

a constant deceleration from that initial speed to zero.  
 There is friction on slope and leveled path  $\mu_k = 0.12$ .

Slope: 2nd Newton's Law:  $\vec{F}_{net} = m\vec{a}$

- Free-body diagram ✓ (2)
- Coordinate system XY ✓ (3)
- Components of mg (4)
- 2nd Newton's law along X & Y (5)

$$\textcircled{5} \begin{cases} F_{net\ x} = m a_x = mg \sin 25^\circ - F_k = mg \sin 25^\circ - \mu_k N & \textcircled{a} \\ F_{net\ y} = m \cdot 0 = N - mg \cos 25^\circ & \textcircled{b} \end{cases}$$

$$\textcircled{b} \ N = mg \cos 25^\circ \rightarrow \textcircled{a} \quad \boxed{a_x = g \sin 25^\circ - \mu_k g \cos 25^\circ}$$

$$a_x = 9.81 (\sin 25^\circ - 0.12 \cos 25^\circ) = 3.08 \text{ m/s}^2$$

→ Calculate final speed at bottom of slope (length = 41m)  
 $x - x_0 = 41\text{m}$

$$\frac{v^2 - v_0^2}{x - x_0} = 2a_x \quad ; \quad v_0 = 0 \text{ (sled starts from rest)}$$

$$\rightarrow v = \sqrt{2a_x(x - x_0)} = \sqrt{2 \times 3.08 \times 41} = 15.9 \text{ m/s}$$

Leveled path: 2nd Newton's Law:  $\vec{F}_{net} = m\vec{a}$

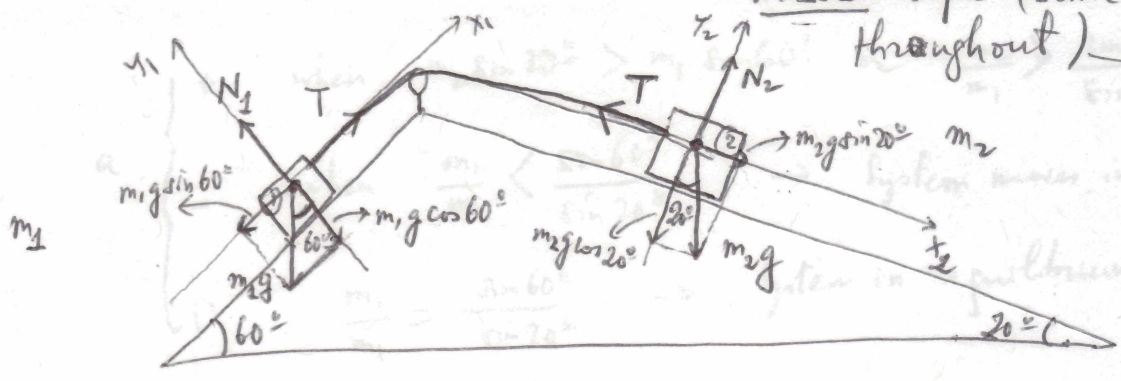
- Free body diagram ✓ (2)
- Coord. system X'Y' ✓ (3)
- Components: not needed ✓ (4)
- 2nd Newton's Law here along X' & Y' (5)

$$\textcircled{5} \begin{cases} F_{net\ x'} = -\mu_k N' = m a_{x'} \rightarrow a_{x'} = \frac{-\mu_k mg}{m} = -0.12 \times 9.81 \\ F_{net\ y'} = N' - mg = m \cdot 0 \rightarrow N' = mg \end{cases} \quad \boxed{a_{x'} = -1.18 \text{ m/s}^2}$$

→ constant deceleration from  $v_0 = 15.9 \text{ m/s}$  to  $v = 0 \rightarrow x' - x'_0 = \frac{0^2 - v_0^2}{2(-1.18)} = 107\text{m}$

Ch 5 (cont.) Method: 1) Sketch 2) Free-body diagram 3) Good. for each object 4) components of force not along axes 5) Newton's 2nd Law

Multiple objects:  $m_1$  &  $m_2$  connected together via a massless rope (same tension throughout) No friction



Massless rope:



Same tension:  $T - T = F_{net \text{ on rope}} = 0 = m_{rope} a$   
 (massless rope & same tension  $\rightarrow$  non-violation of 2nd Newton's law)  
 $0 \cdot a \rightarrow a$  could be non-zero

5) 2nd Newton's law for each object:

Object #1

$$\begin{cases} F_{net x_1} = T - m_1 g \sin 60^\circ = m_1 a_{1x} & (a) \\ F_{net y_1} = N_1 - m_1 g \cos 60^\circ = 0 & (b) \end{cases}$$

(\*) We assume system move in CW direction ( $m_1$  uphill &  $m_2$  downhill)

Object #2

$$\begin{cases} F_{net x_2} = m_2 g \sin 20^\circ - T = m_2 a_{2x} & (c) \\ F_{net y_2} = N_2 - m_2 g \cos 20^\circ = 0 & (d) \end{cases}$$

c) Solve: for the common acceleration of the objects:  $a_{1x} = a_{2x} \equiv a$

$$\begin{aligned} \hookrightarrow (a) \quad T - m_1 g \sin 60^\circ &= m_1 a \\ + (c) \quad m_2 g \sin 20^\circ - T &= m_2 a \end{aligned}$$

$$a(m_2 \sin 20^\circ - m_1 \sin 60^\circ) = (m_1 + m_2)a \rightarrow a = g \frac{m_2 \sin 20^\circ - m_1 \sin 60^\circ}{m_1 + m_2}$$

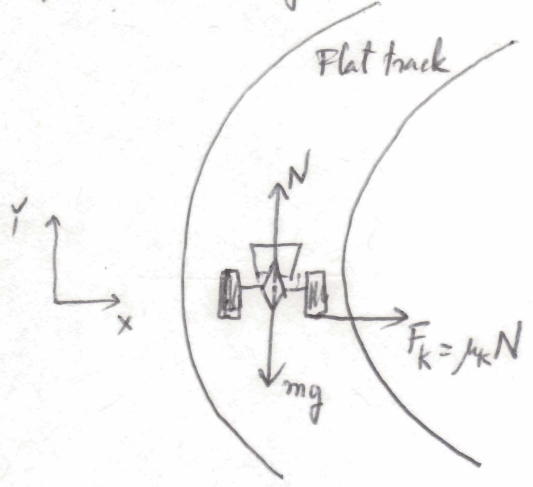
a

- + when  $m_2 \sin 20^\circ > m_1 \sin 60^\circ$  or  $\frac{m_2}{m_1} > \frac{\sin 60^\circ}{\sin 20^\circ}$  → System moves in CW
- when  $\frac{m_2}{m_1} < \frac{\sin 60^\circ}{\sin 20^\circ}$  → System moves in CCW
- 0  $\frac{m_2}{m_1} = \frac{\sin 60^\circ}{\sin 20^\circ}$  → System in equilibrium

Circular Motion, (Uniform)

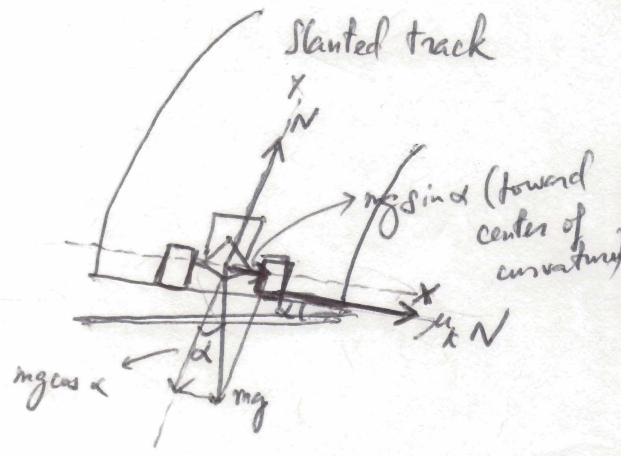
Application of 2nd Newton's law to Car Racing.

Turn: Radius of curvature is R



2nd Newton's Law

$$\begin{cases} F_{net,x} = \mu_k N = m \frac{v^2}{R} \\ F_{net,y} = N - mg = 0 \end{cases}$$



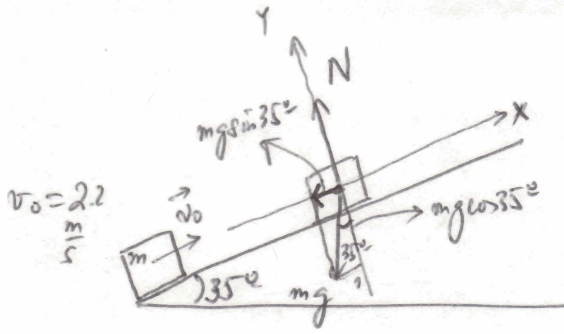
2nd Newton's Law

$$\begin{cases} F_{net,x} = mg \sin \alpha + \mu_k N = m \frac{v^2}{R} \\ F_{net,y} = N - mg \cos \alpha = 0 \end{cases}$$

higher v during turn is slanted track

Possible scenarios: given  $m; \mu_k; R$  what is  $v$  (max) for  $\alpha = 0$  and  $\alpha = 20^\circ$

5.33



No friction

- 1) sketch ✓ 2) FBD ✓ 3) x & y 4) x & y components for mg 5) 2<sup>nd</sup> Newton's law

5) 2<sup>nd</sup> Newton's law

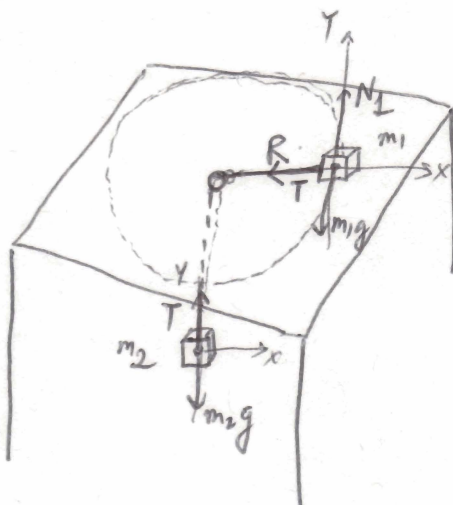
$$\begin{cases} F_{net\ x} = -mg \sin 35^\circ = m a_x \quad (\text{downward down hill}) \\ F_{net\ y} = N - mg \cos 35^\circ = 0 \end{cases}$$

6) solve for  $x - x_0 =$  3<sup>rd</sup> kinematic eq:  $\frac{v^2 - v_0^2}{x - x_0} = 2a_x$

$$\begin{aligned} x - x_0 &= \frac{v^2 - v_0^2}{2a_x} = \frac{-v_0^2}{2a_x} = \frac{v_0^2}{2g \sin 35^\circ} \\ &= \frac{2.2^2}{2 \times 9.8 / \sin 35^\circ} = \boxed{0.43\text{ m}} \end{aligned}$$

5.37

No friction  
Massless string  
↳ same tension



$m_1$ : circular motion around hole at radius  $R$   
 $m_2$ : stationary ( $a_2 = 0$ )  
 $m_1$  &  $m_2$  connected together

a) Tension in string T?

- 1) sketch 2) FBD 3) coord. XY 4) ✓ 5) 2<sup>nd</sup> Newton's law:

5)

$$\begin{cases} m_1 \begin{cases} F_{net\ x} = T = m_1 \frac{v^2}{R} \quad (i) \\ F_{net\ y} = N_1 - m_1 g = 0 \quad (ii) \end{cases} \\ m_2 \begin{cases} F_{net\ x} = 0 \quad (iii) \\ F_{net\ y} = T - m_2 g = m_2 \cdot 0 \quad (iv) \end{cases} \end{cases}$$

$\boxed{T = m_2 g}$

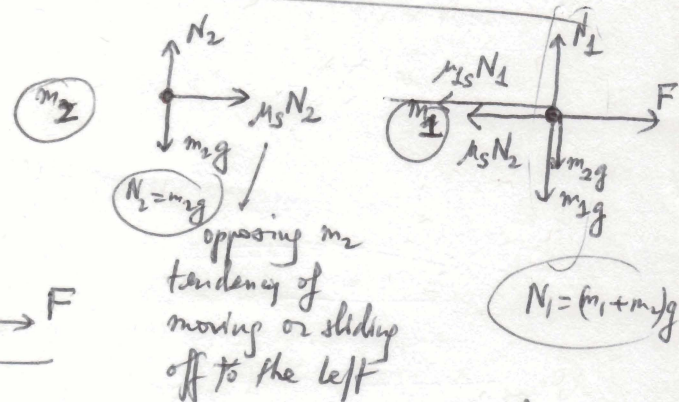
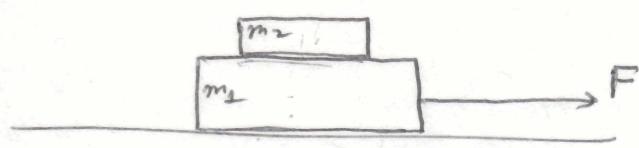
b) Period of circular motion: time to complete one turn  $2\pi R$ :

$$\hookrightarrow \frac{2\pi R}{v} = \boxed{\frac{2\pi \sqrt{m_1 R}}{\sqrt{m_2 g}}}$$

2nd Newton's law:  $v = \sqrt{\frac{TR}{m_1}} = \sqrt{\frac{m_2 g R}{m_1}}$

$$\frac{2\pi R \sqrt{\frac{m_2 g R}{m_1}}}{m_1} = \frac{2\pi R}{\sqrt{\frac{m_2 g R}{m_1}}} = \frac{2\pi \sqrt{m_1 R}}{\sqrt{m_2 g}}$$

5.48



$m_1 = 1.2 \text{ kg}$   
 $m_2 = 0.31 \text{ kg}$

Applied on  $m_2$

$m_1$  &  $m_2$  accelerate together

$v_0 = 0 \rightarrow v = 0.96 \frac{\text{m}}{\text{s}}$  in  $\Delta t = 0.42 \text{ s}$

const.  $a: v = v_0 + at \rightarrow a = \frac{v - v_0}{t} = \frac{0.96}{0.42} = 2.28 \text{ m/s}^2$

Then  $m_1$  is brought to stop in  $0.33 \text{ s}$ ,  $m_2$  slides off  $\rightarrow$  estimate  $\mu_s$

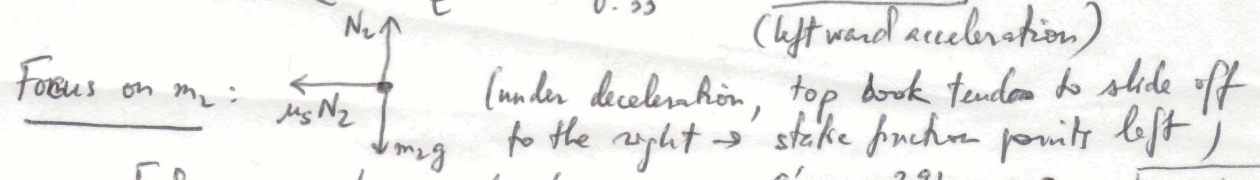
5) Focus on  $m_2$ :

$$\begin{cases} F_{net,x} = \mu_s m_2 g = m_2 a \rightarrow \mu_s = \frac{a}{g} \\ F_{net,y} = N_2 - m_2 g = 0 \end{cases}$$

min  $\mu_s (\mu_s \geq \frac{a}{g})$

$\mu_s \geq \frac{a}{g} = \frac{2.28}{9.81} = 0.23$  for the two books to accelerate together

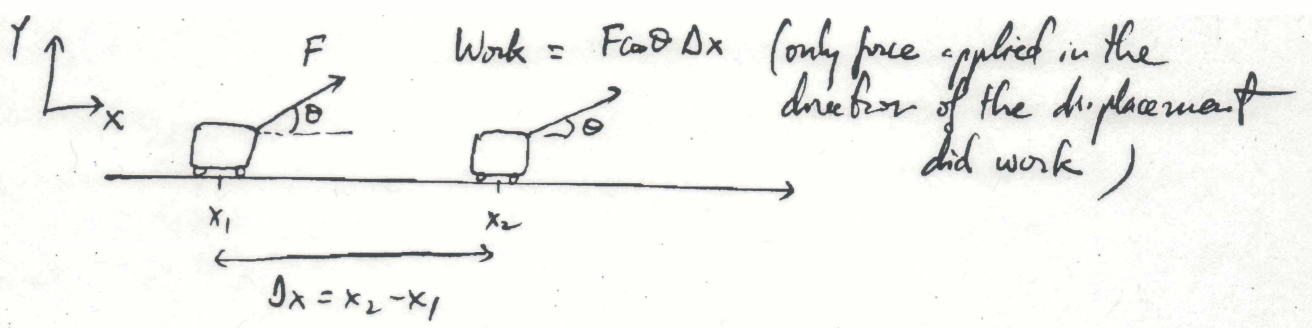
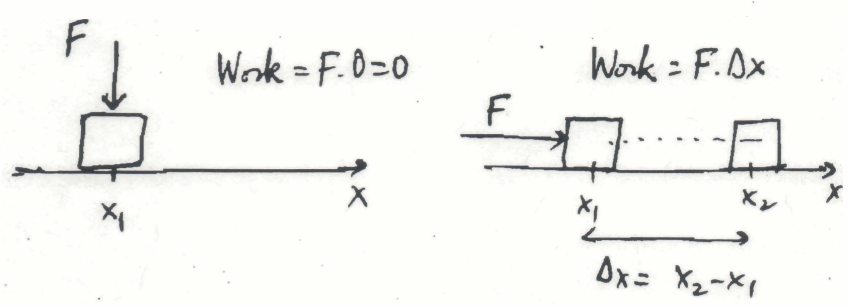
constant deceleration:  $a' = \frac{v' - v_0'}{t'} = \frac{0 - 0.96}{0.33} = -2.91 \text{ m/s}^2$



$F_{net,x} = -\mu_s m_2 g = m_2 a' \rightarrow \mu_s = -\frac{a'}{g} = \frac{2.91}{9.81} = 0.3 \rightarrow 0.23 \leq \mu_s \leq 0.3$

# Ch 6: Work, Energy and Power:

Work:  $F \cdot \Delta x$  (unit: SI. Nm = J (Joule))

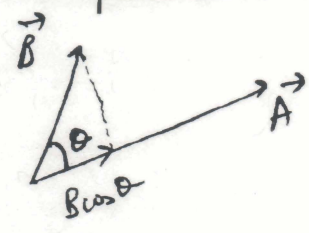


Along y-direction:  $Work = F \sin \theta \Delta y = 0$

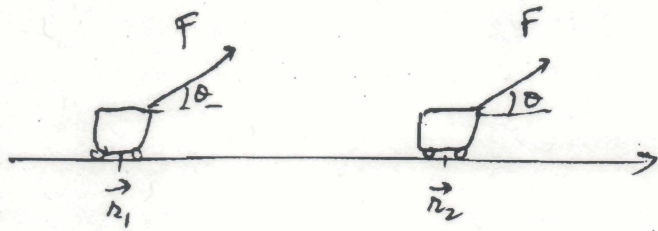
↳ Work done =  $\vec{F} \cdot \Delta \vec{r}$

- $\vec{F}$ : Force applied (vector)
- $\Delta \vec{r}$ : displacement
- $\cdot$ : scalar product (b/w 2 vectors produce a number)

Scalar product: b/w two vectors  $\vec{A}$  &  $\vec{B}$



$\vec{A} \cdot \vec{B} = A \underbrace{B \cos \theta}_{\text{projection of } \vec{B} \text{ onto the direction of } \vec{A}}$

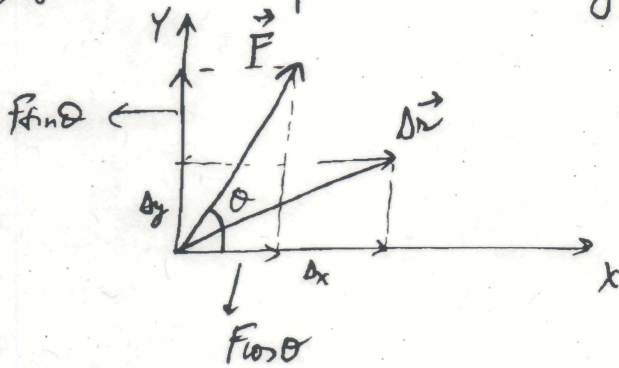


$$\vec{F} \cdot d\vec{r} = F dr \cos \theta$$

$$= dr \underline{F \cos \theta}$$

projection of the force onto the direction of displacement

With the scalar product we can calculate the work done by forces and displacements along any direction:



$$\text{Work done} = \vec{F} \cdot d\vec{r}$$

$$= (F \cos \theta \hat{i} + F \sin \theta \hat{j}) \cdot (dx \hat{i} + dy \hat{j})$$

$$= F \cos \theta dx + F \sin \theta dy$$

$$\hat{i} \cdot \hat{i} = 1 ; \hat{j} \cdot \hat{j} = 1$$

$$\hat{i} \cdot \hat{j} = 0 ; \hat{j} \cdot \hat{i} = 0 \quad (\cos 90^\circ = 0)$$

If the force applied is changing with the position:

$$\text{Work done} = \int_{\vec{r}_1}^{\vec{r}_2} \vec{F} \cdot d\vec{r}$$

↳ infinitesimal displacement vector

↳ Work done in stretching a spring:

Hooke's law:  $F = -kx$  (force applied by a person is  $kx$ )

$$\int_0^x F dx = \int_0^x kx dx = k \left[ \frac{x^2}{2} \right]_0^x = \frac{1}{2} kx^2$$

$$\left( \int x^n dx = \frac{x^{n+1}}{n+1} \right)$$

**Kinetic Energy:**

2<sup>nd</sup> Newton's Law:  $\vec{F}_{net} = \frac{d\vec{p}}{dt} = m \frac{d\vec{v}}{dt}$   $\nearrow$  m is constant

$$\Delta K.E. = \int_{\vec{r}_1}^{\vec{r}_2} \vec{F}_{net} \cdot d\vec{r} = m \int_{\vec{r}_1}^{\vec{r}_2} \frac{d\vec{v}}{dt} \cdot d\vec{r} = m \int_{\vec{r}_1}^{\vec{r}_2} d\vec{v} \cdot \frac{d\vec{r}}{dt} = m \int_{\vec{r}_1}^{\vec{r}_2} d\vec{v} \cdot \vec{v}$$

$$\int_{\vec{r}_1}^{\vec{r}_2} v d\vec{v} = \left[ \frac{1}{2} m v^2 \right]_{\vec{r}_1}^{\vec{r}_2} = \frac{1}{2} m v_2^2 - \frac{1}{2} m v_1^2$$

Linear motion:  $\vec{v} \parallel d\vec{v} \rightarrow \vec{v} \cdot d\vec{v} = v dv \cos 0 = v dv$

Power: P work or energy per unit time

Average power:  $\bar{P} = \frac{\Delta \text{Work}}{\Delta t}$

Instantaneous power:  $P = \frac{d \text{Work}}{dt}$

Unit:  $\frac{J}{s} = W \text{ (Watt)}$

Power & velocity:

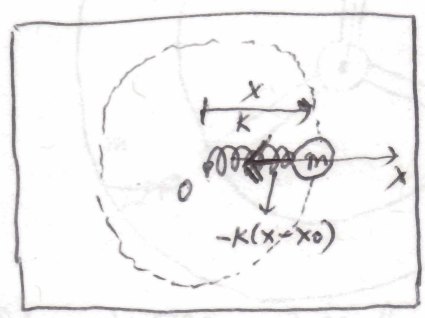
$$P = \frac{d \text{Work}}{dt} = \frac{d}{dt} (\vec{F} \cdot d\vec{r}) = \vec{F} \cdot \frac{d(d\vec{r})}{dt} = \vec{F} \cdot \vec{v}$$



5.62

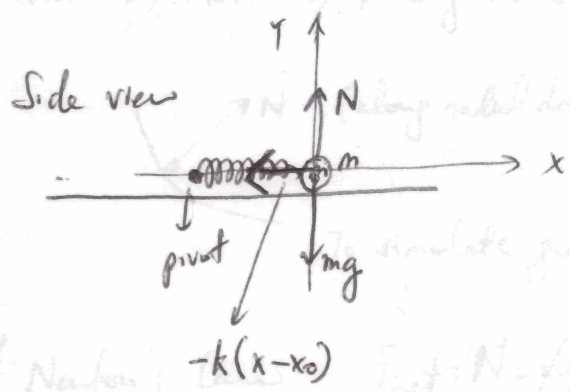
1) sketch: 2) FBD on mass m 3) find x & y 4) ✓ 5)

View from above:



No friction on air table.

$m = 2.1 \text{ kg}$  → uniform circular motion  
 $k = 150 \frac{\text{N}}{\text{m}}$   
 $x_0 = 0.18 \text{ m}$  (unstretched length)  
 $v = 1.4 \text{ m/s}$   
 $R?$



5) 2nd Newton's law:

$$\begin{cases} F_{net,y} = N - mg = 0 \rightarrow N = mg \\ F_{net,x} = -k(x - x_0) = -m \frac{v^2}{R} \end{cases}$$

• Length of spring:  $x$   
 displacement from unstretched length  $x_0$  is  $(x - x_0)$

separation b/w  $m$  & center of curvature

$a = -\frac{v^2}{R}$  (toward center = toward negative  $x$ )

→ c) solve for  $x$ :

$$\begin{aligned} kx - kx_0 &= \frac{mv^2}{R} \\ kx^2 - kx_0x &= mv^2 \\ kx^2 - kx_0x - mv^2 &= 0 \end{aligned}$$

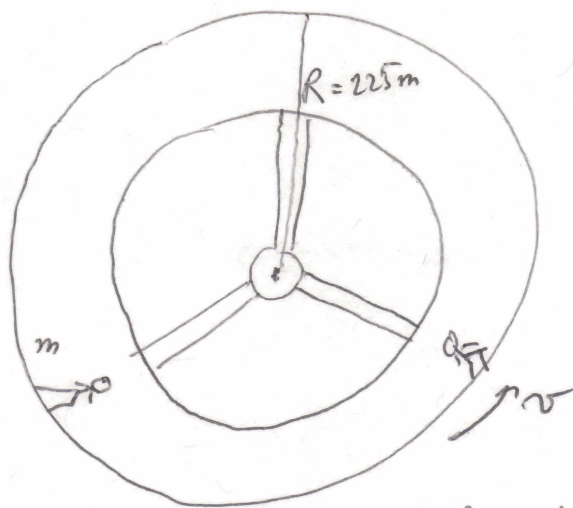
$$150x^2 - 27x - \frac{2.1 \times 1.4^2}{0.28} = 0$$

$$\rightarrow x = \frac{27 \pm \sqrt{27^2 + 600 \times 4.12}}{300}$$

$x = 0.28 \text{ m}$  length of spring = radius of circular path.  
 $-0.097 \text{ m}$

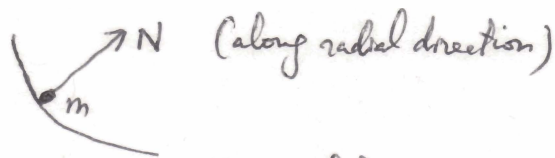
5.56

54

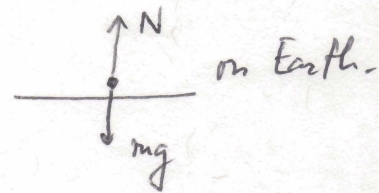


Space Station

- 1) Sketch 2) FBD: 3)  $\gamma$  along radial direction 4)  $v$  5)



To simulate gravity:  $N = mg$



5) 2nd Newton's Law:  $F_{\text{net}} = N = mg = m \frac{v^2}{R}$

6) Solve for  $v = \sqrt{gR} = \sqrt{9.81 \times 225} \frac{\text{m}}{\text{s}} = 46.98 \text{ m/s}$

$$46.98 \frac{\text{m}}{\text{s}} \cdot \frac{1 \text{ rev}}{2\pi \times 225 \text{ m}} \cdot \frac{60 \text{ s}}{1 \text{ min}} = 1.99 \frac{\text{rev}}{\text{min}}$$

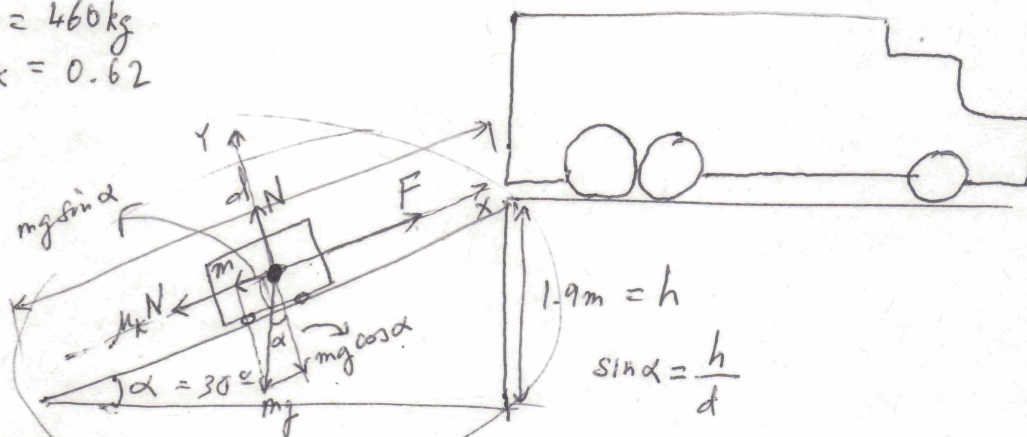
# Ch 6 (Cont.) Work, Energy, and Power

Unit: SI

}	Work = J (Joule)
	Energy = J (Joule)
	Power = $\frac{J}{s} = W$ (Watt)

## Example:

$m = 460 \text{ kg}$   
 $\mu_k = 0.62$



**Work done** in pushing the piano from bottom of ramp to top of ramp if  $\alpha = 15^\circ$  and if  $\alpha = 30^\circ$  ( $h$  is fixed) (in our sketch,  $d$  will be larger when  $\alpha = 15^\circ$ ).

$$F \cdot d = F \frac{h}{\sin \alpha}$$

What is  $F$ ?  $\rightarrow$  force applied on piano.

- 1) sketch  $\checkmark$
- 2) FBD  $\checkmark$
- 3) X & Y
- 4) components X & Y for  $mg$
- 5) 2nd Newton's law

$$\begin{cases} F_{net x} = \overset{LHS}{F - mg \sin \alpha - \mu_k N} = \overset{RHS}{m a_x} \\ F_{net y} = N - mg \cos \alpha = 0 \end{cases}$$

$$F = mg \sin \alpha + \mu_k mg \cos \alpha + m a_x$$

Min. work required when  $a_x = 0$  (constant speed)

$$\hookrightarrow F = mg (\sin \alpha + \mu_k \cos \alpha)$$

Work done:  $W = F \cdot \frac{h}{\sin \alpha} = mg \frac{(\sin \alpha + \mu_k \cos \alpha) h}{\sin \alpha} = mgh \left( 1 + \frac{\mu_k}{\tan \alpha} \right)$

$\left\{ \begin{array}{l} \alpha = 15^\circ \\ \alpha = 30^\circ \end{array} \right. \rightarrow W_{15^\circ} = 460 \times 9.81 \times 1.9 \left( 1 + \frac{0.62}{\tan 15^\circ} \right) = 28.5 \text{ kJ}$   
 $W_{30^\circ} = 460 \times 9.81 \times 1.9 \left( 1 + \frac{0.62}{\tan 30^\circ} \right) = 19.8 \text{ kJ}$

kilo = 1000

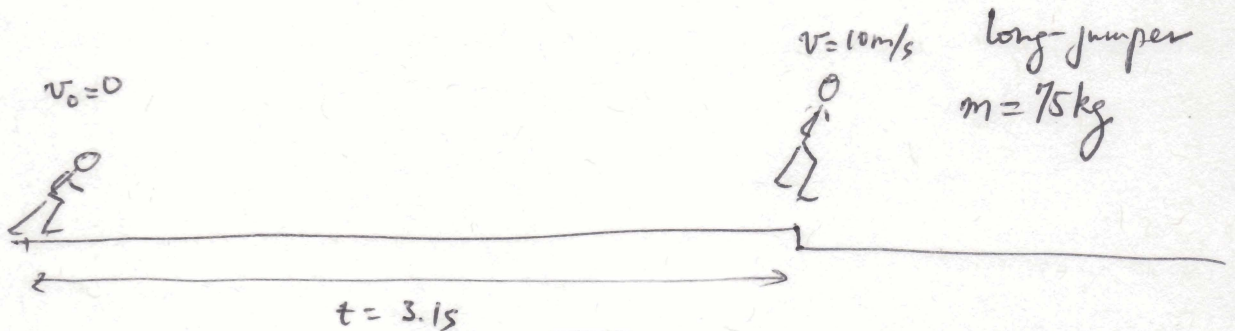
Force applied F

$\left\{ \begin{array}{l} \alpha = 15^\circ \\ \alpha = 30^\circ \end{array} \right. \rightarrow F_{15^\circ} = 460 \times 9.81 (\sin 15^\circ + 0.62 \cos 15^\circ) = 3.88 \text{ kN}$   
 $F_{30^\circ} = 460 \times 9.81 (\sin 30^\circ + 0.62 \cos 30^\circ) = 4.68 \text{ kN}$

crew with ability to push up to 4kN → use 15° ramp

- 6.38
- 6.67;
- 6.80; 6.81;

6.38



$P$  (power output) =  $\frac{\text{Work done (0 m/s} \rightarrow \text{10 m/s)}}{\text{time (3.1 s)}} = \frac{3750}{3.1} = 1.21 \text{ kW}$

Work done (0 m/s → 10 m/s) =  $\Delta KE = KE_{10 \text{ m/s}} - KE_{0 \text{ m/s}}$   
 $KE = \frac{1}{2}mv^2$   
 $= \frac{1}{2} \times 75 \times 10^2 - 0$   
 $= 3750 \text{ J}$

$1 \text{ HP} = 746 \text{ W} \rightarrow P = 1.21 \text{ kW} \frac{1 \text{ HP}}{0.746 \text{ kW}} = 1.6 \text{ HP}$

Kinetic energy:

$$\Delta KE = \text{Work done} = \int_{\vec{r}_1}^{\vec{r}_2} \vec{F}_{\text{net}} \cdot d\vec{r} = m \int_{\vec{r}_1}^{\vec{r}_2} \frac{d\vec{v}}{dt} \cdot d\vec{r}$$

2nd Newton's Law  
 $\vec{F}_{\text{net}} = \frac{d\vec{p}}{dt} = m \frac{d\vec{v}}{dt}$   
 constant mass system.

$$= m \int_{\vec{r}_1}^{\vec{r}_2} d\vec{v} \cdot \frac{d\vec{r}}{dt} = m \int_{\vec{r}_1}^{\vec{r}_2} v dv = \left[ \frac{1}{2} m v^2 \right]_{\vec{r}_1}^{\vec{r}_2} = \frac{1}{2} m v_2^2 - \frac{1}{2} m v_1^2$$

linear motion  
 $\vec{v} \parallel d\vec{v} \rightarrow \vec{v} \cdot d\vec{v} = v dv \cos 0 = v dv$

$$\rightarrow \boxed{KE = \frac{1}{2} m v^2}$$

W/O using  
 $KE = \frac{1}{2} m v^2$

☆ calculate  $a$ , then  $x - x_0$ , find  $F_{\text{net}}$  applied by long-jumper

$a = 3.23 \text{ m/s}^2$ ;  $d = x - x_0 = 15.5 \text{ m}$ ;  $F_{\text{net}} = ma = 75 \text{ kg} \times 3.23 \frac{\text{m}}{\text{s}^2} = 241.94 \text{ N}$

$\rightarrow \text{Work done} = F_{\text{net}} \cdot d = 3750 \text{ J} \rightarrow P = 1.6 \text{ HP}$

using  
 $KE = \frac{1}{2} m v^2$

☆  $F_{\text{net}} = \frac{\text{Work}}{d} = \frac{\frac{1}{2} m v^2 - 0}{d} = \frac{3750}{15.5} = 241.94 \text{ N}$

6.67

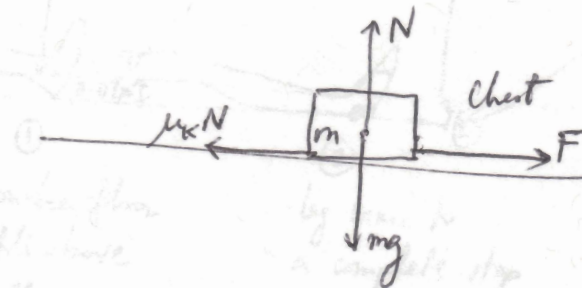
a) P?

$m = 95 \text{ kg}$  @  $v = 0.62 \text{ m/s}$  (const.)

$\mu_k = 0.78$

$\hookrightarrow \frac{\text{Work}}{\text{time}}$

$= \frac{F \cdot d}{\text{time}} = F \cdot v = \mu_k mg v = 0.78 \times 95 \times 9.81 \times 0.62 = 450 \text{ W}$



2nd Newton's law:

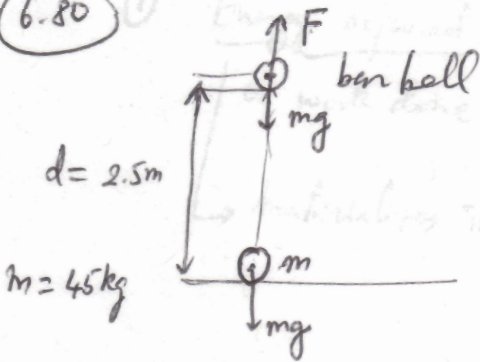
$F_{net,x} = F - \mu_k N = ma = 0$

↓  
const. speed.

$F = \mu_k N = \mu_k mg$

$F_{net,y} = N - mg = 0 \rightarrow N = mg$

6.80



$230 \text{ cal} \frac{4.186 \text{ kJ}}{1 \text{ cal}} = 230 \times 4.186 \text{ kJ}$

One lift would burn:  $F \cdot d = mgd = 45 \times 9.81 \times 2.5 = 1.1 \text{ kJ}$

$F - mg = ma \rightarrow F = mg$

↳ best economy =  $a = 0$

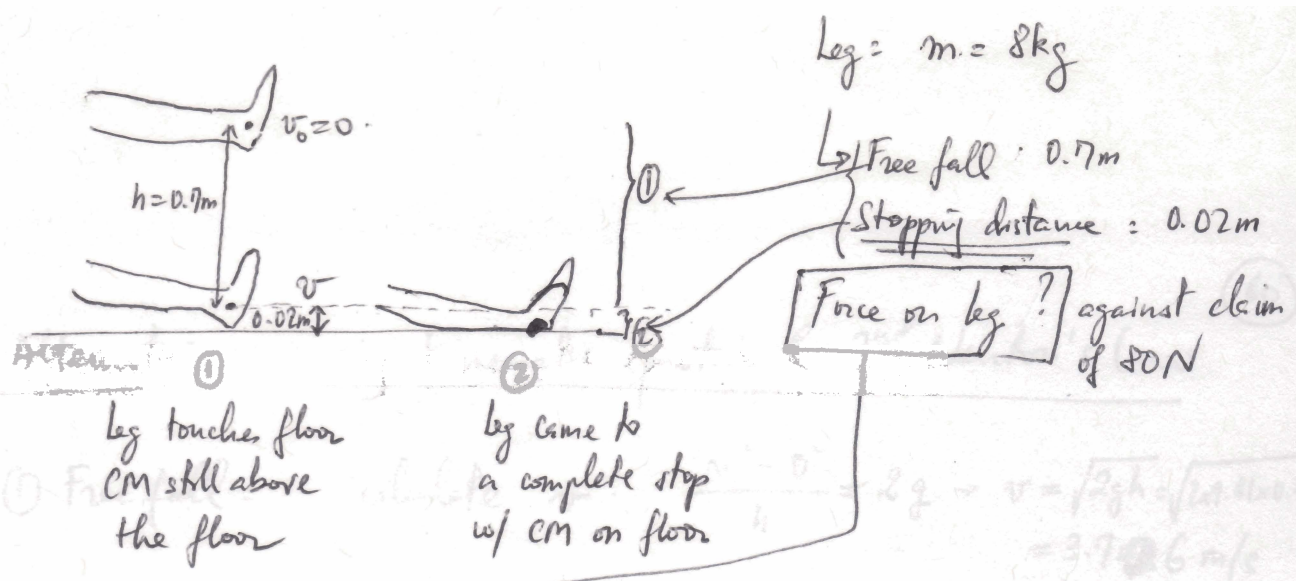
$\frac{230 \times 4.186 \text{ kJ}}{1.1 \text{ kJ}} = 873 \text{ lifts}$

How long?

$\frac{8 \times 9.81 \times 0.7}{0.02} = 2764 \text{ W}$

by 3rd Newton's law (didn't react) = floor exerts equal and opposite force

6.81



1st alternative: using work/energy

① Energy acquired by leg during free fall:  $F \cdot d = F \cdot h$   
 or work done on leg  $= mgh$

↳ materializes into K.E of leg  $= \frac{1}{2}mv^2 = mgh$   
 speed of leg as it touches the floor (CM still above floor)

② During stopping distance of  $0.02\text{m}$  leg would lose all the KE acquired during ①: by applying a force  $F_{\text{stop}}$  on floor such that:

$$F_{\text{stop}} \cdot d_{\text{stop}} = \frac{1}{2}mv^2 = mgh$$

$$F_{\text{stop}} = \frac{mgh}{d_{\text{stop}}} = \frac{8 \times 9.81 \times 0.7}{0.02} = 2744\text{N}$$

By 3rd Newton's Law (Action & reaction) = floor exerts equal and opposite force on leg =  $2744\text{N}$

2nd Alternative: using kinematic equation & 2nd Newton's law

① Free fall: calculate  $v$ :  $\frac{v^2 - 0^2}{h} = 2g \rightarrow v = \sqrt{2gh} = \sqrt{2 \times 9.81 \times 0.7} = 3.726 \text{ m/s}$

② Stopping distance:  $\rightarrow$  calculate deceleration  $a$ , then  $F_{\text{stop}}$

$$\frac{0^2 - 3.7^2}{0.02} = 2a \rightarrow a = \frac{-3.7^2}{0.04} = -342.35 \text{ m/s}^2$$

$$F_{\text{stop}} = ma = 8 \times (+342) = +2747 \text{ N}$$

$\downarrow$   
2nd Newton's Law

$\rightarrow$  Floor exerts equal & opposite force on leg!  
(Not 80N)

Drag forces (air resistance) & terminal speed

$$\rightarrow F_D = \frac{1}{2} C_p \rho_{\text{fluid}} A_{\text{body}} v_{\text{body}}^2$$

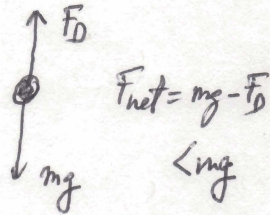
$C$ : constant

$\rho$ : fluid density

$A$ : surface area of body

$v$ : speed of body

Why?



Is  $F_D$  constant during a free fall? No:  $F_D \propto v^2$   
as  $v \uparrow \rightarrow F_D \uparrow$  at some point  $F_D = mg \rightarrow F_{\text{net}} = 0$   
 $\rightarrow$  object has no longer any acceleration  $\rightarrow$  continue to go down at const speed or terminal speed.

During a free fall do you want to get a terminal speed earlier or later?

$$F_D = mg \rightarrow \boxed{v_T = \sqrt{\frac{2mg}{C_p \rho_{\text{fluid}} A_{\text{body}}}}$$