

# Ch. 9 Gravitation

$$F = G \frac{m_1 m_2}{r^2}$$

Universal Gravitation

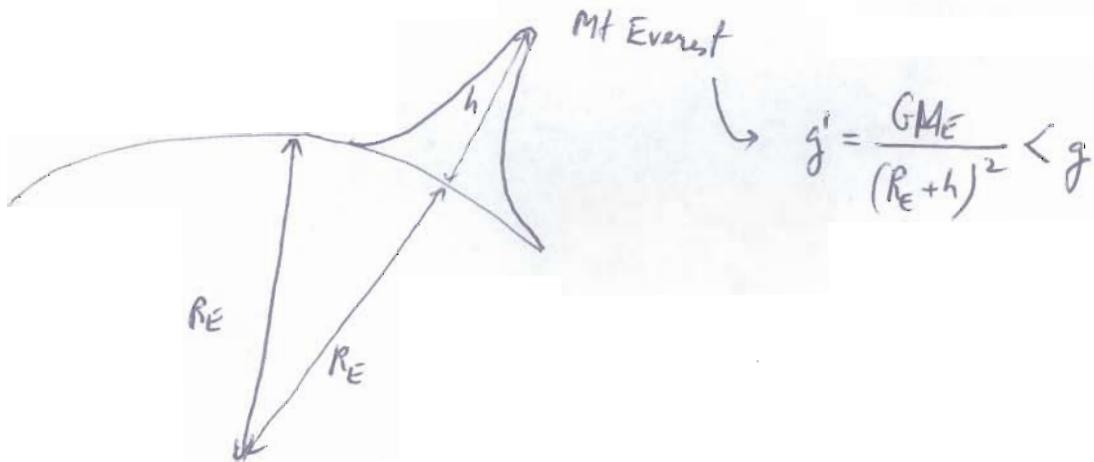
$$\text{Universal Gravitational constant} = 6.67 \times 10^{-11} \frac{\text{Nm}^2}{\text{kg}^2}$$

Force of attraction b/w 2 objects of mass  $m_1$  &  $m_2$  separated by  $r$

Why  $g = 9.81 \text{ m/s}^2$  ? Gravitation by our Planet  $\left\{ \begin{array}{l} M_E = 5.97 \times 10^{24} \text{ kg} \\ R_E = 6.37 \times 10^6 \text{ m} \end{array} \right.$

An object on the surface :  $r = R_E$

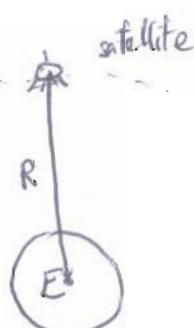
$$F = G \frac{M_E m_2}{R_E^2} = m_2 g \rightarrow \left[ g = \frac{GM_E}{R_E^2} \right] = \frac{6.67 \times 10^{-11} \times 5.97 \times 10^{24}}{(6.37 \times 10^6)^2} = 9.81 \text{ m/s}^2$$



## Orbital Motion

$M_E$

Period of a satellite  
at orbit  $R$  (Uniform  
Circular motion)



Agent that provides  
radial acceleration  
for this UCM is gravitation

$$\frac{GM_E m_s}{R^2} = m_s \frac{v_s^2}{R} \rightarrow v_s = \sqrt{\frac{GM_E}{R}}$$

$$T = \frac{2\pi R}{v_s} = \frac{2\pi}{\sqrt{GM_E}} R^{3/2}$$

(23)

A satellite at :  $R = 250 \text{ km}$   $\rightarrow \left\{ \begin{array}{l} v_s = 7.75 \text{ km/s} \\ T = 5400 \text{ s} = 1.5 \text{ h.} \end{array} \right.$

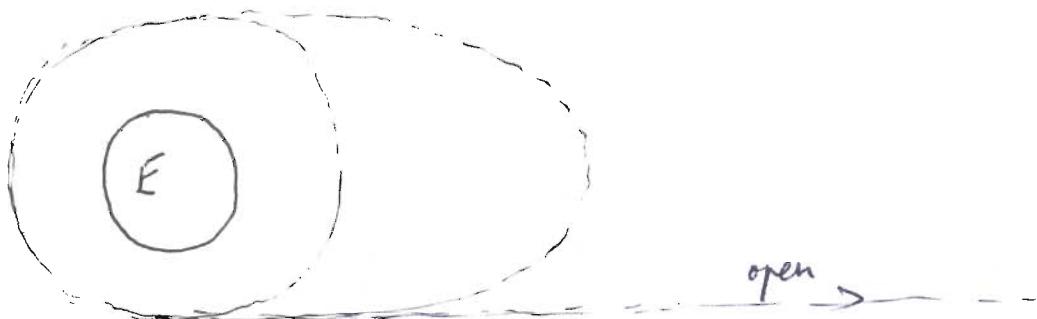
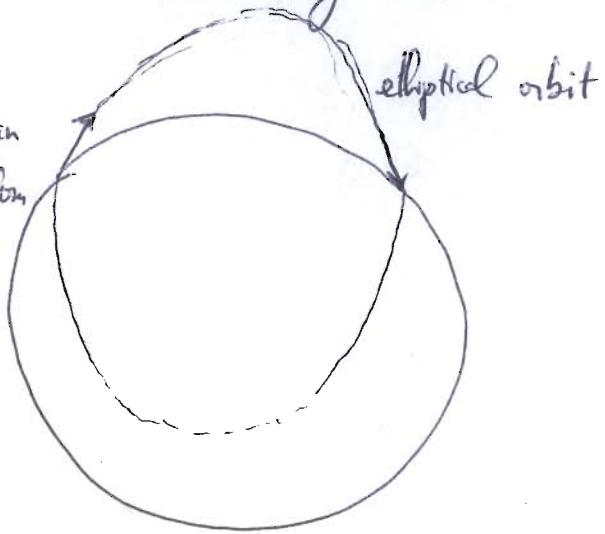
$R_E = 6370 \text{ km}$   $= 27900 \text{ km/h}$   $1.26 \times 10^6 \text{ km/s}$

$$R = 6370 \text{ km} + 250 \text{ km} = 6.62 \times 10^6 \text{ m}$$

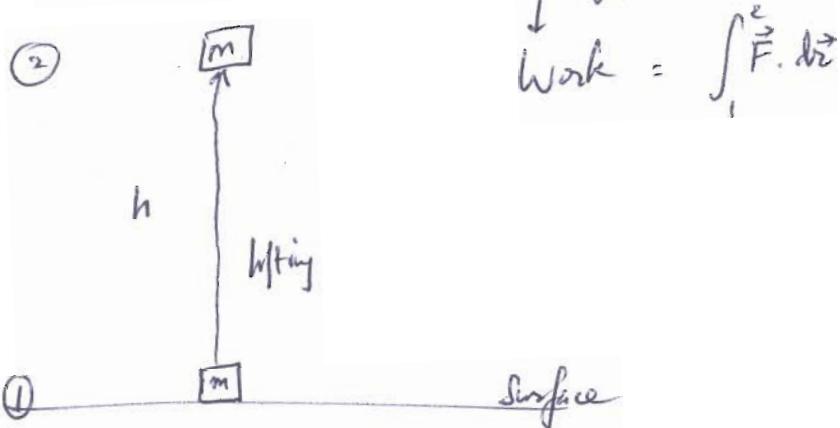


→ In general orbits under gravity by round objects are elliptical  
 Projectile motion over long distance: → Earth's surface is not flat:

a portion of an elliptical trajectory rather than parabolic



## Gravitational Potential Energy



Gravitational energy for  $m$  at ② is higher compared to at ①

$$\Delta U = \int_1^2 \frac{GMEm}{r^2} dr = GMEm \left( -\frac{1}{r} \right)_1^2 = \underbrace{GMEm \left( \frac{1}{R_E+h} - \frac{1}{R_E} \right)}_{\frac{1}{R_E} - \frac{1}{R_E+h}}$$

$$\int x^n dx = \frac{x^{n+1}}{n+1}; \quad \int \frac{dx}{x^n} = \int x^{-n} dx = \frac{x^{-n+1}}{-n+1}$$

$$\int \frac{dr}{r^2} = -\frac{1}{r}$$

(if you define  $\Delta U = U_1 - U_2 \rightarrow$  use  $F = -\frac{GMEm}{r^2}$  (sign to indicate attraction) & the RHS is +)

$$\Delta U = GMEm \left( \frac{1}{R_E} - \frac{1}{R_E+h} \right) = GMEm \left( \frac{h}{R_E(R_E+h)} \right)$$

(General)

Now  $h \ll R_E$  ( $h$  up to 1000m)  $R_E+h \approx R_E$

$$\Delta U = \frac{(GM_E)m}{R_E} h = mgh$$

for  $h \ll R_E$

Escape speed:

Total energy of object under gravity is 0

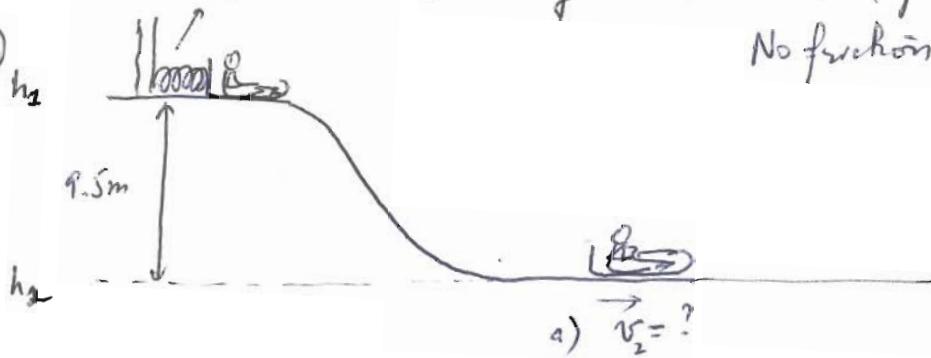
$$\hookrightarrow \underbrace{KE + PE}_{=0}$$

$$\frac{1}{2}mv^2 - \frac{GM_E m}{r} = 0 \rightarrow v_{esc} = \sqrt{\frac{2GM_E}{r}}$$

$$r = R_E \rightarrow v_{esc} = \sqrt{\frac{2 \times 6.67 \times 10^{-11} \times 5.97 \times 10^{24}}{6.37 \times 10^6}} = 11.2 \frac{\text{km}}{\text{s}}$$

$$= 40320 \frac{\text{km}}{\text{h}}$$

(8.21)



$$k = 890 \text{ N/m}$$

$$m = 80 \text{ kg}$$

$$\Delta x = 2.6 \text{ m} \quad (\text{spring compression})$$

No friction.

$$a) \vec{v}_2 = ?$$

$$b) KE_f \text{ in spring.}$$

$$\frac{1}{2}mv_1^2 + mgh_1 + \frac{1}{2}k\Delta x^2 = \frac{1}{2}mv_2^2 + mgh_2$$

Elastic potential energy ↑

$$mg(h_1 - h_2) + \frac{1}{2}k\Delta x^2 = \frac{1}{2}mv_2^2$$

$$v_2 = \sqrt{2g(h_1 - h_2) + \frac{k}{m}\Delta x^2}$$

$$= \sqrt{2 \times 9.81 \times 9.5 + \frac{890}{80} 2.6^2}$$

$$= 16.1 \text{ m/s}$$

$$b) \frac{\frac{1}{2}mv_2^2}{\frac{1}{2}k\Delta x^2} = \frac{80 \times 16.1^2}{890 \times 2.6^2} = 3.44$$

Final speed from both elastic pot. energy AND gravitational potential energy:

$$\frac{\frac{1}{2}k\Delta x^2}{\frac{1}{2}mv^2} = \frac{1}{3.44} = 0.29 \text{ or } 29\%$$

(9.59)

$$v_{esc} = \sqrt{\frac{2GM_E}{R_E}}$$

$$v_{esc}' = \sqrt{\frac{2GM_E}{R_E'}}$$

$$\frac{v_{esc}}{v_{esc}'} = \sqrt{\frac{R_E'}{R_E}} \rightarrow \frac{11.2^2}{30^2} = \frac{R_E'}{R_E}$$

$$\rightarrow R_E' = \left(\frac{11.2}{30}\right)^2 R_E = 887 \text{ km}$$

(24)

Ch. 10

System of Particles

Center of Mass : average position of components weighted by their masses,  $\vec{R}$

$$\vec{R} = \frac{\sum m_i \vec{r}_i}{M}; \quad M = \sum_i m_i \text{ (total mass)}$$

So far, 2<sup>nd</sup> Newton's Law : 
$$\boxed{\vec{F}_{\text{net}} = M \frac{d^2 \vec{R}}{dt^2}}$$

Can we justify this, from the point of view of individual particles?

Particle  $i$  :  $\vec{F}_i = m_i \frac{d^2 \vec{r}_i}{dt^2}$ , sum over particles :

$$\underbrace{\sum_i \vec{F}_i}_{\vec{F}_{\text{total}}} = \sum_i m_i \frac{d^2 \vec{r}_i}{dt^2} = M \frac{d^2}{dt^2} \underbrace{\left( \sum_i m_i \vec{r}_i \right)}_{\vec{R}} \frac{1}{M}$$

$$\Rightarrow \vec{F}_{\text{total}} = M \frac{d^2 \vec{R}}{dt^2}$$

$$\sum_i$$

so far

$$\vec{F}_{\text{total}} = M \frac{d^2 \vec{R}}{dt^2} = \vec{F}_{\text{net, ext}}$$

$$\vec{F}_{\text{net}} = M \frac{d^2 \vec{R}}{dt^2}$$

$$\boxed{\vec{F}_{\text{total}}} = \sum_i (\vec{F}_i)_{\text{net}} = \boxed{\sum_i (\vec{F}_i)_{\text{int}}} + \sum_i (\vec{F}_i)_{\text{ext}}$$

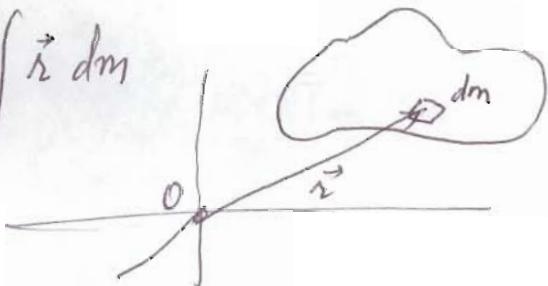
(a) internal forces      (b) external forces

$$= \boxed{\vec{F}_{\text{net, ext}}}$$

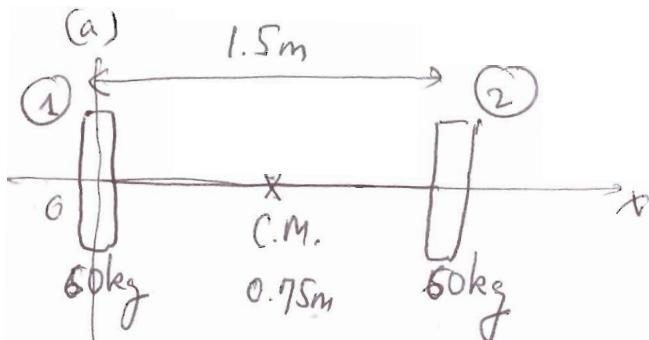
3rd Newton's Law  
→ 0

C.M.

$$\left\{ \begin{array}{l} \vec{R} = \frac{\sum_i m_i \vec{r}_i}{M} \\ \vec{R} = \frac{1}{M} \int \vec{r} dm \end{array} \right.$$

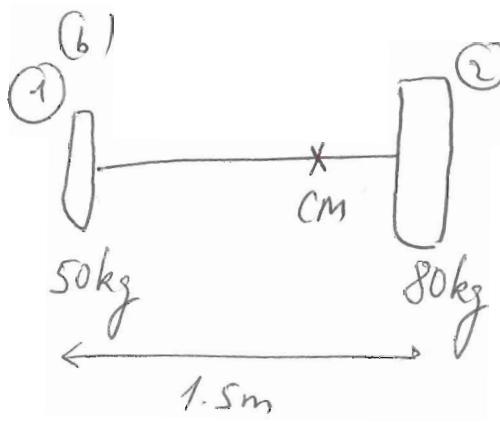


Example:



$$\text{CM} : \vec{R} = \frac{\vec{r}_1 + \vec{r}_2}{2} = \frac{0 + 1.5}{2} = 0.75 \text{ m}$$

$$\vec{R} = \frac{\sum m_i \vec{r}_i}{M} = \frac{m_1 \cdot 0 + m_2 \cdot 1.5}{2m} = 0.75 \text{ m}$$



$$\text{CM} : \vec{R} = \frac{m_1 \cdot 0 + m_2 \cdot 1.5}{m_1 + m_2}$$

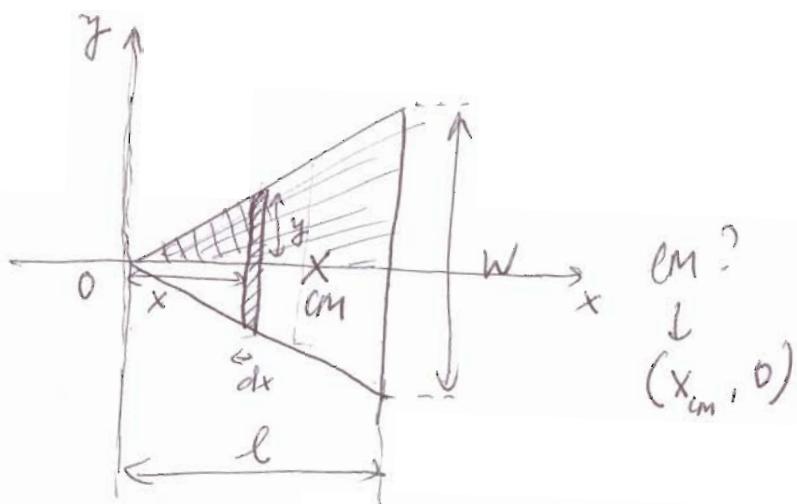
$$= \frac{80 \times 1.5}{130} \text{ m}$$

$$= 0.92 \text{ m}$$

Example:

$$\frac{y}{x} = \frac{\frac{w}{2}}{l}$$

$$\rightarrow y = \frac{xw}{2l}$$



$$\vec{R} = \frac{1}{M} \int \vec{r} dm \quad 1) \text{ Symmetry axis } \rightarrow x\text{-axis}$$

$$\rightarrow x_{cm} = \frac{1}{M} \int x dm \quad (*)$$

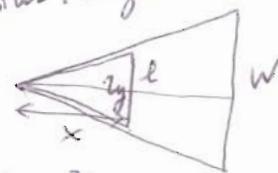
CM?  
 $\downarrow$   
 $(x_{cm}, 0)$

(CM along  
this symmetry axis)

$$2) dm =$$

Since need  $\int$  over the whole triangle, along x-direction  
 $\rightarrow$  need to use vertical strips.

similar triangles



$$\frac{w}{l} = \frac{y}{x}$$

$$dm = A_{strip} \times \rho \quad \left\{ \begin{array}{l} \rho = \frac{M}{\frac{l w}{2}} \\ A_{strip} = y dx = \frac{xw}{l} dx \end{array} \right. \quad (\text{mass density} = \frac{M}{A_{total}})$$

$$\Rightarrow dm = \frac{xw}{l} dx \cdot \frac{2M}{l \frac{w^2}{2}} = \frac{2M}{l^2} x dx$$

$$(*) \quad x_{cm} = \frac{1}{M} \int_0^l \frac{2M}{l^2} x^2 dx = \frac{2}{l^2} \left[ \frac{x^3}{3} \right]_0^l = \frac{2}{3} l$$

## Momentum :

$$\vec{F}_{\text{net}} = M \frac{d^2 \vec{R}}{dt^2} = M \frac{d \vec{V}}{dt} = \underbrace{\frac{d}{dt} (M \vec{V})}$$

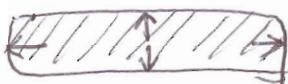
$$\boxed{\vec{V} = \frac{d \vec{R}}{dt} = \frac{d}{dt} \left( \frac{\sum m_i \vec{r}_i}{M} \right) = \frac{\sum m_i \vec{v}_i}{M} \rightarrow \vec{P}}$$

Mom. of a system of particles is  $\vec{P} = M \vec{V} = \sum_i m_i \vec{v}_i$

## Conservation of momentum:

$$\vec{F}_{\text{net}} = 0 \quad = \frac{d \vec{P}}{dt} \Rightarrow \boxed{\vec{P} = \text{constant} = \sum_i m_i \vec{v}_i}$$

## Rockets:

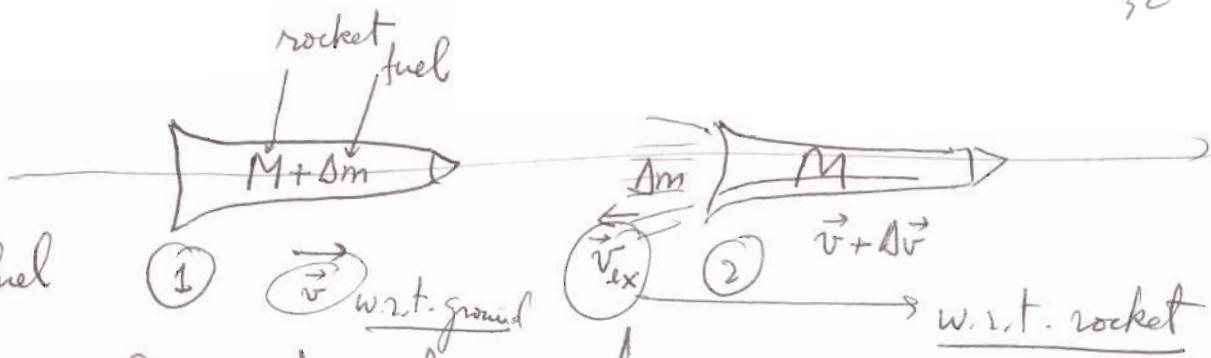


Focus on cylinder:



System of 2 components:

rocket & fuel



$\vec{F}_{\text{net}} = 0 \rightarrow \text{Conservation of momentum:}$

$$\vec{P}_1 = \vec{P}_2$$

$$M\vec{v} + \Delta m \vec{v} = M(\vec{v} + \Delta \vec{v}) + \Delta m (\vec{v}_{\text{ex}})_{\text{w.r.t. ground}}$$

$$\begin{aligned} \text{1D} \quad (M + \Delta m)v &= M(v + \Delta v) - \cancel{\Delta m v_{\text{ex}}} + \cancel{\Delta m v} \\ &= M \Delta v - \Delta m v_{\text{ex}} + \cancel{\Delta m v} \end{aligned}$$

$$(v_{\text{ex}})_{\text{w.r.t. ground}} = (v_{\text{ex}})_{\text{w.r.t. rocket}} + v = -v_{\text{ex}} + v$$

$$\rightarrow \boxed{M \Delta v = \Delta m v_{\text{ex}}}$$

Consequence of  
Conservation of momentum  
of Fuel + Rocket system

$$\Delta m = -\Delta M \rightarrow \left[ M \frac{\Delta v}{\Delta t} = -\frac{\Delta M}{\Delta t} v_{\text{ex}} \right] \lim_{\Delta t \rightarrow 0}$$

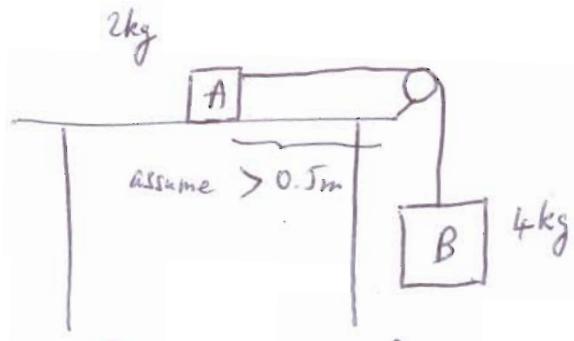
$$\downarrow \boxed{M \frac{dv}{dt} = -\frac{dM}{dt} v_{\text{ex}}}$$

$$M \frac{dv}{dt} = -dM v_{\text{ex}}$$

$$\int \left[ dv = -\frac{dM}{M} v_{\text{ex}} \right]$$

$$\rightarrow \boxed{v_f - v_i = -v_{\text{ex}} \left[ \ln M \right]_{M_i}^{M_f} = +v_{\text{ex}} \ln \frac{M_i}{M_f}}$$

8.35



No friction  $\rightarrow$  Conserv. of Mech. Energy

Speed of these masses after they moved 0.5m

$$\underbrace{KE_1 + U_1}_{\text{rest}} = \underbrace{KE_2 + U_2}_{\text{moved } 0.5\text{m}}$$

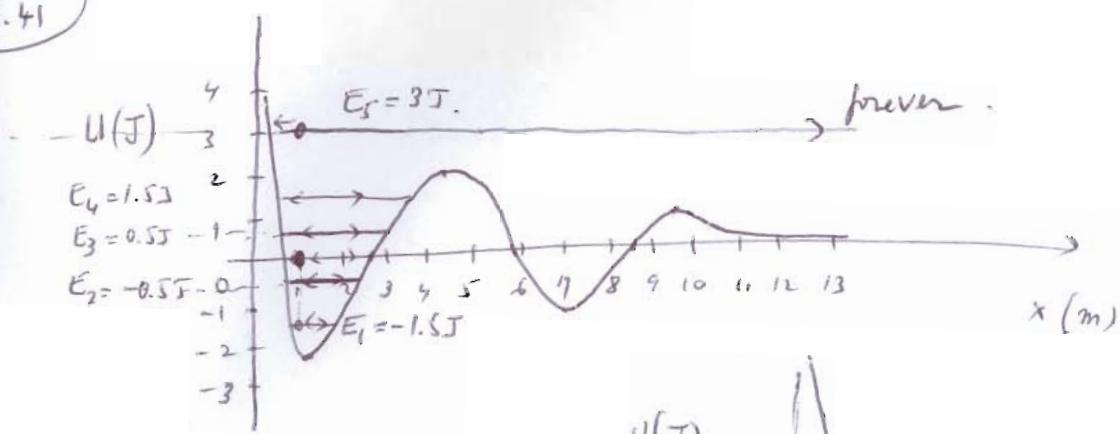
isolate this for final speed.

$$\underbrace{U_1 - U_2}_{\text{0}} + \underbrace{V_0}_{mg \cdot 0.5} = \underbrace{KE_2}_{\frac{1}{2}(m_A + m_B)v_f^2}$$

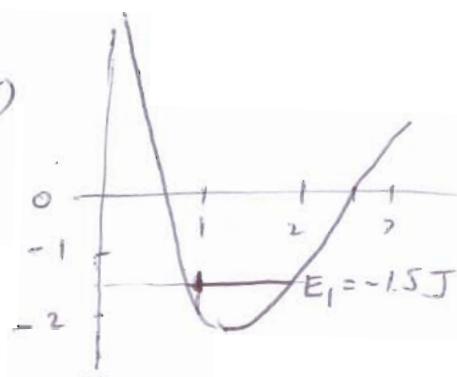
$$\frac{(U_1 - U_2)_A}{0} + \frac{(U_1 - U_2)_B}{mg \cdot 0.5} \rightarrow v_f = \sqrt{\frac{2m_B g \cdot 0.5}{(m_A + m_B)}}$$

$$v_f = \sqrt{\frac{2 \times 4 \times 9.81 \times 0.5}{2+4}} \frac{m}{s} = 2.56 \text{ m/s.}$$

8.41

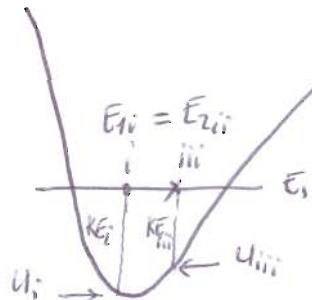
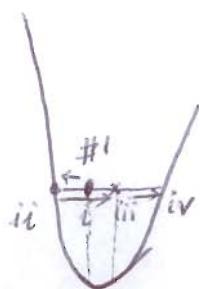


Potential energy curve



at  $x=1\text{m}$   
 $E_1 > U_1$   
 $E_1 = KE_1 + U_1$  (30)

When particle #1 started at  $x=1m$  :  $E_i > U_1$  (above the pot. energy curve)  
 $\rightarrow KE_i = E_i - U_1 > 0 \rightarrow$  there is some  $KE_i$  left to move left.  
 When particle #1 hits pot. energy wall :  $E_i = U_1 \Rightarrow KE_i = 0$   
 $\rightarrow$  it will stop (and turns back)



$$v_i > v_{ii} = 0; \quad v_i > v_{in}; \quad v_i > v_{iin} = 0$$

$$KE_i = E_i - U_i > KE_{iin} = E_i - U_{iin}$$