Delta x}{\Delta t} = \frac{dx}{dt}$ ("time derivative of position")

Example: $x = at^4 \rightarrow v = 4at^3$ (unit: $\frac{m}{s}$)

↓
constant

(unit: m) ← $\left(\frac{dt^n}{dt} = nt^{n-1}\right)$

Acceleration: change of velocity over time

Average acceleration ($\frac{m}{s^2}$) $\bar{a} = \frac{\Delta v}{\Delta t}$

$\left\{ \begin{array}{l} \Delta v = \text{change of velocity or increment in velocity} \\ \Delta t = \text{time} \end{array} \right.$

Instantaneous acceleration ($\frac{m}{s^2}$) $a = \lim_{\Delta t \rightarrow 0} \frac{\Delta v}{\Delta t} = \frac{dv}{dt}$

(time derivative of velocity)

Example: $x = at^4 (m) \rightarrow v = 4at^3 (\frac{m}{s}) \rightarrow a = 12at^2 (\frac{m}{s^2})$

(varies quadratically in time)

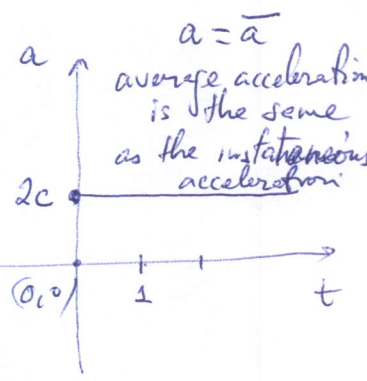
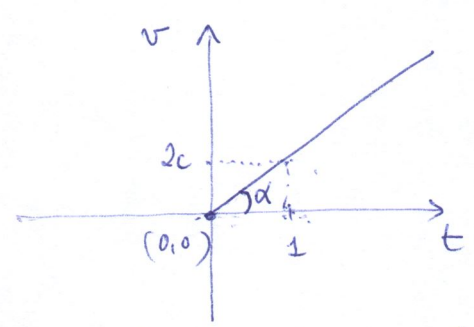
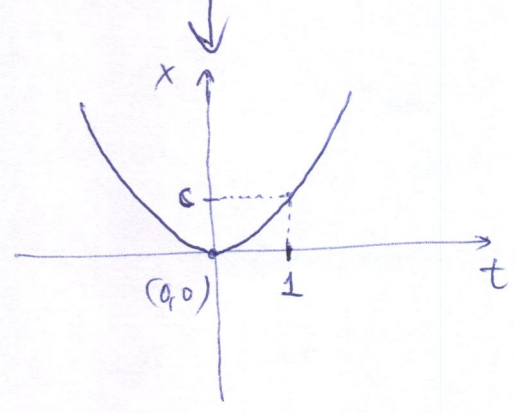
$x = ct^2 \rightarrow v = 2ct \rightarrow a = 2c (\frac{m}{s^2})$

constant acceleration

(position varies quadratically wrt. time)

$x = ct \rightarrow v = c \rightarrow a = 0$

constant velocity (uniform motion)



$\tan \alpha = \text{slope of the line} = 2c$

From these basic physics we now derive the kinematic equations to describe a constant acceleration motion in a straight line (1D).

→ Constant acceleration:

$$a = \bar{a}$$

$$a = \frac{\Delta v}{\Delta t} = \frac{v - v_0}{t - 0} \Rightarrow v - v_0 = at$$

current velocity initial velocity
 ↓ ↓
 current time initial time

→ $v = v_0 + at$ (1)

Kinematic equation # 1

Kinematic equation # 2,

$$\bar{v} = \frac{\Delta x}{\Delta t} = \frac{x - x_0}{t - 0}$$

current position initial position
 ↑ ↑

→ $x = x_0 + \bar{v} \cdot t$ (A)

$$\bar{v} = \frac{\int_0^t v \cdot dt}{t - 0} \stackrel{(1)}{=} \frac{1}{t} \int_0^t (v_0 + a \cdot t) dt$$

$$= \frac{1}{t} \left[v_0 t + \frac{1}{2} a t^2 \right]_0^t = \frac{1}{t} \left[v_0 t + \frac{1}{2} a t^2 \right]$$

$$= v_0 + \frac{1}{2} a t$$

$\int v_0 dt = v_0 \int dt = v_0 t$
$\int t dt = \frac{t^2}{2}$
$\int t^n dt = \frac{t^{n+1}}{n+1}$

$$\bar{v} = v_0 + \frac{1}{2} a \cdot t = \frac{1}{2} v_0 + \underbrace{\frac{1}{2} v_0 + \frac{1}{2} a \cdot t}_{\frac{1}{2} v} = \frac{1}{2} (v_0 + v)$$

(B)

(A) $\Rightarrow x = x_0 + \bar{v} \cdot t = x_0 + \left(\frac{v_0 + v}{2} \right) \cdot t \stackrel{(1)}{=} x_0 + \frac{1}{2}(v_0 + v_0 + a \cdot t) \cdot t$

(B) $\Rightarrow \bar{v} = \frac{v_0 + v}{2}$ \uparrow

$x = x_0 + v_0 \cdot t + \frac{1}{2} a \cdot t^2$ (2)

Kinematic eq. # 2

Summary: to describe a **constant acceleration** motion in 1D:

- 1) $v = v_0 + a \cdot t$
- 2) $x = x_0 + v_0 \cdot t + \frac{1}{2} a \cdot t^2$
- 3) $\frac{v^2 - v_0^2}{x - x_0} = 2 \cdot a$ (can be derived from 1) & 2)

\hookrightarrow No time variable \rightarrow good equation to start with in those problems where time info is not given

x_0 (m) = initial position; x (m) = current or final position
 v_0 ($\frac{m}{s}$) = initial velocity; v ($\frac{m}{s}$) = current velocity
 a ($\frac{m}{s^2}$) = constant acceleration; t (s) = time ($t_0 = 0$)
 $\bar{a} = a$

2.33

Info: or facts:

- $v_0 = 50 \frac{mi}{h}$
- "begins slowing down at constant rate" = constant acceleration
- "100 ft short of stop light" $\Rightarrow x - x_0 = 100 \text{ ft}$
- "car comes to full stop @ light" $\Rightarrow v = 0 \left(\frac{m}{s}\right)$
- $a?$

1)

$$v_0 = 50 \frac{mi}{h}$$

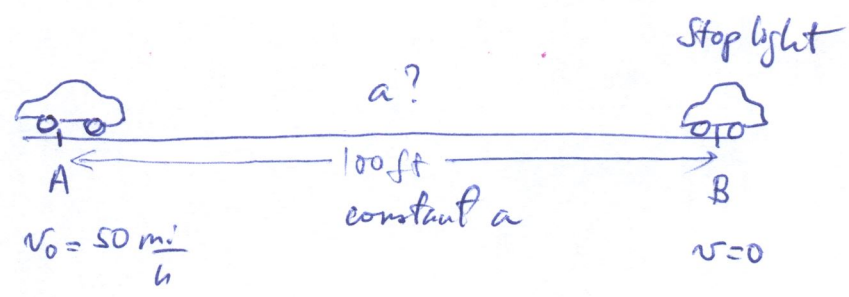
$$\text{constant } a$$

$$x - x_0 = 100 \text{ ft}$$

$$v = 0$$

$$a?$$

2) Sketch:



3) Write down appropriate equation

Kinematic eq. 3: $\frac{v^2 - v_0^2}{x - x_0} = 2 \cdot a$

Unit conversions: $v_0, x - x_0$ need to be in S.I units

$$v_0 = 50 \frac{mi}{h} \cdot \frac{1609m}{mi} \cdot \frac{1h}{3600s} = 22.35 \frac{m}{s}$$

$$x - x_0 = 100 \text{ ft} \cdot \frac{0.3048m}{1ft} = 30.48m$$

$$a = \frac{1}{2} \frac{0 - 22.35^2}{30.48m} = - 8.192 \frac{m}{s^2}$$

Negative acceleration or deceleration to come to a stop from $v_0 = 50 \frac{mi}{h}$

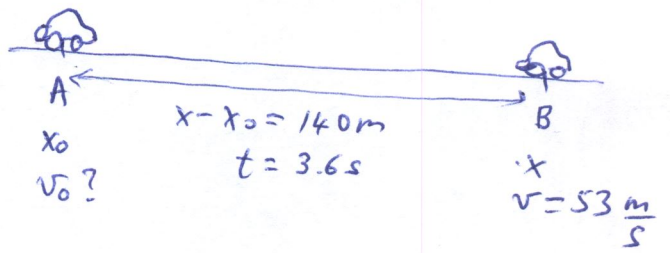
a is constant

2.59

1)

$$\begin{array}{l}
 \text{a constant} \\
 x - x_0 = 140\text{m} \\
 t = 3.6\text{s} \\
 v = 53 \frac{\text{m}}{\text{s}} \\
 v_0 ?
 \end{array}$$

2)



3) a) Alternative #1 Eliminating a from eqs 1 & 2)

Eq 1: $v = v_0 + a \cdot t \rightarrow a = \frac{v - v_0}{t}$

Eq 2: $x - x_0 = v_0 \cdot t + \frac{1}{2} a \cdot t^2 = v_0 \cdot t + \frac{1}{2} (v - v_0) \cdot t$

$$= \frac{1}{2} v_0 t + \frac{1}{2} v \cdot t$$

$$\rightarrow 2(x - x_0) = (v_0 + v) \cdot t$$

$$v_0 = \frac{2(x - x_0)}{t} - v$$

$$= \frac{2(140)}{3.6} - 53 \rightarrow \boxed{v_0 = 24.8 \frac{\text{m}}{\text{s}}}$$

Alternative #2: Find a , then find v_0

Eq 2: $x - x_0 = v_0 \cdot t + \frac{1}{2} a t^2 \rightarrow$ Need to eliminate v_0

Eq 1: $v = v_0 + a \cdot t \rightarrow v_0 = v - a \cdot t$

$$\rightarrow x - x_0 = (v - a t) \cdot t + \frac{1}{2} a t^2$$

$$= v \cdot t - \underbrace{a t^2 + \frac{1}{2} a t^2}_{-\frac{1}{2} a t^2}$$

$$\frac{1}{2} a t^2 = v \cdot t - (x - x_0)$$

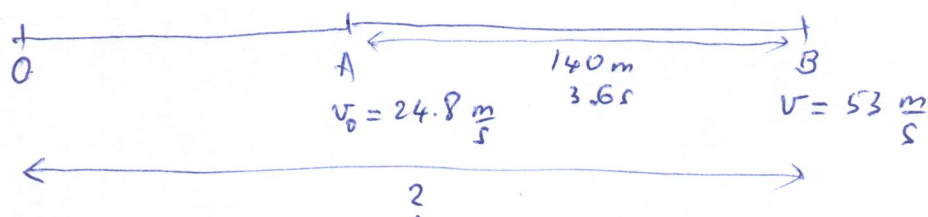
$$a = \frac{2[v \cdot t - (x - x_0)]}{t^2} = \frac{2[53 \cdot 3.6 - 140]}{3.6^2}$$

$$a = 7.83 \frac{\text{m}}{\text{s}^2}$$

$$v = v_0 + a t \rightarrow \boxed{v_0 = v - a t = 53 - 7.83 \cdot 3.6 = 24.8 \frac{\text{m}}{\text{s}}}$$

b) How far did it travel from rest till end of 140 m distance
point O point B

New sketch



Continuing w/ Alternative #1 used in part a)

$$\text{Find } OA \Rightarrow OB = OA + 140 \text{ m} = 39.4 + 140 = 179.4 \text{ m}$$

$$a = \frac{v - v_0}{t} = \frac{53 - 24.8}{3.6} = 7.83 \frac{\text{m}}{\text{s}^2}$$

$$\begin{aligned} \text{Eq 3} \rightarrow \frac{v^2 - v_0^2}{(x - x_0)_{OA}} &= 2 \cdot a \rightarrow (x - x_0)_{OA} = \frac{(v^2 - v_0^2)_{OA}}{2 \cdot a} \\ &= \frac{24.8^2 - 0}{2 \cdot 7.83} = 39.4 \text{ m} \end{aligned}$$

Continuing w/ Alternative #2 used in part a)

$$a = 7.83 \frac{\text{m}}{\text{s}^2} \quad (\text{same } a \text{ from } O \text{ to } B)$$

$$\begin{aligned} \text{Eq 3} \rightarrow \frac{(v^2 - v_0^2)_{OB}}{(x - x_0)_{OB}} &= 2 \cdot a \rightarrow (x - x_0)_{OB} = \frac{(v^2 - v_0^2)_{OB}}{2 \cdot a} \\ &= \frac{(53^2 - 0)}{2 \cdot 7.83} \\ &= 179.4 \text{ m} \end{aligned}$$

2.34/

$v = 0$ $\Delta t = 10^{-9} \text{ s}$
 $v_0 = 10^8 \frac{\text{m}}{\text{s}}$

$x - x_0 = ?$

constant acceleration \rightarrow

$$\begin{cases} 1) v = v_0 + a \cdot t \\ 2) x - x_0 = v_0 \cdot t + \frac{1}{2} a t^2 \end{cases}$$

1) $a = \frac{v - v_0}{t} = \frac{0 - 10^8}{10^{-9}} = -10^{17} \frac{\text{m}}{\text{s}^2}$

2) $x - x_0 = 10^8 \cdot 10^{-9} + \frac{1}{2} (-10^{17}) 10^{-18} = 10^{-1} - \frac{10^{-1}}{2} = 0.05 \text{ m} = 5 \text{ cm}$

2.69/

1)

3m height

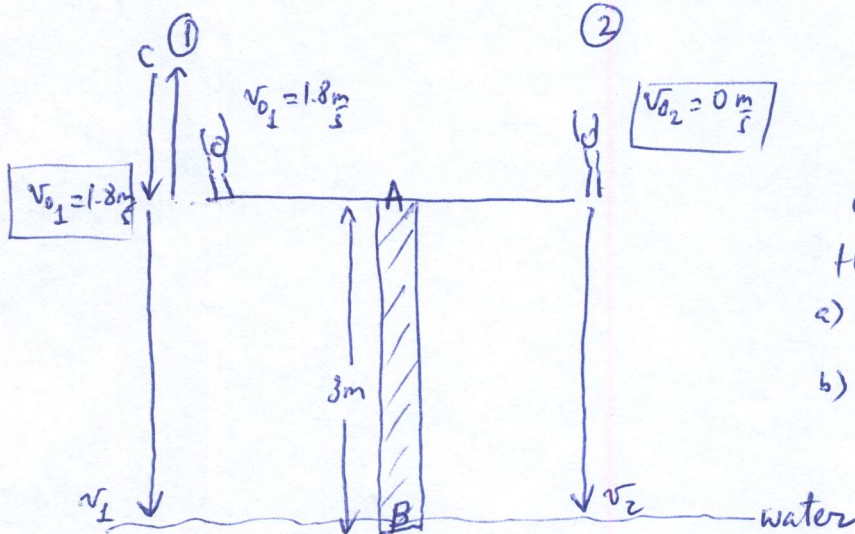
$v_{01} = 1.8 \frac{\text{m}}{\text{s}}$ (up)

$v_{02} = 0 \frac{\text{m}}{\text{s}}$ (down)

constant acceleration: $g = 9.8 \frac{\text{m}}{\text{s}^2}$

Diver 2 steps off when
 diver 1 comes back down
 by the platform.

2)



Compare motion of
 these two divers:
 a) v_1 vs v_2 @ B
 b) which diver will
 enter water first?

A \rightarrow C \rightarrow A \rightarrow B

A \rightarrow B

3)

Use kinematic equations 1) 2) or 3)

Predictions:

- b) Diver 1 will enter water first since she has the additional $v_0 = 1.8 \frac{\text{m}}{\text{s}}$
- a) Diver 1 will enter water @ higher speed since both are subject to the same g & diver 1 has the additional v_0

Calculations: eg 3 (no time info)
find v_1 & v_2

a) Driver 1 Driver 2

$$\frac{v_1^2 - v_{01}^2}{x - x_0} = 2 \cdot g$$

$$\frac{v_2^2 - 0}{x - x_0} = 2 \cdot g$$

$$\begin{cases} x - x_0 = AB = 3m \\ g = 9.81 \frac{m}{s^2} \end{cases}$$

$$\begin{aligned} v_1 &= \sqrt{v_{01}^2 + 2 \cdot g \cdot (x - x_0)} \\ &= \sqrt{1.8^2 + 2 \cdot 9.81 \cdot 3} \\ &= 7.88 \frac{m}{s} \end{aligned}$$

$$\begin{aligned} v_2 &= \sqrt{2 \cdot g \cdot (x - x_0)} \\ &= \sqrt{2 \cdot 9.81 \cdot 3} \\ &= 7.67 \frac{m}{s} \end{aligned}$$

b) $v = v_0 + a \cdot t \rightarrow$ eg 1 (have v_1 & v_2 & v_{01} & v_{02} & g , find t)

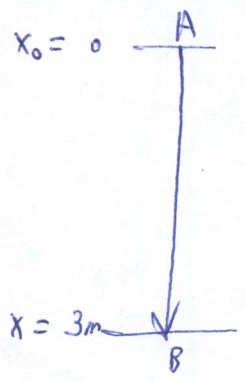
$$\begin{aligned} t_1 &= \frac{v_1 - v_{01}}{g} \\ &= \frac{7.88 - 1.8}{9.81} \\ &= 0.62s \end{aligned}$$

$$\begin{aligned} t_2 &= \frac{v_2 - v_{02}}{g} \\ &= \frac{7.67 - 0}{9.81} \\ &= 0.78s \end{aligned}$$

↓
Driver 1 takes less time or she will enter water first.

Sign for g : two alternatives: for placing origin of coordinate

1) Downward is + or
origin @
platform A



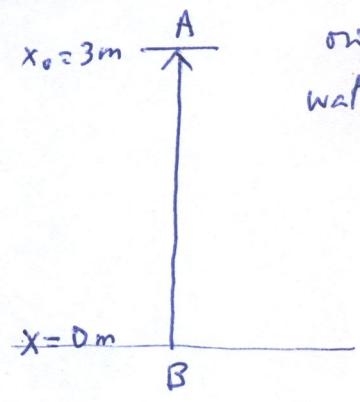
$x - x_0 = 3m$

$g = + 9.81 \frac{m}{s^2}$

$$v_1 = \sqrt{v_{01}^2 + \underbrace{2g(x-x_0)}_+}$$

$$= 7.88 \frac{m}{s}$$

2) Downward is - or
origin @
water surface B



$x - x_0 = -3m$

$g = - 9.81 \frac{m}{s^2}$

$$v_1 = \sqrt{v_{01}^2 + \underbrace{2g(x-x_0)}_{-}}$$

$$= 7.88 \frac{m}{s}$$

2.49]

$x = bt^4$, b constant

$v = \frac{dx}{dt} = 4bt^3$

1) Mathematical average of v over time interval $(0, t)$

$\bar{v} = \frac{1}{t-0} \int_0^t v \cdot dt = \frac{4b}{t} \int_0^t t^3 dt = \frac{b}{t} [t^4]_0^t$

$\bar{v} = bt^3$

$\int t^n dt = \frac{t^{n+1}}{n+1}$

$\bar{v} = \frac{v}{4}$

2) $\bar{v} = \frac{\Delta x}{\Delta t} = \frac{x(t) - x(0)}{t - 0} = \frac{bt^4 - 0}{t} = bt^3$

2.10

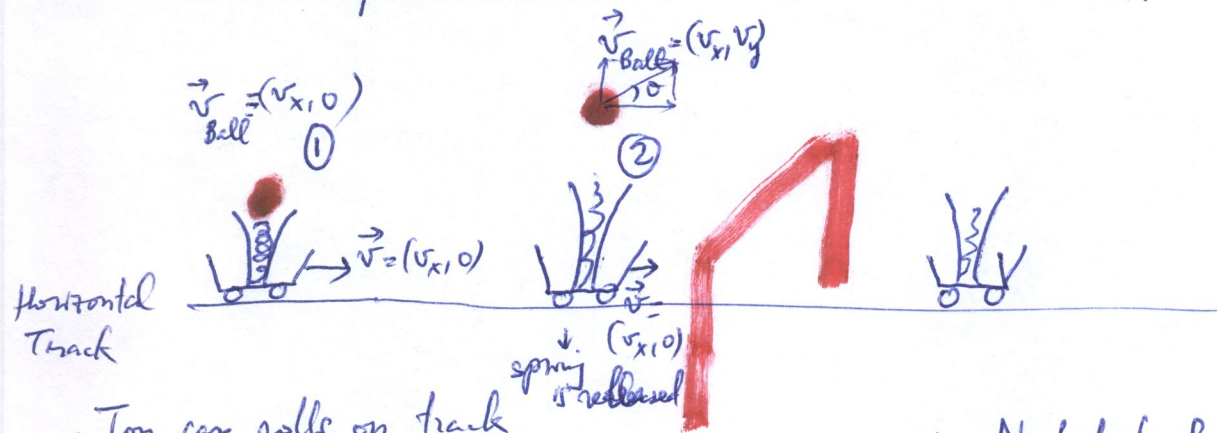
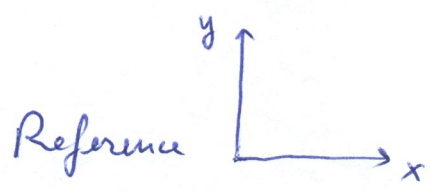
$50 \frac{km}{h}$ during 1h & $100 \frac{km}{h}$ during 1h

$\bar{v} = \frac{\Delta x}{\Delta t} = \frac{150 km}{2 h} = 75 \frac{km}{h}$

Ch3 Motion in Two & Three Dimensions

Note: Ch2: horizontal or vertical, now in 2D we will describe motions involving both horizontal & vertical components at the same time.

Visual experiment #1



- Toy car rolls on track at speed $\vec{v} = (v_x, 0)$ (constant)
- Spring is released with a switch controlled by the user. It will launch the ball up in the y-direction (spring is vertical)

- Neglect friction b/w car wheels & track
 $\vec{v}_{car} = \text{constant}$
- Neglect any air resistance on the metal ball

- @ ① ball has 1D motion same as the toy car
- @ ② ball has 2D motion (with an angle) toy car still 1D

Big question: will ball make it back to funnel after car passes the gate?

→ Yes given (i) no friction (ii) no air resistance; also

(iii) Motions in perpendicular directions (in y vertical & in x - horizontal) are independent!
(Ball actually makes it back to funnel!)

Mathematical descriptions

	<u>1D</u>	<u>2D</u>	<u>3D</u>
position	x	$\vec{r} = (x, y) = (r, \theta)$	$\vec{r} = (x, y, z) = (r, \theta, \phi)$
velocity	v	$\vec{v} = (v_x, v_y) = (v, \theta_v)$	$\vec{v} = (v_x, v_y, v_z) = (v, \theta_v, \phi_v)$
acceleration	a	$\vec{a} = (a_x, a_y) = (a, \theta_a)$	$\vec{a} = (a_x, a_y, a_z) = (a, \theta_a, \phi_a)$

\vec{r} = position vector

$\left\{ \begin{array}{l} (x, y, z) = \text{Cartesian coordinates (in 2D } (x, y)) \\ (r, \theta, \phi) = \text{Spherical coordinates} \end{array} \right.$

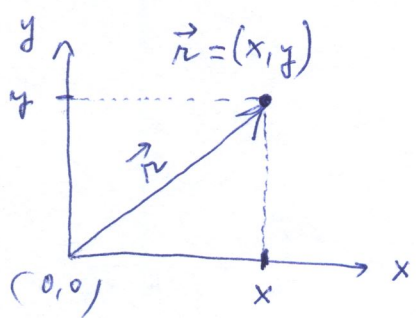
$\downarrow \quad \downarrow$
 theta phi

(in 2D (r, θ) = Polar Coordinates)

\vec{v} = velocity vector
 \vec{a} = acceleration vector

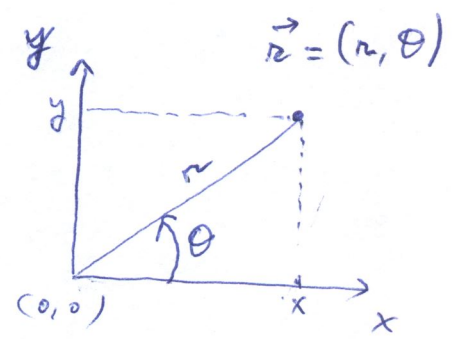
2D

Cartesian



Cartesian coordinates of a position described by position vector \vec{r} are obtained by projecting it onto the x & y axes

Polar



r = length of \vec{r} or its magnitude
 θ = angle formed by \vec{r} from the x-axis (CCW)

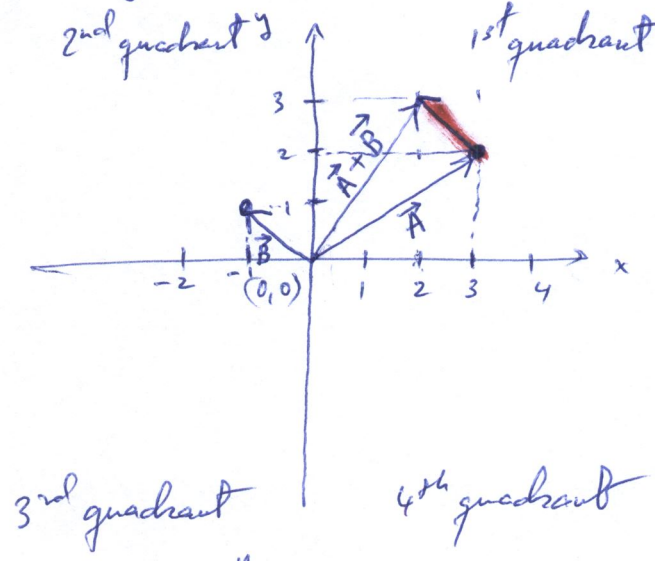
Cartesian (x, y) \longrightarrow Polar $\left\{ \begin{array}{l} r = \sqrt{x^2 + y^2} \text{ Pythagorean Theorem} \\ \theta = \tan^{-1} \frac{y}{x} \text{ Trigonometry} \end{array} \right.$

Polar (r, θ) \longrightarrow Cartesian $\left\{ \begin{array}{l} x = r \cos \theta \\ y = r \sin \theta \end{array} \right. \text{ Trigonometry}$

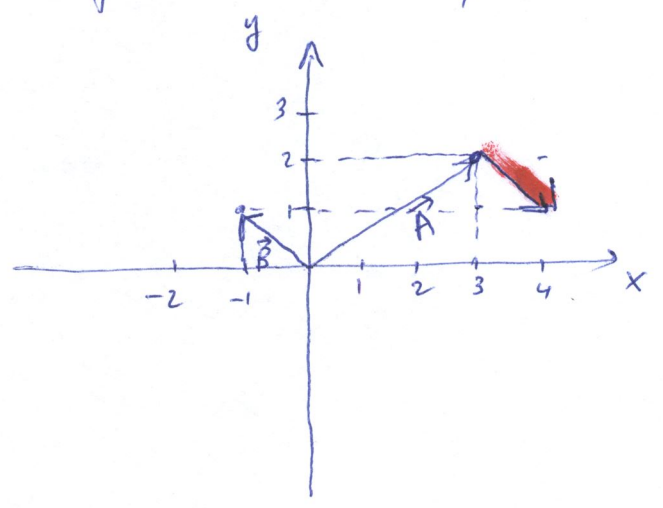
Add & Subtract vectors $(\vec{v}, \vec{a}, \vec{r})$

1) Graphically $\vec{A} + \vec{B}$; $\vec{A} - \vec{B}$

$\vec{A} = (3, 2)$ 1st quadrant
 $\vec{B} = (-1, 1)$ 2nd quadrant



$\vec{A} + \vec{B}$: 1) Draw a copy of \vec{B} from tip of \vec{A}
 2) $\vec{A} + \vec{B}$ starts from origin of \vec{A} to tip of the copy of \vec{B}
 $\vec{A} + \vec{B} = (2, 3)$



$\vec{A} - \vec{B}$: 1) Draw a copy of $-\vec{B}$ from tip of \vec{A}
 2) $\vec{A} - \vec{B}$ starts from origin of \vec{A} to tip of copy of $-\vec{B}$
 $\vec{A} - \vec{B} = (4, 1)$

2) Mathematically using Unit Vectors :

Unit vectors { vectors with length or magnitude of 1
 x-direction = \hat{i} (i-hat)
 y-direction = \hat{j} (j-hat)
 z-direction = \hat{k} (k-hat)

$\vec{A} = (3, 2) = (A_x, A_y)$

$\vec{A} = A_x \hat{i} + A_y \hat{j} = 3\hat{i} + 2\hat{j}$

$\vec{B} = (-1, 1) = (B_x, B_y)$

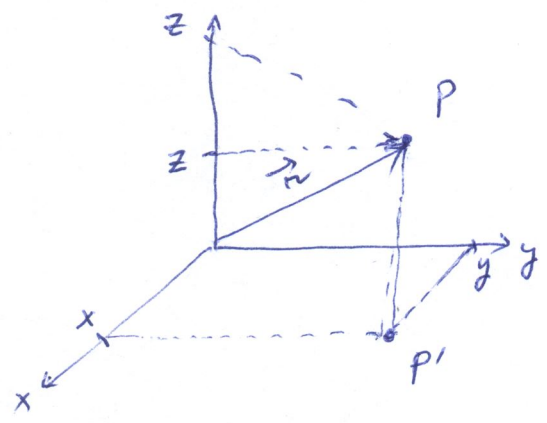
$\vec{B} = B_x \hat{i} + B_y \hat{j} = -\hat{i} + \hat{j}$

Addition: $\vec{A} + \vec{B} = 3\hat{i} + 2\hat{j} - \hat{i} + \hat{j} = 2\hat{i} + 3\hat{j} = (2, 3)$

Subtraction: $\vec{A} - \vec{B} = 3\hat{i} + 2\hat{j} - (-\hat{i} + \hat{j}) = 4\hat{i} + \hat{j} = (4, 1)$

3D

Cartesian: $\vec{r} = (x, y, z)$



Spherical $\vec{r} = (r, \theta, \phi)$

